Computational Methods in Population Genetics

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Contents

1 Introduction 2
   1.1 Example .......................................................... 2
   1.2 How to study ................................................... 3
   1.3 Wright-Fisher model and Kingman’s Coalescent .......... 4
   1.4 Estimators for $\theta$ and Tajima’s D ................. 10
   1.5 Outline of methods ....................................... 12
      1.5.1 ML with Importance Sampling ............... 12
      1.5.2 MCMC for frequentists and Bayesians ..... 13
      1.5.3 Approximate Bayesian Computation (ABC) .... 13

2 Importance sampling for genealogies 14
   2.1 Griffiths and Tavaré ....................................... 17

3 MCMC with Lamarc (or Migrate) 19

4 IM, IMa, IMa2 29

5 Approximate Bayesian Computation (ABC) 32
   5.1 ABC with local regression correction ............... 34
   5.2 MCMC without likelihoods .................................. 37
   5.3 Sequential / Adaptive ABC ............................. 38
   5.4 Optimizing sets of summary statistics with PLS .... 39

6 Jaatha and dadi 42
   6.1 Wild Tomatoes and Jaatha 1.0 ......................... 42
   6.2 Jaatha 2.0 ................................................ 50
   6.3 Application to genome-wide data ....................... 53
   6.4 Statistics in jaatha beyond jsf ....................... 54
   6.5 Conclusions ............................................... 54

7 ARG read from left to right and its approximations 55
   7.1 Why ARG read from left to right is not Markovian .... 55
   7.2 SMC, SMC: Markovian approximations of the ARG .... 55
   7.3 MaCS, SCRM: closer approximations of the ARG .... 56

8 Hidden-Markov model approaches for coalescents with recombination 58
   8.1 The Pairwise Sequential Markov Chain (PSMC) Approach .... 58
   8.2 Excursus: hidden Markov models (HMMs) ............ 60
   8.3 Back to PSMC ............................................. 63
   8.4 MSMC and MSMC2 ...................................... 63
1 Introduction

1.1 Example

Complex Demography
substructure
population growth
recent speciation
introgression?
recombination within loci
can we still detect selection?

1.2 How to study

References


ECTS and work load per week

For Computational Methods in Evolutionary Biology, 8 ECTS ≈ 0.53 per week, 16 hours per week:

• 4 hours lecture (each 45 min + break)
• 3 hours exercise sessions
• 4 hours homework (exercises)
• 5 study lecture contents

For Comp. Meth. Pop. Gen. I/II blocks, 3 ECTS per block = 0.75 per week, 22.5 hours per week,

• all as above plus
• 4 hours of practicals and additional exercise session
• 2.5 hours learn software, apply to data, prepare presentation
How to study the content of the lecture
For the case that you are overwhelmed by the contents of this course, and if you don’t have a good strategy to study, here is my recommendation:

1. Try to explain the items under “Some of the things you should be able to explain”
2. Discuss these explanations with your fellow students
3. Do this before the next lecture, such that you can ask questions if things don’t become clear
4. Do the exercises (at least some of them) in time
5. Study all the rest from the handout, your notes during the lecture, and in books

What will the exam be like
You can bring:

• pocket calculator
• formula sheet, hand-written by yourself

What you need to answer the questions:
• understanding concepts
• be able to apply concepts
• do calculations
• think during the exam
• (not just reproduce facts)

1.3 Wright-Fisher model and Kingman’s Coalescent

Basic assumptions of the Wright Fisher model

• non-overlapping generations
• constant population size
• panmictic
• neutral (i.e. no selection)
• no recombination
• \( N \) diploid individuals \( \rightarrow \) population of \( 2N \) haploid alleles (in case of autosomal DNA)
Wright Fisher model

Each allele chooses an ancestor in the generation before.

Samples are assumed to be taken purely randomly from the population.

This induces a specific random distribution for the genealogies of the sampled alleles.

Haploid population of size $N_e$
Average time until two ancestral lineages coalesce: \( N_e \) generations.

Scale time: (1 time unit) = \((N_e \text{ generations})\) \(\Rightarrow\) pairwise coalescence rate = 1

\[ \mu := \text{mutation rate per generation} \]

\[ \theta := 2N_e \cdot \mu \]

is the expected number of mutations between 2 random individuals

Let \( N_e \to \infty \)

**Time until two lineages coalesce**

\( W \): time in generations until two lineages coalesce, \( X = W/N_e \).

\[
\Pr(W > k) = \left( 1 - \frac{1}{N_e} \right)^k \approx e^{-k/N_e}
\]

\[
\Pr(X > t) = \Pr(W > t \cdot N_e) \approx e^{-t}
\]

For \( N_e \to \infty \) the “\( \approx \)” becomes “\( = \)”.

Thus \( W \) is geometrically distributed with success probability \( \frac{1}{N_e} \).

\( X \) is (for \( N_e \to \infty \)) exponentially distributed with rate 1.

**Geometric distribution**

\[
\Pr(W > k) = (1 - p)^k \\
\Pr(W = k) = (1 - p)^{k-1} \cdot p \\
\mathbb{E}W = 1/p
\]

**Exponential distribution**

\[
\Pr(X > t) = e^{-\lambda t} \\
f(t) = \lambda \cdot e^{-\lambda t} \\
\mathbb{E}X = 1/\lambda
\]

If there are \( k \) lineages traced back, each of the

\[
\binom{k}{2} = \frac{k \cdot (k - 1)}{2}
\]
pairs of lineages coalesces with rate 1 (per \( N_e \) generations).

Going to the limit \( N_e \to \infty \) we can neglect that more than two lineages coalesce in the same generation.

Thus, the total rate of coalescence is \( \frac{k}{2} \) and the expectation value for the time back until the first coalescence is

\[
\frac{1}{\binom{k}{2}} = \frac{2}{k \cdot (k - 1)}
\]
time units (of \( N_e \) generations).
Minimum of independent exponentials

If \( X_1, X_2, \ldots, X_n \) are exponential random variables with rates \( \lambda_1, \lambda_2, \ldots, \lambda_n \), then the minimum of the \( X_i \) is exponentially distributed with rate \( \Lambda = \lambda_1 + \lambda_2 + \cdots + \lambda_n \). (E.g. each \( \lambda_i \) is the rate of certain events, and \( X_i \) is the waiting time for the first of these events.)

This implies that for \( k \) lineages (and \( N_e \to \infty \)) the waiting time (in units of \( N_e \) generations) is geometrically distributed with rate \( \binom{k}{2} \).

(Doob-)Gillespie algorithm

To simulate the process, first simulate the waiting time for the first event according to an exponential distribution with rate \( \Lambda \).

Then make a random decision which type of event occurred, using the probabilities

\[
\frac{\lambda_1}{\Lambda}, \frac{\lambda_2}{\Lambda}, \ldots, \frac{\lambda_n}{\Lambda}.
\]

Proceed with the next and all other events accordingly.

This is often called Gillespie’s algorithm. Dan Gillespie applied it in the 1970ies to simulate chemical reactions. The algorithm was, however, known long before, e.g. by Doob in the 1940ies.

The Kingman Coalescent

Simulating Kingman’s coalescent for \( k \) lineages

Apply Doob-Gillespie algorithm.

\( \binom{k}{2} \) pairs of lineages, each pair coalescing with rate 1.
• Draw the time $\tau$ until the first two lineages coalesce from exponential distribution with rate $\binom{k}{2}$.

• Choose one of the $\binom{k}{2}$ pairs of lineages (each with the same probability of $1/\binom{k}{2}$) and coalesce them to one lineage.

• Draw next time interval from exponential with rate $\binom{k-1}{2}$ and let two of the $k-1$ coalesce, and so on, until the last two lineages coalesce.

Typical coalescent trees for $n = 8$:

Simulated coalescent tree with $n = 500$:

Time to the most recent ancestor (TMRCA)
\[
E(\text{TMRCA}) = \frac{1}{(k)} + \frac{1}{(k-1)} + \cdots + \frac{1}{(2)} + \frac{1}{(2)} \\
= \frac{2}{k \cdot (k-1)} + \frac{2}{(k-1) \cdot (k-2)} + \cdots + \frac{2}{3 \cdot 2} + \frac{2}{2} \\
= 2 \cdot \left( \frac{1}{k \cdot (k-1)} + \frac{1}{(k-1) \cdot (k-2)} + \cdots + \frac{1}{3 \cdot 2} + \frac{1}{2} \right) \\
= 2 \cdot \left( \frac{(k-1)}{k \cdot (k-1)} + \frac{(k-1)}{(k-1) \cdot (k-2)} + \cdots + \frac{3}{3 \cdot 2} + \frac{2-1}{2} \right) \\
= 2 \cdot \left( -\frac{1}{k} + \frac{1}{k-1} - \frac{1}{k-1} + \frac{1}{k-2} + \cdots + \frac{1}{3} + \frac{1}{2} - \frac{1}{2} + \frac{1}{1} \right) \\
= 2 \cdot \left( 1 - \frac{1}{k} \right)
\]

**In the diploid case**

If \( N_e \) is the effective population size of individuals, and the locus under consideration is diploid, time is scaled in units of \( 2N_e \) generations or, in some programs, in \( 4N_e \) generations. We then define

\[
\theta = 4 \cdot N_e \cdot \mu.
\]

The expected waiting time until the ancestral lineages of two gene copies coalesce is then \( 2N_e \) generations. The expectation values

\[
E(\text{total length}) = 2 \cdot \sum_{i=1}^{k-1} \frac{1}{i} \quad \text{and} \quad E(\text{TMRCA}) = 2 \cdot \left( 1 - \frac{1}{k} \right)
\]

hold in the diploid case in units of \( 2N_e \) generations.

**Simulate coalescent with mutations**

\( k \) lineages ⇒

- each of \( \left( \begin{array}{c} k \\ 2 \end{array} \right) \) pairs of lineages coalesce with rate 1
- each of \( k \) lineages mutate with rate \( \theta/2 \)

⇒ time \( \tau_i \) to next event is exponentially distrib. with rate \( \frac{k \cdot (k-1)}{2} + k \cdot \frac{\theta}{2} \)

Then, the probabilities are proportional to the rates, that is:

Next event is mutation with probability

\[
\frac{k \cdot \frac{\theta}{2}}{\frac{k \cdot (k-1)}{2} + k \cdot \frac{\theta}{2}} = \frac{\theta}{k-1 + \theta}
\]

and coalescence with probability

\[
\frac{k-1}{k-1 + \theta}
\]

**Some things that you should be able to explain**

- Wright-Fisher model for population genetics
- Coalescent model; rate of coalescence of \( k \) lineages
• Geometrically distributed coalescent times, approximated by exponential
• Rates of independent processes add up
• the typical genealogy of a sample from W-F population
  – very long internal branches
  – very short tip branches for large sample size
  – how to calculate expectation values for
    * total of all branch lengths
    * TMRCA: time to the most recent ancestor
  – how can we let population size go to $\infty$
• Why time is scaled in const. $N_e$ generations
• $\theta = 4N_e\mu$ or $\theta = 2N_e\mu$ or...

1.4 Estimators for $\theta$ and Tajima’s D

Two estimators of $\theta$

$\theta_\pi$ (“Tajima’s $\pi$” or “nucleotide diversity”) Average number of pairwise differences.

$\theta_W$ (“Watterson’s $\theta$”) = \frac{\text{number of mutations}}{\sum_{i=1}^{n} 1/i}$

Both are unbiased estimators of $\theta$, i.e. $E\theta_W = E\theta_\pi = \theta$.

Note the difference

parameter: 
• hypothetical value in theoretical model;
  • example: $\theta = 4N_e\mu$
  • non-random (in classical frequentistic stats)
  • assumed usually in stats: there is a true value that is unknown

statistic: 
• a function of the data (that is, is calculated from the data)
  • examples: $\theta_W$ and $\theta_\pi$,
  • are random variables because data is also random due to
    – randomly sampling from natural variation
    – random process
    – measurement error

estimator: 
• statistic to estimate the value of a parameter
  • example: $\theta_W$ and $\theta_\pi$ are estimators for $\theta$

Example: Ward et al. (1991) sampled 360 bp sequences from mtDNA control region of $n = 63$ Nuu Chah Nulth and observed 26 mutations.

$\theta_W = \frac{26}{\sum_{i=1}^{n} 1/i} = 5.5123$

This corresponds to 0.0153 Mutations per base and per $2 \cdot N_e$ generations. Assuming a mutation rate $\hat{\mu} \approx 6.6 \cdot 10^{-6}$ per generation per site this leads to an effective population size of

$\hat{N_e} = \frac{\theta_W/360}{2 \cdot \hat{\mu}} \approx 1150$ females

How precise is this estimation?

$\text{var}(\theta_W) = \frac{\theta}{\sum_{i=1}^{n} 1/i} + \theta^2 \cdot \frac{\sum_{i=1}^{n} 1/i^2}{(\sum_{i=1}^{n} 1/i)^2}$
**Theorem 1** Any unbiased estimator of $\theta$ has variance at least

$$\frac{\theta}{\sum_{k=1}^{n-1} \frac{1}{k+\theta}}.$$

(Here, we assume that the estimation is based on a single locus without recombination).

For the Nuu Chah Nulth data we get:

$$\theta_W = 5.5123$$

$$\sigma_{\theta_W} = 3.42$$

Confidence range? (2$\sigma$-rule would lead to negative values...)

Conclusion: $N_e$ could perhaps also be 200 or 3000 females.

How can we improve this estimate? Sample more individuals? How many individuals $n$ would we need to get $\sigma_{\theta_W} = 0.1 \cdot \theta$? From the formula for $\text{var} \theta_W$ follows that we need $n \approx 2 \cdot e^{100/\theta}$. For $\theta = 5$, this is $n \approx 10^9$. For $\theta = 1$, this is $n \approx 10^{43}$. number of water molecules on earth$\approx 10^{47}$ number of seconds since big bang$\approx 4.3 \cdot 10^{17}$

Solution: sample many loci!

**References**


How to sample if

- one read is 600 bp long
- costs for developing a new locus is 40$
- costs for collecting a sample is 10 or 0.10$
- costs for a single read is 6$
- you can spend 1000$
- true $\theta$ is 1.8 (per locus)

Optimal sampling scheme: $n = 7$ or $n = 8$, respectively, individuals and 11 loci.

With this sampling scheme we get:

$$\sigma_{\theta_W} \approx 0.2 \cdot \theta \text{ and } \sigma_{\theta_z} \approx 0.22 \cdot \theta$$

(all this is based on infinite-sites assumptions)
Some of the things you should be able to explain

- $\theta$, $\theta_W$, $\theta_x$, Tajima’s $D$
- difference between parameters and statistics and which of the different $\theta$s is which
- How do population growth, substructure and selection shape the genealogy of a random sample and how is this reflected in Tajima’s $D$?
- Why does a single locus (or several completely linked loci) not allow for reasonable estimates?
- why are more loci usually better than more or longer sequences?
- Why do we need to know $\mu$ to estimate $N_e$ from data and vice versa?

1.5 Outline of methods
1.5.1 ML with Importance Sampling

The Likelihood

$\psi = (\psi_i)_i$ vector of model parameters

$D$ sequence data

$$L_D(\psi) = Pr_\psi(D) = \int_{\text{all Genealogies } G} Pr_\psi(D \mid G) \cdot P_\psi(dG).$$

Importance Sampling

Draw $G_1, \ldots, G_k$ (approx.) i.i.d. with density $Q$ and approximate

$$\int Pr_\psi(D \mid G)P_\psi(dG) \approx \frac{1}{k} \sum_{i=1}^{k} \frac{Pr_\psi(D \mid G_i) \cdot P_\psi(G_i)}{Q(G_i)}.$$

efficient for $\psi$ with

$$Q(G_i) \approx \text{const} \cdot P_\psi(D \mid G_i) \cdot P_\psi(G_i)$$

Methods differ in their choice of $Q$. 

12
Griffiths & Tavaré (1994)

Q: Generate $G$ backwards in time, greedy proportional to coalescence and mutation probabilities. Choose between all allowed events.

Good for infinite sites models, inefficient if back-mutations are allowed.

1.5.2 MCMC for frequentists and Bayesians

Felsenstein, Kuhner, Yamato, Beerli, ... 

For some initial $\psi_0$, sample Genealogies $G$ approx. i.i.d. according to $Pr_{\psi_0}(G \mid D)$ by Metropolis-Hastings MCMC.

Coalescent is a natural prior for $G$!

Two flavours:

for frequentists: use $G_1, \ldots, G_k$ for Importance Sampling

Optimize approx. Likelihood $\rightarrow \psi_1$

Iterate with $\psi_0$ replaced by $\psi_1$

for Bayesians: Then sample $\psi$ conditioned on Genealogies and iterate to do Gibbs-sampling from $Pr(\psi, G \mid D)$.

Problems of full-data methods

- usual runtime for one dataset: several weeks or months
- complex software, development takes years
- most programs not flexible, hard to write extensions

1.5.3 Approximate Bayesian Computation (ABC)

Pritchard et al. (1999)

Approximate Bayesian Computation

1. Select summary statistics $S = (S_i)_i$ and compute their values $s = (s_i)_i$ for given data set

2. Choose tolerance $\delta$

3. repeat until $k$ accepted $\psi'$:

- Simulate $\psi'$ from prior distribution of $\psi$
- Simulate genealogy $G$ according to $Pr_{\psi'}(G)$.
- Simulate data and compute values $s'$ of $S$
- accept $\psi'$ if $\|s - s'\| \leq \delta$

Only possible if a few summary statistics suffice. We will later discuss refinements and extensions of this approach.


“[…] the MCMC-based method is consistently superior to the summary-statistics-based methods and highlights that it is well worth making the effort to obtain full-data inferences if possible.”

“[…] there are advantages to the use of summary statistics, both in the ease of implementation and in the time to obtain the results […]”

“Further research is needed to find a more rigorous way for choosing summary statistics, including the use of orthogonalization and ‘projection-pursuit’ methods”
Some of the things you should be able to explain
Basic ideas of the following approaches in computational population genetics

- maximum likelihood with importance sampling
- full-data Bayesian with MCMC
- Approximate Bayesian Computation (ABC)

2 Importance sampling for genealogies

$D$: data set of DNA sequences sampled from a population. In case of a structured population sampling locations are known.

Aim: Estimate parameters $\Theta := (\theta_i, M_{ij})_{ij}$.

Maximum-Likelihood (ML) approach: Find the set of parameter values that maximizes the likelihood:

$$\hat{\Theta} := \arg \max \Pr_{\Theta}(D)$$

How to compute the likelihood?

$$L_D(\Theta) = \Pr_{\Theta}(D) = \sum_G \Pr_{\Theta}(G) \cdot \Pr_{\Theta}(D | G).$$

More precisely:

$$L_D(\Theta) = \Pr_{\Theta}(D) = \int_{\text{all genealogies } G} \Pr_{\Theta}(D | G) \cdot \Pr_{\Theta}(G) dG$$

where $\Pr_{\Theta}(G)$ is the density of the (structured) coalescent distribution at the genealogy $G$.

What does this mean?

How to compute $\Pr_{\Theta}(G)$?

And what is $dG$?

How to compute $\Pr_{\Theta}(G)$

Example: Kingman coalescent with mutations as part of $G$ (different than in LAMARC). Let $r_k = \binom{k}{2} + k \theta^2$ be the total rate if $k$ lineages are present.

$$P_{\Theta}(G) = r_5 \cdot e^{-r_5 \tau_1} \cdot 1/r_5 \cdot r_4 \cdot e^{-r_4 \tau_2} \cdot 1/r_4 \cdot r_3 \cdot e^{-r_3 \tau_3} \cdot \theta/2/r_3 \cdot r_3 \cdot e^{-r_3 \tau_4} \cdot 1/r_3 \cdot r_2 \cdot e^{-r_2 \tau_5} \cdot \theta/2/r_2 \cdot r_2 \cdot e^{-r_2 \tau_6} \cdot 1/r_2 \cdot$$

$$= e^{-r_5 \tau_1-r_4 \tau_2-r_3 \tau_3-r_3 \tau_4-r_2 \tau_5-r_2 \tau_6} \cdot (\frac{\theta}{2})^2$$

So what is $dG$?

Let’s first ask: What is the $dx$ in

$$\int_0^1 x^2 dx \quad ?$$

$dx$ is used in an ambiguous way. This is sloppy but intuitive.

It means “a small environment around $x$”, but also the size of this environment.

To explain this we be a little bit less sloppy for a few minutes and write $dx$ for the environment and $dx$ for its size.

For some small $n \in \mathbb{N}$ and $x \in \mathbb{R}$ we can define $dx = [x - \frac{1}{2n}, x + \frac{1}{2n}]$. Then, $dx = 1/n$. 

We can approximate \( \int_{0}^{1} x^2 dx \) by

\[
\sum_{x \in \left\{ \frac{1}{n}, \frac{2}{n}, \ldots, \frac{n}{n} \right\}} x^2 \cdot \frac{1}{n} = \sum_{x \in \left\{ \frac{1}{n}, \frac{2}{n}, \ldots, \frac{n}{n} \right\}} x^2 \cdot dx \xrightarrow{n \to \infty} \int_{0}^{1} x^2 dx
\]

\( dx \) is always meant to be “infinitesimally small”, i.e. \( dx \to 0 \)

**What is a probability density?**

\( P(x) \) is the probability density of a random variable \( X \) in \( x \) if

\[
\Pr(X \in dx) \approx P(x) \cdot dx
\]

and the “\( \approx \)” becomes a “\( = \)” for “infinitesimally small” \( dx \).

This is again sloppy and intuitive. It actually means that

\[
\lim_{dx \to 0} \frac{\Pr(X \in dx)}{dx} = P(x)
\]

It then follows that

\[
\Pr(X \in [a,b]) = \int_{a}^{b} P(x)dx.
\]

**Examples**

The density of the exponential distribution with rate \( \lambda \) at \( x \) is

\[
\lambda e^{-\lambda x}.
\]

The density of the normal distribution with mean value \( \mu \) and standard deviation \( \sigma \) is

\[
\frac{1}{\sigma \sqrt{2\pi}} \cdot e^{-\frac{(x-\mu)^2}{2\sigma^2}}.
\]

**Now for \( dG \)**

Let \( dG \) be a small environment around the genealogy \( G \). This means, \( dG \) consists of all genealogies \( G' \) that have the same topology as \( G \) and if \( \tau_1, \ldots, \tau_n \) are the points in time where coalescent events or migrations of lineages or the like occur in \( G \), and \( \tau_1', \ldots, \tau_n' \) are the corresponding points in time for \( G' \), then

\[
\forall k \leq n |\tau_k - \tau_k'| \leq \varepsilon.
\]

Thus, the volume \( dG \) of \( dG \) can be defined to be \( (2\varepsilon)^n \).
The density $P_{\Theta}(G)$ is then defined by

$$\Pr_{\Theta}(G' \in dG) \approx P_{\Theta}(G) \cdot dG$$

where $\Pr_{\Theta}(G' \in dG)$ is the probability that a genealogy $G'$ that was generated according to the probability distribution of a structured coalescent with parameter values $\Theta$ results to be in the environment $dG$ of $G$, or, more precisely:

$$\frac{\Pr_{\Theta}(G' \in dG)}{dG} \stackrel{dG \to 0}{\longrightarrow} P_{\Theta}(G)$$

The equation

$$L_D(\Theta) = \Pr_{\Theta}(D) = \int_{\text{all genealogies}} \Pr_{\Theta}(D \mid G) P_{\Theta}(G) dG$$

should now make some more sense to us. But how can we compute it? We use Importance Sampling. How can we compute the integral $\int_a^b h(x) dx$ of this function $h$?

Approximation by a step function: If $x_1, \ldots, x_k$ are the means of the partition intervals and $c = \frac{b-a}{k}$ is their width, then

$$\int_a^b h(x) dx \approx \sum_{i=1}^k c \cdot h(x_i) = \frac{b-a}{k} \sum_{i=1}^k h(x_i).$$

Maybe save some time by just taking a sample of $k$ values $h(x)$.

$$\int_a^b h(x) dx \approx \frac{b-a}{k} \sum_{i=1}^k h(X_i) = \frac{1}{k} \sum_{i=1}^k \frac{h(X_i)}{b-a}.$$
We can sample more from the relevant range but we have to correct this by the Importance-Sampling formula:

\[ \int h(x) \, dx \approx \frac{1}{k} \sum_{i=1}^{k} \frac{h(X_i)}{q(X_i)} \]

where \( X_1, \ldots, X_k \) are independent samples from a distribution whose density \( q \) is proportional to \( f \). The closer \( f \) is to \( h \), the better the approximation.

**Sketch of proof of the IS formula**

\[
\int_{a}^{b} h(x)dx = \int_{a}^{b} \frac{h(x)}{q(x)} \cdot q(x)dx = \mathbb{E}_q \frac{h(X)}{q(X)} \approx \frac{1}{k} \sum_{i=1}^{k} \frac{h(X_i)}{q(X_i)},
\]

where \( \mathbb{E}_q \) is the expectation value under the assumption that \( X \) has probability density \( q \), and \( X_1, \ldots, X_k \) are independently sampled with probability density \( q \).

Importance Sampling for computing the likelihood of for a range of parameter values \( \Theta \): Generate genealogies \( G_1, \ldots, G_k \) (more or less) independently according to a probability density \( Q(G_i) \). Then,

\[
L_D(\Theta) = \int_{\text{all genealogies}} \Pr_{\Theta}(D|G) \cdot P_{\Theta}(G) dG \approx \frac{1}{k} \sum_{i=1}^{k} \Pr_{\Theta}(D|G_i) \cdot P_{\Theta}(G_i) .
\]

Method differ in their choice of \( Q \) and will be most efficient if

\[ Q(G) \approx \text{const.} \cdot \Pr_{\Theta}(D|G) \cdot P_{\Theta}(G). \]

2.1 Griffiths und Tavaré

References


We roughly follow the rationale and notations of

References

Start with an initial guess $\Theta_0$. Define the history of a sample to be $H = (H_1, H_2, \ldots, H_\ell)$, where the historical events $H_k$ can be:

1. lineages $i$ and $j$ coalesce
2. mutation on lineage $i$
3. lineage $i$ from island $a$ traces back to island $b$

and $H_1, H_2, \ldots, H_\ell$ goes from present to past.

For the Importance Sampling procedure, many histories $H^{(1)}, H^{(2)}, \ldots, H^{(M)}$ are generated. For each history $H^{(i)}$ are sampled step by step from the tips to the root of the tree. Given the data, not all events are possible. E.g., lineages cannot coalesce if they are of different allelic type. If the infinite-site mutation model is used (to make the Griffith-Tavaré scheme efficient), not all mutations are allowed.

- Let $b_{ij}(\theta_0)$ be the rates of the $j$th event $h = H^{(i)}_j$ in the $i$th sampled history $H^{(i)}$ and
- let $(a_{ijk}(\theta_0))_k$ be the series of rates of all events that are in accordance with the data and the infinite-sites assumption, and
- $(r_{ij}(\theta))$ the total rate of all possible events, disregarding the data.

Then, the probability to choose $h$ was $b_{ij}(\theta_0) / \sum_k a_{ijk}(\theta_0)$. Thus, $\prod_j b_{ij}(\theta_0) / \sum_k a_{ijk}(\theta_0)$ is the importance-sampling probability $Q_{\theta_0}(H^{(i)})$ of the entire history $H^{(i)}$. According to the importance-sampling formula we get for all $\theta$ that are not too far from $\theta_0$:

$$L_{(D)}(\theta) \approx \frac{1}{M} \sum_{i=1}^M \left( \prod_j \frac{b_{ij}(\theta_0)}{r_{ij}(\theta)} \right) \left/ \prod_j \frac{b_{ij}(\theta_0)}{\sum_k a_{ijk}(\theta_0)} \right.$$

$$= \frac{1}{M} \sum_{i=1}^M \prod_j \frac{b_{ij}(\theta) \cdot \sum_k a_{ijk}(\theta_0)}{r_{ij}(\theta) \cdot b_{ij}(\theta_0)}$$

For example, let this be the $i$th sampled history under infinite-sites assumptions:

(only segregating sites shown)

$$\prod_j \frac{b_{ij}(\theta)}{r_{ij}(\theta)} = \frac{1}{6 + 2 \theta} \cdot \frac{\theta/2}{3 + 1.5 \cdot \theta} \cdot \frac{1}{1 + 2 \cdot \frac{\theta}{1 + \theta}}$$
For example, let this be the \( i \)th sampled history under infinite-sites assumptions:

- **step 1**: allowed are coalescence of first two lineages or mutation of 2nd position in sequence 4.
  \[ b_{i,1}(\theta_0) = a_{i,1,1}(\theta_0) = 1, \quad a_{i,1,2}(\theta_0) = \theta_0/2 \]

- **step 2**: allowed is mutation of position 1 in on lineage 1 or position 2 on lineage on lineage 3
  \[ b_{i,2}(\theta_0) = a_{i,2,1}(\theta_0) = a_{i,1,2}(\theta_0) = \theta_0/2 \]

- **step 3**: allowed are coalescence of lineages 1 and 2 or mutation on lineage 3
  \[ b_{i,3}(\theta_0) = a_{i,3,1}(\theta_0) = 1, \quad a_{i,3,2}(\theta_0) = \theta_0/2 \]

- **step 4**: position 2 can mutate in lineage 1 or 2
  \[ b_{i,4}(\theta_0) = a_{i,4,1}(\theta_0) = a_{i,4,2}(\theta_0) = \theta_0/2 \]

\[
\prod_j b_{ij}(\theta_0) \sum_k a_{ijk}(\theta_0) = \frac{1}{1 + \frac{\theta_0}{2}} \cdot \frac{\theta_0/2}{1 + \frac{\theta_0}{2}} \cdot \frac{1}{1 + \frac{\theta_0}{2}} \cdot \frac{\theta_0/2}{1 + \frac{\theta_0}{2}}
\]

- Advantage over MCMC: Histories are sampled really independent of each other.
- Disadvantage: For finite-sites models many different mutation events are allowed in each step, which makes the method very inefficient. Stephens and Donnelly (2000) found a solution for this, which we will discuss later in the semester.

**Some of what you should be able to explain**

- The formula
  \[ L_D(\Theta) = \int P_\Theta(D(G))P_\Theta(G)dG \]
  and all its terms, including \( dG \)
- what is a probability density, in particular \( P_\Theta(G) \)
- how to compute \( P_\Theta(G) \)
- importance sampling: idea and formula
- Griffiths-Tavaré method

### 3 MCMC with Lamarc (or Migrate)

**Rate parameters and time scales**

For autosomal DNA:

<table>
<thead>
<tr>
<th>Rate parameter</th>
<th>per generation</th>
<th>per ( 2N_i ) generations</th>
<th>per ( 1/\mu ) generations</th>
</tr>
</thead>
<tbody>
<tr>
<td>mutation rate</td>
<td>( \mu )</td>
<td>( \frac{2\mu}{\theta} = 2N_i\mu )</td>
<td>( 1 )</td>
</tr>
<tr>
<td>migration rate of ancestral lineage from ( i ) tracing back to ( j )</td>
<td>( m_{ij} )</td>
<td>( \gamma_{ij} = 2N_i m_{ij} )</td>
<td>( M_{ij} = \frac{m_{ij}}{\mu} = \frac{2\gamma_{ij}}{\theta_i} )</td>
</tr>
<tr>
<td>coalescence on island ( i )</td>
<td>( 1/(2N_i) )</td>
<td>1</td>
<td>( \frac{1}{2N_i} = \frac{2}{\theta_i} )</td>
</tr>
</tbody>
</table>

Number of alleles on island \( i \) that choose their parent allele on island \( j \):

\[ 2N_i \cdot m_{ij} = \gamma_{ij} \]
example: two populations, time unit $1/\mu$ generations

- total rate when $k$ lineages in pop 1 and $\ell$ lineages in pop 2:

\[
\begin{align*}
\frac{r(k, \ell)}{2} &= \frac{2}{\theta_1} + \frac{k \cdot M_{1,2}}{\theta_1} + \frac{\ell \cdot (\ell - 1)}{2} + \frac{2}{\theta_2} + \ell \cdot M_{2,1} = \frac{k \cdot (k - 1)}{2} \theta_1 + k \cdot M_{1,2} + \frac{\ell \cdot (\ell - 1)}{\theta_2} + \ell \cdot M_{2,1}.
\end{align*}
\]

\[
p(G) = r(4, 3) \cdot e^{-r(4, 3) \cdot 1/3} \cdot \frac{2}{\theta_1} \cdot r(4, 3) \cdot e^{-r(3, 3) \cdot 0.2} \cdot \frac{2}{\theta_2} \cdot r(2, 3) \cdot e^{-r(2, 2) \cdot 1/2} \cdot \frac{M_{1,2}}{\theta_2} \cdot r(2, 2) \cdot e^{-r(2, 2) \cdot 1/2} \cdot \frac{M_{1,2}}{\theta_2} \cdot r(2, 2) \cdot e^{-r(2, 2) \cdot 0.4} \cdot \frac{2}{\theta_2} \cdot r(1, 3) \cdot e^{-r(1, 3) \cdot 0.7} \cdot \frac{2}{\theta_2} \cdot r(1, 3) \cdot e^{-r(1, 3) \cdot 0.7} \cdot \frac{2}{\theta_2} \cdot r(1, 3) \cdot e^{-r(1, 3) \cdot 0.7} \cdot \frac{2}{\theta_2} \cdot e^{-r(1, 1) \cdot 0.4} \cdot \frac{2}{\theta_2}.
\]

\[
M_{1,2} \cdot e^{-r(1, 1) \cdot 0.4} \cdot \frac{2}{\theta_2} / 2 = e^{-r(4, 3) \cdot 1.3} \cdot e^{-r(3, 3) \cdot 0.2} \cdot \frac{2}{\theta_1} / 2 \cdot e^{-r(2, 2) \cdot 1/2} \cdot \frac{M_{1,2}}{\theta_1} \cdot e^{-r(2, 2) \cdot 1/2} \cdot \frac{M_{1,2}}{\theta_1} \cdot e^{-r(2, 2) \cdot 0.4} \cdot \frac{2}{\theta_1} \cdot r(1, 3) \cdot e^{-r(1, 3) \cdot 0.7} \cdot r(1, 3) \cdot e^{-r(1, 1) \cdot 0.5} \cdot \frac{2}{\theta_1} / 2 \cdot e^{-r(1, 1) \cdot 0.4} \cdot \frac{2}{\theta_1}.
\]

\[
M_{1,2} \cdot e^{-r(1, 1) \cdot 0.5} \cdot \theta_1 / 2 = e^{-r(4, 3) \cdot 1.3} \cdot e^{-r(3, 3) \cdot 0.2} \cdot \frac{2}{\theta_1} / 2 \cdot e^{-r(2, 2) \cdot 1/2} \cdot \frac{M_{1,2}}{\theta_1} \cdot e^{-r(2, 2) \cdot 1/2} \cdot \frac{M_{1,2}}{\theta_1} \cdot e^{-r(2, 2) \cdot 0.4} \cdot \frac{2}{\theta_1} \cdot r(1, 3) \cdot e^{-r(1, 3) \cdot 0.7} \cdot r(1, 3) \cdot e^{-r(1, 1) \cdot 0.5} \cdot \frac{2}{\theta_1} / 2 \cdot e^{-r(1, 1) \cdot 0.4} \cdot \frac{2}{\theta_1}.
\]

Combining IS with MCMC

References


- MIGRATE-N [http://popgen.sc.fsu.edu/Migrate/Migrate-n.html]
- LAMARC [http://evolution.genetics.washington.edu/lamarc/lamarc.html]

LAMARC strategy

Begin with initial parameter guess $\Theta_0 = (\theta_1^{(0)}, \theta_2^{(0)}, \ldots; M_{12}^{(0)}, M_{12}^{(0)}, M_{23}^{(0)}, \ldots)$, repeat the following steps for $i = 0, 1, 2, \ldots, m - 1$

1. Metropolis-Hastings MCMC sampling of genealogies $G_1, G_2, \ldots, G_k$ (approx.) according to the posterior density $p_{\Theta_0}(G/D)$ given the data $D$. What is Metropolis-Hastings MCMC?

2. importance sampling:

\[
\frac{L_D(\Theta)}{L_D(\Theta_i)} \approx \frac{1}{k} \sum_{j=1}^{k} p_{\Theta_i}(G_j) =: F_{\Theta_i}(\Theta).
\]

Why is this justified as importance sampling?

3. $\Theta_{i+1} := \arg \max_{\Theta} F_{\Theta_i}(\Theta)$

and hope that $\Theta_m \approx \hat{\Theta} = \arg \max_{\Theta} L_D(\Theta)$

20
Justification of step 2

\[
\frac{L_D(\Theta)}{L_D(\Theta_i)} \approx \frac{1}{k} \sum_{j=1}^{k} \frac{Pr_\Theta(D|G_j)p_\Theta(G_j)}{p_\Theta_i(D|G_j)\cdot Pr_\Theta_i(D)} \quad \text{(importance sampling)}
\]

\[
= \frac{1}{k} \sum_{j=1}^{k} \frac{Pr_\Theta(D|G_j)p_\Theta(G_j)}{p_\Theta_i(G_j,D)\cdot Pr_\Theta_i(D)}
\]

\[
= \frac{1}{k} \sum_{j=1}^{k} \frac{Pr_\Theta(D|G_j)p_\Theta(G_j)}{Pr_\Theta_i(D)\cdot p_\Theta_i(G_j)} = \frac{1}{k} \sum_{j=1}^{k} \frac{p_\Theta(G_j)}{p_\Theta_i(G_j)}
\]

The last equation follows from \( Pr_\Theta(D|G_j) = Pr_\Theta_i(D|G_j) \), which holds since the mutation rate is always 1 and thus the \( D \) is independent of \( \Theta \) when \( G \) is given.

**Markov-Chain Monte Carlo (MCMC)**

MCMC: construct Markov chain \( X_0, X_1, X_2, \ldots \) with stationary distribution \( Pr(G|D) \) and let it converge.

**Markov property:**

\[
\forall i,x : \ Pr(X_{i+1} = x | X_i) = Pr(X_{i+1} = x | X_i, X_{i-1}, \ldots, X_0)
\]

In words: The probability for the next state may depend on the current state but not additionally on the past.

**“Equilibrium” or “Stationary distribution”** \( p \):

\[
\forall i,x : \ p(x) = \sum_y p(y) \cdot Pr(X_{i+1} = x | X_i = y)
\]

In words: If you choose an element of the state space according to \( p \) and go one step, the probability to be in \( x \) is \( p(x) \) not only in the first step but also in the second step and consequently in any further step. When you are once in equilibrium, you’ll be forever.

**Theorem 2** If \( X_0, X_1, X_2 \ldots \) is a aperiodic, irreducible Markov chain on a finite state space \( S \) with equilibrium \( p \), it will converge against the equilibrium \( p \) in the following sense:

\[
\forall x,y : \ Pr(X_n = x | X_0 = y) \xrightarrow{n \to \infty} p(x)
\]

**Irreducible means:**

\[
\forall x,y: \exists\forall m : \ Pr(X_{i+m} = x | X_m = y) > 0
\]

**Aperiodic means:**

\[
\forall x,y,m : \ \gcd\{k \in \mathbb{N} | \Pr(X_{k+m} = x | X_m = y) > 0\} = 1,
\]

where \( \gcd \) means “greatest common divisor”.

(let’s watch a Tcl/Tk simulation of a Markov chain)

**“Equilibrium” or “Stationary distribution”** \( p \):

\[
\forall i,x : \ p(x) = \sum_y p(y) \cdot Pr(X_{i+1} = x | X_i = y)
\]

Stronger condition than equilibrium: reversibility (or “detailed balance”)

\[
p(x) \cdot Pr(X_{i+1} = y | X_i = x) = p(y) \cdot Pr(X_{i+1} = x | X_i = y)
\]
In words: If you start in equilibrium, and it is reversible, a move from \( x \) to \( y \) is as probable as a move from \( y \) to \( x \).

Alternative explanation: If you watch a movie of the process starting in a reversible equilibrium, the probability of what you see does not change if you watch the movie backwards.

Given the probability distribution \( \text{Pr}(\cdot | D) \), how can we construct a Markov chain that converges against it?

One possibility: **Metropolis-Hastings**

Given current state \( X_i = x \) propose \( y \) with Prob. \( Q(x \rightarrow y) \)

Accept proposal \( X_{i+1} := y \) with probability

\[
\min \left\{ 1, \frac{Q(y \rightarrow x) \cdot \text{Pr}(y | D)}{Q(x \rightarrow y) \cdot \text{Pr}(x | D)} \right\}
\]

otherwise \( X_{i+1} := X_i \)

(All this also works with continuous state space, with some probabilities replaced by densities.)

**Why Metropolis-Hastings works**

Let’s assume that \( \frac{Q(y \rightarrow x) \cdot \text{Pr}(y | D)}{Q(x \rightarrow y) \cdot \text{Pr}(x | D)} \leq 1 \). (Otherwise swap \( x \) and \( y \) in the following argument).

Then, if we start in \( x \), the probability \( \text{Pr}(x \rightarrow y) \) to move to \( y \) (i.e. first propose and then accept this) is

\[
Q(x \rightarrow y) \cdot \frac{Q(y \rightarrow x) \cdot \text{Pr}(y | D)}{Q(x \rightarrow y) \cdot \text{Pr}(x | D)} = Q(y \rightarrow x) \cdot \frac{\text{Pr}(y | D)}{\text{Pr}(x | D)}
\]

If we start in \( y \), the probability \( \text{Pr}(y \rightarrow x) \) to move to \( x \) is

\[ Q(y \rightarrow x) \cdot 1, \]

since our assumption implies \( \frac{Q(x \rightarrow y) \cdot \text{Pr}(x | D)}{Q(y \rightarrow x) \cdot \text{Pr}(y | D)} \geq 1 \).

This implies that the reversibility condition

\[
\text{Pr}(x | D) \cdot \text{Pr}(x \rightarrow y) = \text{Pr}(y | D) \cdot \text{Pr}(y \rightarrow x)
\]

is fulfilled. This implies that \( \text{Pr}(\cdot | D) \) is an equilibrium of the Markov chain that we have just constructed, and the latter will converge against it. (let’s watch a simulation in R)

**Applying Metropolis-Hastings**

- You are never in equilibrium (your target distribution), but you can get close if you run enough steps.
- You can take more than one sample from the same chain, but you should run enough steps between the sampling steps to make the sampled objects only weakly dependent.
- Your initial state may be “far from equilibrium” (i.e. very improbable). So you should run the chain long enough before you start sampling (“burn-in”).

**Lamarc’s Metropolis-Hastings step**

Proposal chain: Remove a randomly picked branch and let the ancestral lineage of the isolated subtree coalesce with the rest according to \( \Theta \). Total rate of all that can happen to lineage on island 1 or 2 with \( k \) other lineages:

\[
\lambda_1(k) = \frac{k \cdot 2}{\theta_1} + M_{1,2} \quad \lambda_2(k) = \frac{k \cdot 2}{\theta_2} + M_{2,1}
\]

Example:
Step 1: Choose a random branch (each with same prob) and remove it.

To reconnect genealogy generate missing branch according to coalescent model.

Step 2:

- generate random time $T_1$ from exp-distribution with rate $\lambda_1(2)$.
- If $1.3 + T_1 < 1.5$, this is the time for the next event (coalescence or migration).
- Otherwise (as shown here) stop at 1.5.

Step 3:

- draw exponential time $T_2$ with rate $\lambda_1(1)$
- Let’s say $T_2 = 0.2$ (rounded)
- As $1.5 + T_2 < 1.9$, an event takes place
- Choose migration (as here) with prob. $M_{1,2}/\lambda_1(1)$ or coalescence with prob. $(2/\theta_1)/\lambda_1(1)$
Step 4: continue at time 1.7
- draw exponential time $T_3$ with rate $\lambda_2(3)$
- if $1.7 + T_3 > 1.9$ continue line down to 1.9
- (we always stop where the rate needs to be updated)

Step 5: continue at 1.9
- draw exponential time $T_4$ with rate $\lambda_2(2)$
- Let’s say $T_4 \approx 1.3$, such that $1.9 + T_4 = 3.2 < 4.5$.
- Choose migration event with prob. $M_{2,1}/\lambda_2(2)$.
- [or coalescence with prob. $(2/\theta_2)/\lambda_2(2)$]

Step 6:
- draw exponential time $T_5$ with rate $\lambda_1(1)$, let’s say $T_5 \approx 1.0$.
- as $3.2 + 1.0 < 4.9$, event takes place, e.g. with prob. $(2/\theta_1)/\lambda_1(1)$ a coalescence
Lamarck’s Metropolis-Hastings step

Target distribution density: \( p_\Theta(G|D) \), where \( \Theta \) is the current set of parameter values, \( G \) is the genealogy and \( D \) is the data.

Proposal chain: Remove a randomly picked branch and let the ancestral lineage of the isolated subtree coalesce with the rest according to \( \Theta \).

\[ Q(G' \rightarrow G) = \frac{p_\Theta(G')}{p_\Theta(G)} \]

\( \Rightarrow \) The MH acceptance probability is:

\[
\min \left\{ 1, \frac{Q(G' \rightarrow G) \cdot p_\Theta(G'|D)}{Q(G \rightarrow G') \cdot p_\Theta(G)} \right\} = \min \left\{ 1, \frac{p_\Theta(G) \cdot p_\Theta(G', D)}{p_\Theta(G') \cdot p_\Theta(G') \cdot p_\Theta(G)} \right\} = \min \left\{ 1, \frac{p_\Theta(G) \cdot p_\Theta(G', D)}{p_\Theta(G') \cdot p_\Theta(G') \cdot p_\Theta(G)} \right\}
\]

How to compute \( Pr(D|G) \)? Felsenstein’s pruning!

We assume that all sites evolve independent of each other. \( \Rightarrow \)

\[ Pr(D|G) = \prod_i Pr(D_i|G), \]

where \( D_i \) is the \( i \)-th column in the alignment.

How to compute \( Pr(D_i|G) \)? For any nucleotides (or amino acids) \( x, y \) let \( p_x \) be the frequency of \( x \) and \( Pr_{x \rightarrow y}(\ell) \) be the probability that a child node has type \( y \), given that the parent node had type \( x \) and the branch between the two nodes has length \( \ell \). Let’s first assume that \( D_i \) knows the nucleotides at the inner nodes of \( G \):

\[
Pr(D_i|G) = p_C \cdot Pr_{C \rightarrow A}(\ell_5) \cdot Pr_{C \rightarrow C}(\ell_6) \cdot Pr_{A \rightarrow A}(\ell_3) \cdot Pr_{A \rightarrow A}(\ell_4) \cdot \frac{1}{4} \cdot Pr_{C \rightarrow C}(\ell_2) \cdot Pr_{C \rightarrow T}(\ell_2)
\]

How to compute or define \( Pr_{x \rightarrow y}(\ell) \)?

Jukes-Cantor model for DNA evolution

- All nucleotide frequencies are \( p_A = p_C = p_G = p_T = 0.25 \).
- “mutation events” happen at rate \( \lambda \) and let the site forget its current type and select a new one randomly from \{A,C,G,T\}. (New one can be the same as old one.)

\[
Pr_{x \rightarrow y}(\ell) = \begin{cases} 
(1 - e^{-\lambda \ell}) \cdot \frac{1}{4} & \text{if } x \neq y \\
e^{-\lambda \ell} + (1 - e^{-\lambda \ell}) \cdot \frac{1}{4} & \text{if } x = y
\end{cases}
\]

(More sophisticated sequence evolution models in the phylogenetics part of the lecture.)
Felsenstein’s pruning algorithm

How to compute $\Pr(D_i|G)$ if (as usual) the data do only contain the nucleotides for the tips of the tree?

For any node $k$ of the genealogy and any nucleotide (or amino acid) $x$ define $w_k(x)$ to be the probability that, given the nucleotide (or a.a.) in $k$ is $x$, the tips that stem from $k$ get the nucleotides (or a.a.) given in $D_i$. Then

$$\Pr(D_i|G) = \sum_{x \in \{A,C,G,T\}} p_x \cdot w_r(x),$$

where $r$ is the root of the genealogy, and for any node $k$ with child nodes $i$ and $j$ and corresponding branch lengths $\ell_i$ and $\ell_j$ we get:

$$w_k(x) = \left( \sum_{y \in \{A,C,G,T\}} \Pr_{x \rightarrow y}(\ell_i) \cdot w_i(y) \right) \cdot \left( \sum_{z \in \{A,C,G,T\}} \Pr_{x \rightarrow y}(\ell_j) \cdot w_j(z) \right).$$

Felsenstein’s pruning algorithm

If $b$ is a tip of $G$, then $w_b(x)$ is 1 if $x$ is the nucleotide at $b$ in $D_i$, and $w_b(x)$ is 0 otherwise.

With the recursion for $w_k(x)$ given above, we can compute $w_k(x)$ for all $x$ and all $k$ starting with the tips and ending in the root $r$.

From the $w_r(.)$ we can compute $\Pr(D_i|G)$.

Some of the things you should be able to explain

- Time scaling of $1/\mu$ generations and how to calculate $p(G)$ for the structured coalescent
- convergence of Markov chains against equilibria
  - formula and what it means
  - sufficient conditions for this convergence
  - when is an equilibrium reversible and why are not all equilibria reversible
- MCMC, in particular Metropolis-Hastings
- How Importance Sampling and MCMC is combined in LAMARC
  - proposals for changes in the genealogy
  - why LAMARC’s Metropolis-Hastings ratio is so simple
  - Felsenstein’s pruning
  - Jukes-Cantor model and how to compute its transition probabilities

Other MCMC strategy than in LAMARC

References


- assign data to inner nodes
- when choosing new parent node take mutation probs into account
- more intelligent proposals but larger state space
- may be superior for microsatellite data
Ancestral Recombination Graph

When recombination occurs, ancestral lineages for the left and the right part of the sequence split up. Each site has a tree-shaped ancestry, and these trees have complex stochastic dependencies. LAMARC can also sample Ancestral Recombination Graphs instead of trees. If \( k \) lineages are present, the total recombination rate is \( \rho \cdot k \).

As the coalescence rate is

\[ \propto k \cdot (k - 1), \]

the number of lineages will not go to \( \infty \).

Due to random fluctuations, the number of lineages will sooner or later reach 1 (ultimate ancestor).

LAMARC must define for each recombination event which segments follow which lineage.

Excursus: simulation of ARG in ms

- Must define:
  - recombination rate (per locus)
  - number of positions (or unbreakable segments)
- Stop when each nucleotide (or segment) has found its MRCA
- Can be very slow when large genomic regions are simulate
- Other programs such as scrm allow to neglect long-range dependencies

LAMARC Search Strategies

initial chains: several short chains to optimize driving values

final chain: longer chain to narrow the final interval

burn-in: discard e.g. first 5% of each chain

symptom of too few chains: parameters are still changing directionally

symptom of too short chains: parameters leap wildly from chain to chain
Metropolis-Coupled MCMC

If $\beta_i \in (0, 1]$ is heat parameter for chain $i$, then chain $i$ samples from distribution $p^\beta_i : x \mapsto p(x) \cdot \text{const}$, with $\beta_1 = 1$.

The usual MH acceptance prob. for chain $i$ is

$$\min \left\{ 1, \frac{p(y)^{\beta_i}}{p(x)^{\beta_i}} \cdot \frac{Q_{y \rightarrow x}}{Q_{x \rightarrow y}} \right\}.$$ 

Sometimes a swap between the current state $x_i$ of chain $i$ and the current state $x_j$ of chain $j$ is proposed. The acceptance with probability

$$\min \left\{ 1, \frac{p(x_j)^{\beta_i}}{p(x_i)^{\beta_j}} \cdot \frac{p(x_i)^{\beta_i}}{p(x_j)^{\beta_j}} \right\}$$

fulfills the requirements of both chains (check this!).

**Bayesian Lamarc**

Aim: sample parameter values $\Theta$ (and Genealogies) according to the posterior probability distribution $\Pr(\Theta|D)$ (or $\Pr(\Theta, G|D)$) given the data $D$.

- needs priors $\Pr(\Theta)$ for the parameters
- Gibbs sampling scheme: iterate update of the $\Theta$, given $D$ and $G$, and update of $G$, given $\Theta$ and $D$.

**Gibbs sampling**

Assume we want to sample from a joint distribution $\Pr(A = a, B = b)$ of two random variables, and for each pair of possible values $(a, b)$ for $(A, B)$ we have Markov chains with transition probabilities $P^{(A=a)}_{b \rightarrow b'}$ and $P^{(B=b)}_{a \rightarrow a'}$ that converge against $\Pr(B = b|A = a)$ and $\Pr(A = a|B = b)$.

Then, any Markov chain with transition law

$$P_{(a, b) \rightarrow (a', b')} = \begin{cases} 
\frac{1}{2} P^{(B=b)}_{a \rightarrow a'} + \frac{1}{2} P^{(A=a)}_{b \rightarrow b} & \text{if } a = a' \text{ and } b = b' \\
\frac{1}{2} P^{(B=b)}_{a \rightarrow a'} & \text{if } a \neq a' \text{ and } b = b' \\
\frac{1}{2} P^{(A=a)}_{b \rightarrow b'} & \text{if } a = a' \text{ and } b \neq b' \\
0 & \text{else}
\end{cases}$$

**Priors in Bayesian Lamarc**

When new values for $\Theta$ are to be proposed,

- e.g. the new values of $\theta$ and the recombination rate are chosen according to a exponential prior that is uniform on the log scaled interval $[10^{-5}, 10]$ and the growth rate $g$ is chosen uniformly from $[-500, 1000]$.
- For the MH acceptance step use a $U$ that is uniform on $[0, 1]$ and accept if

$$U < \frac{\Pr(G|\Theta_{\text{proposal}})}{\Pr(G|\Theta_{\text{old}})}.$$
Some of the things you should be able to explain

- Difference between LAMARC and Wilson-Balding approach
- Ancestral Recombination Graph (ARG) and its properties
- short and long chains in LAMARC
- how to check convergence in LAMARC
- MCMC (heated chains)
- Differences btw. Bayesian and frequentist LAMARC
- Gibbs sampling

4 IM, IMa, IMa2

References


time

\[ N_i \rightarrow \infty \]
\[ 2N_im_i \rightarrow M_i \]
\[ N_2/N_1 \rightarrow r \]
\[ 4N_1\mu \rightarrow \theta \]
\[ N_A/N_1 \rightarrow a \]
\[ t/(2N_1) \rightarrow \tau \]

\[ \Theta = (\theta, r, a, \tau, M_1, M_2) \]

IM is an implementation of a Bayesian sampler with flat priors, e.g.
\[ M_i \sim \text{Unif}([0, 10]), \quad \tau \sim \text{Unif}([0, 10]) \]
\[ \log(r) \sim \text{Unif}([-10, 10]), \quad \log(a) \sim \text{Unif}([-10, 10]) \]

Proposals \( G^* \) for genealogy updates like in Lamarc with MH acceptance probability
\[
\min \left\{ \frac{1}{1 + \frac{\Pr(D|\Theta, G^*)}{\Pr(D|\Theta, G)}} \right\},
\]
where \( G_i \) is the current genealogy and \( \Theta_i \) is the current vector of parameter values in MCMC step \( i \).

Proposals for parameter updates: Given the current value \( \lambda \) of some parameter, the new value is proposed from \( \text{Unif}[\lambda - \Delta, \lambda + \Delta] \). MH acceptance probability:
\[
\min \left\{ \frac{1}{1 + \frac{p(G_i|\Theta^*)}{p(G_i|\Theta_i)}} \right\}
\]

IM can handle datasets of unlinked loci (but NO intralocus-recombination!).
\[ D = (D^1, \ldots, D^n), \quad D^i: \text{data from locus } i, \quad G = (G^1, \ldots, G^n), \quad G^i: \text{genealogy of locus } i \text{ (including topology, branch lengths, migration times, coalescent times)} \]

\[ p(\Theta|D) = \frac{p(\Theta) \cdot \Pr(D|\Theta)}{\Pr(D)} = \frac{p(\Theta) \cdot \prod_i \Pr(D_i|\Theta)}{\Pr(D)} = \frac{p(\Theta)}{\Pr(D)} \cdot \prod_{i=1}^n \int_{G^i} \Pr(D^i|G^i, \Theta) \cdot p(G^i|\Theta) dG^i \]

additional parameters: locus-specific mutation scalars \( u_i \) with constraint \( \prod_i u_i = 1 \).
Updating \( (u_1, \ldots, u_n) \): choose \( i \) and \( j \) and propose
\[ u_i^* = x \cdot u_i \text{ and } u_j^* = u_j/x, \]
where \( \log(x) \sim \text{Unif}(-\delta, \delta) \).

In IMa, some MCMC steps are replaced by faster numerical computation. We discuss this first in a 1-population model with sample size \( m \).

- Let \( \tau_k \) be the time while the number of lineages is \( k \), measured in \( 1/\mu \) generations.
- \( \Rightarrow \) coalescence rate is \( 2/\theta \)
\[ p(G|\Theta) = \left( \frac{2}{f_m} \right)^{m-1} \cdot \exp(-f_m/\theta), \]

where \( f_m := \sum_{i=2}^{m} \tau_i \cdot i \cdot (i - 1) \). Assume a flat prior \( \theta \sim \text{Unif}(0, \theta_{\text{max}}) \). This implies (with the substitution \( \theta = f_m/x \)):

\[
p(G) = \int_{0}^{\theta_{\text{max}}} p(\theta) \cdot p(G|\theta) d\theta = \frac{1}{\theta_{\text{max}}} \int_{f_m/\theta_{\text{max}}}^{\infty} \left( \frac{2x}{f_m} \right)^{m-1} \cdot e^{-x} \cdot \frac{f_m}{x^2} dx
\]

where \( \Gamma(a,b) = \int_{b}^{\infty} x^{a-1} e^{-x} dx \) is the “incomplete Gamma-function”.

This implies

\[
p(\theta|G) = \frac{p(G|\theta) \cdot p(\theta)}{p(G)} = \frac{(f_m/\theta)^{m-2} \exp(-f_m/\theta)}{\theta \cdot \Gamma(m-2, f_m/\theta_{\text{max}})}
\]

Hence, given \( f_m \), the posterior probability can be computed and the expression above gives a smooth curve.

- works in a similar way for models with subpopulations with migration
- for the split time \( \tau \) a standard MH step is required
- population growth not allowed in IMa (other than IM)
- “branch sliding” proposals for \( G \): move randomly chosen branch a random distance. Current migration events are removed and replaced by a Poisson number of migration events conditioned on odd or even.

**Likelihood Ratio Testing with IMa**

Let

\[
\hat{\Theta}_0 = \arg \max p(\Theta|D) \text{ in the general model}
\]

and

\[
\hat{\Theta}_r = \arg \max p(\Theta|D) \text{ in a restricted model, e.g. without migration}.
\]

Since we use uniform priors for all parameters (some log-scaled), we get

\[
\frac{p(\Theta_0|D)}{p(\Theta_r|D)} = \frac{\text{Pr}(D|\Theta_0) \cdot p(\Theta_0)}{\text{Pr}(D|\Theta_r) \cdot p(\Theta_r)} = \frac{L_D(\Theta_0)}{L_D(\Theta_r)}
\]

Hence, \( \hat{\Lambda} = \log \left( \frac{L_D(\Theta_0)}{L_D(\Theta_r)} \right) \) is an approximation of the log likelihood-ratio and thus, \( 2\hat{\Lambda} \) is approximately \( \chi^2_d \)-distributed under the null hypothesis of the restricted model, where \( d \) is the number of additional parameters in the general model.However, this approximation is only appropriate for extremely large datasets. IMa assesses the significance of \( \hat{\Lambda} \) by comparing it to values of \( \hat{\Lambda} \) from simulations based on the null hypothesis (restricted model).

**Bayes factors**

Other authors use so-called Bayes factors to decide between two models \( M_1 \) and \( M_2 \):

\[
B_{M_1, M_2} = \frac{\text{Pr}(D|M_1)}{\text{Pr}(D|M_2)},
\]

where

\[
\text{Pr}(D|M) = \int p(D, \Theta|M) d\Theta
\]

\[
= \int \text{Pr}(D|M, \Theta) \cdot p(\Theta|M) d\Theta
\]

\[
\approx \left( \frac{1}{m} \sum_{j=1}^{m} \frac{1}{\text{Pr}(D|\Theta_j, M)} \right)^{-1},
\]

31
where $\Theta_1, \ldots, \Theta_m$ are the samples from an MCMC run.

**Why harmonic mean estimator for $Pr(D)$?**

Let $\theta_1, \ldots, \theta_m$ be (approx.) independent samples according to $p(\theta|D)$. Then,

\[
1 = \int p(\theta) d\theta \approx \frac{1}{m} \sum_{i=1}^{m} \frac{p(\theta_i)}{p(\theta_i|D)} \quad \text{(importance sampling)}
\]

\[
= \frac{1}{m} \sum_{i=1}^{m} \frac{p(\theta_i)}{Pr(D|\theta_i)p(\theta_i)} \quad \text{(Bayes formula)}
\]

\[
= Pr(D) \cdot \frac{1}{m} \sum_{i=1}^{m} \frac{1}{Pr(D|\theta_i)}.
\]

$\Rightarrow$

\[
Pr(D) \approx \frac{1}{\frac{1}{m} \sum_{i=1}^{m} \frac{1}{Pr(D|\theta_i)}}.
\]

Advantages of Bayes factors:

- can also support the restricted model while tests can only support the general model by statistically rejecting the restricted one.
- can also compare non-nested models

Problems:

- Prior has influence even for large amount of data
- harmonic mean estimator can have infinite variance (more sophisticated methods exist)
- Tests and Bayesian model selection can lead to opposite results (Lindley’s paradox).

Study accuracy of different possibilities to apply IMa if there is recombination within loci (which is usually the case):

**References**


Note that meanwhile LAMARC also works with demographic models of populations splits.

**Some of the things you should be able to explain**

- Model assumptions and time scaling in IM and IMa
- IM/IMa assumptions for parameter variations among loci
- likelihood-ratio testing vs. Bayes factors
- harmonic mean estimator to compute marginal model probability from MCMC samples

**5 Approximate Bayesian Computation (ABC)**

Problems of full-data methods:

- usual runtime for one dataset: several weeks or months
- complex software, development takes years
- most programs not flexible, hard to write extensions
References


Pritchard et al. (1999)

- Compute MRCA of human Y chromosome in population models with growth.
- Find strong signal of population expansion in all populations.
- Explanations: recent expansion from a small ancestral population in the last 120,000 years or natural selection on the Y chromosome.
- Data: 8 microsatellite loci from 445 humans
- Try various microsatellite mutation models
- Use summary statistics:
  1. mean across loci in the variance of repeat numbers
  2. mean effective heterozygosity
  3. number of distinct haplotypes

Pritchard et al. (1999) Approximate Bayesian Computation

1. Select summary statistics $S = (S_i)_i$ and compute their values $s = (s_i)_i$ for given data set
2. Choose tolerance $\delta$
3. Repeat until k accepted parameter combinations $\Theta'$:
   (a) Simulate $\Theta'$ from prior distribution of $\Theta$
   (b) Simulate genealogy $G$ according to $Pr_{\Theta'}(G)$
   (c) Simulate data and compute values $s'$ of $S$
   (d) Accept $\Theta'$ if $\|s - s'\| \leq \delta$

Only possible if a few summary statistics suffice. Otherwise acceptance will be rare.
5.1 ABC with local regression correction


- combine ABC with local regression:

simulate data for some parameter combinations $\Theta$ and compute corresponding $s$.

- Accept in a wider range but put a smaller weight on $s'$ if $|s - s'|$ is large.

Epanechnikov-Kernel
$$K_\delta(t) = \begin{cases} c \cdot \left( 1 - \left( \frac{t}{\delta} \right)^2 \right) / \delta & \text{for } |t| \leq \delta \\ 0 & \text{for } |t| > \delta \end{cases}$$

where \( c \) is a the normalizing constant:

$$c = 1 / \int_{-\delta}^{\delta} \left( 1 - \left( \frac{x}{\delta} \right)^2 \right) / \delta \, dx$$

Epanechnikov-Kernels with \( \delta = 1 \) and \( \delta = 2 \)


Simulate pairs \((\Theta^{(i)}, s^{(i)})\) and fit local regression model, i.e. find \(\alpha\) and \(\beta\) to minimize

$$\sum_i \left( \Theta^{(i)} - \alpha - (s^{(i)} - s)^T \beta \right)^2 \cdot K_\delta(\|s^{(i)} - s\|),$$

where \(\|v\| = \sqrt{\sum_i v_i^2}\) (or some other vector norm).

Consider

$$\Theta^{(i)}_s = \Theta^{(i)} - (s^{(i)} - s)^T \hat{\beta}$$

as random sample from \(\Pr(\Theta | S = s)\).

Posterior density estimation:

$$\hat{p}(\Theta_0 | S = s) = \frac{\sum_i K_\Delta(\Theta^{(i)}_s - \Theta_0) \cdot K_\delta(\|s^{(i)} - s\|)}{\sum_j K_\delta(\|s - s^{(j)}\|)}$$

where \(\Delta = \) density estimation bandwidth.

**Reminder/Introduction to solution for normal regression**

Problem: predict \(Y\) from \(X_1, X_2, \ldots, X_m\). Observations:

\[
\begin{array}{c}
Y_1, X_{11}, X_{12}, \ldots, X_{1m} \\
Y_2, X_{21}, X_{22}, \ldots, X_{2m} \\
\vdots \\
Y_n, X_{n1}, X_{n2}, \ldots, X_{nm}
\end{array}
\]

with

\[
X_i = \begin{pmatrix}
X_{i1} \\
X_{i2} \\
\vdots \\
X_{in}
\end{pmatrix}
\]

Model: \(Y = a + b_1 \cdot X_1 + b_2 \cdot X_2 + \cdots + b_m \cdot X_m + \varepsilon\) Equation system for \(a, b_1, b_2, \ldots, b_m\):

\[
\begin{align*}
Y_1 &= a + b_1 \cdot X_{11} + b_2 \cdot X_{12} + \cdots + b_m \cdot X_{1m} + \varepsilon_1 \\
Y_2 &= a + b_1 \cdot X_{21} + b_2 \cdot X_{22} + \cdots + b_m \cdot X_{2m} + \varepsilon_2 \\
&\vdots \\
Y_n &= a + b_1 \cdot X_{n1} + b_2 \cdot X_{n2} + \cdots + b_m \cdot X_{nm} + \varepsilon_n
\end{align*}
\]
Model:

\[
Y_1 = a + b_1 \cdot X_{11} + b_2 \cdot X_{12} + \ldots + b_m \cdot X_{1m} + \varepsilon_1 \\
Y_2 = a + b_1 \cdot X_{21} + b_2 \cdot X_{22} + \ldots + b_m \cdot X_{2m} + \varepsilon_2 \\
\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\
Y_n = a + b_1 \cdot X_{n1} + b_2 \cdot X_{n2} + \ldots + b_m \cdot X_{nm} + \varepsilon_n
\]

target variables \( Y \) Explanatory variables \( X_1, X_2, \ldots, X_m \) Parameters to be estimated \( a, b_1, \ldots, b_m \) Independent normally distributed errors \( \varepsilon_1, \ldots, \varepsilon_m \) with unknown variance \( \sigma^2 \).

Approach to estimate \( a \) and \( b \):

minimize residual sum of squares: \( f(\beta) := \sum_{i=1}^{n} \left( Y_i - a - \sum_{j=1}^{m} b_j X_{ij} \right)^2 \)

For this be

\[
\beta = \begin{pmatrix}
a \\
b_1 \\
\vdots \\
b_m
\end{pmatrix}, \quad y = \begin{pmatrix}
Y_1 \\
\vdots \\
Y_n
\end{pmatrix} \quad \text{und} \quad X = \begin{pmatrix}
1 & X_{11} & \ldots & X_{1m} \\
1 & X_{21} & \ldots & X_{2m} \\
\vdots & \vdots & \ddots & \vdots \\
1 & X_{n1} & \ldots & X_{nm}
\end{pmatrix}
\]

and thus \( f(\beta) = \langle y - X \beta, y - X \beta \rangle = \| y - X \beta \|^2 \).

This means: find \( \hat{\beta} \), such that \( \hat{y} = X \hat{\beta} \) has minimal euclidian distance to \( y \).

Geometric solution: minimizing \( f(\beta) = \| y - X \beta \|^2 \) means that \( \hat{y} = X \hat{\beta} \) must be the projection of \( y \) to the space spanned by the vectors \( x_0, x_1, \ldots, x_N \) (with \( x_0 = (1, \ldots, 1)^T \)). Therefore, \( y - X \beta \) must be in a right angle on each \( x_i \),

This implies

\[
\forall i : \langle y - X \hat{\beta}, x_i \rangle = 0,
\]

and thus

\[
(y - X \hat{\beta})^T X = (0, \ldots, 0),
\]

from which we obtain the solution \( \hat{\beta} = (X^T X)^{-1} X^T y \).

**Solution of the local regression problem**

Solution for \( j \)-th parameter: \((\hat{\alpha}, \hat{\beta}_1, \ldots, \hat{\beta}_k) = (X^T W X)^{-1} X^T W \Theta^{(j)}\), where

\[
\Theta^{(j)} = \begin{pmatrix}
\Theta_1^{(j)} \\
\Theta_2^{(j)} \\
\vdots \\
\Theta_m^{(j)}
\end{pmatrix} : \text{Values of the } j \text{-th parameter from } m \text{ simulations},
\]

\( s = (s^{(1)}, \ldots, s^{(k)}) \): Vector of summary statistics for observed data,

\( s_i = (s_i^{(1)}, \ldots, s_i^{(k)}) \): Vector of summary statistics from \( i \)-th simulation,

\[
X = \begin{pmatrix}
1 & s_1^{(1)} & \ldots & s_1^{(k)} \\
1 & s_2^{(1)} & \ldots & s_2^{(k)} \\
\vdots & \vdots & \ddots & \vdots \\
1 & s_m^{(1)} & \ldots & s_m^{(k)}
\end{pmatrix}
\]

and

\( W \) is diagonal matrix with diagonal entries \( K_3(||s_1 - s||), \ldots, K_3(||s_m - s||) \).


**ABC with local regression**

1. Select summary statistics \( S = (S_i)_i \) and compute their values \( s = (s_i)_i \) for given data set
2. Choose tolerance $\delta$ and bandwidth $\Delta$.

3. repeat for $i = 1, \ldots, m$:
   \begin{itemize}
   \item[(a)] Simulate $\Theta^{(i)}$ from prior distribution of $\Theta$.
   \item[(b)] Simulate genealogy $G$ according to $\Pr_{\Theta^{(i)}}(G)$.
   \item[(c)] Simulate data and compute values $s^{(i)}$ of $S$.
   \end{itemize}

4. $(\tilde{\alpha}, \tilde{\beta}) = \arg \min_{\alpha, \beta} \sum_{i=1}^{m} (\Theta_i - \alpha - (s^i - s)^T \beta)^2 \cdot K_\delta(||s^i - s||)$

5. $\Theta^{(i)} := \Theta^{(i)} - (s^{(i)} - s)^T \tilde{\beta}$

6. Approximate $p(\Theta | S = s)$ by $\frac{\sum_j K_\Delta(\Theta^{(i)} - \Theta) K_\delta(||s - s^{(j)}||)}{\sum_j K_\delta(||s - s^{(j)}||)}$

Summary statistics used by Beaumont et al. (2002) for microsatellite data:

1. Mean across loci in the variance of repeat numbers
2. Mean effective heterozygosity
3. Number of distinct haplotypes
4. Mean across loci of kurtosis of repeat numbers
5. Variance across loci of variance of repeat numbers
6. Mean across loci of maximum allele-frequency
7. Multivariate kurtosis
8. Linkage disequilibrium (LD) measured with Hudson’s $\Delta^2$

5.2 MCMC without likelihoods

Marjoram et al. (2003) MCMC without likelihoods

Aim: For given data $D$ with summary statistics $S = s$ sample parameter vectors according to $p(\Theta | ||S - s|| \leq \epsilon)$.

1. If current parameter estimation is $\Theta'$, propose $\Theta^*$ with probability $Q_{\Theta' \rightarrow \Theta^*}$.
2. Simulate data $D^*$ according to $\Theta^*$ and compute their summary statistics $s^*$.
3. If $||s^* - s|| > \epsilon$ reject proposal, else accept with probability
   \[
   \min \left\{ 1, \frac{p(\Theta^*) \cdot Q_{\Theta^* \rightarrow \Theta'}}{p(\Theta') \cdot Q_{\Theta' \rightarrow \Theta^*}} \right\}.
   \]

4. repeat steps 1 to 4.

Application example: Nuu Chah Nulth data, $n=63$ samples of HVR-I.

Estimate $\theta$ and time to the MRCA based on F84 substitution model.

Summary statistics: number of variable sites and number of haplotypes.

Simple approach: when updating parameters, generate entirely new tree. (will usually be rejected $\rightarrow$ inefficient.)

Compromise: keep some information about the tree an modify it slightly for next step:

1. tree topology
2. times of coalescence events
3. number of mutations between two coalescents events
Some of the things you should be able to explain

- Basic rejection ABC
- improvements in local-regression ABC
  - use of Epanechnikov kernel in local regression
  - local regression correction
  - use of Epanechnikov smoothing kernel
  - why this leads to higher accuracy in shorter runtime
- how to combine ABC with Metropolis-Hastings ("MCMC without likelihoods")

5.3 Sequential / Adaptive ABC

Sequential ABC

Basic idea: Run several iterations of ABC, always using the results from the previous run (posterior distribution of parameters) as priors for the new run.

Problem: priors are not allowed to depend on the data. Using posteriors as priors for the analysis of the same data is cheating!

Solution: Make some correction like in importance sampling to make sure that the initial prior is used for the final posterior.

Sequential/Adaptive ABC

References


Sequential/Adaptive ABC (ABC-PMC)

Proposed by Beaumont et al. (2009); PMC=“Population Monte Carlo”

Notations for the description of the algorithm:

\( \hat{\theta}_i^{(t)} \) i-the sampled parameter in iteration t (for simplicity assumed one-dimensional in following pseudocode, but can be parameter vector in general.)

\( S \) vector of summary statistics

\( s_o \) vector of summary statistics for original data

\( \varphi \) density of standard normal distribution \( \mathcal{N}(0,1) \) (can also be multivariate).

\( p(\theta) \) prior probability density

\( p(s|\theta) \) probability density of s given \( \theta \)
\[ \delta_1 > \delta_2 > \cdots > \delta_T \] decreasing thresholds

In most applications \( \theta \) is a vector (a multi-dimensional parameter). Then in the following pseudo-code \( \tau \) is the matrix such that \( \tau^2/2 \) (or actually \( \tau \cdot T(\tau)/2 \), where \( T \) is the transpose operation) is a variance matrix (also called covariance matrix).

References


ABC-PMC

\[
\text{for } i = 1, \ldots, N \text{ do}
\]
\[
\text{repeat}
\]
\[
\text{Draw } \theta_i^{(1)} \text{ from prior and simulate } s \sim p(S|\theta_i^{(1)})
\]
\[
\text{until } ||s, s_0|| < \delta_1
\]
\[
\omega_i^{(1)} := 1/N
\]
\[
\text{end for}
\]
\[
\text{choose matrix } \tau_1 \text{ such that } \tau_1^2/2 = \text{empirical variance matrix of the } \theta_i^{(1)}
\]
\[
\text{for } t = 2, \ldots, T \text{ do}
\]
\[
\text{for } i = 1, \ldots, N \text{ do}
\]
\[
\text{repeat}
\]
\[
\text{Draw } \theta_i^t \text{ from } (\theta_i^{(t-1)}, \ldots, \theta_i^{(1)}) \text{ with probability distribution } (\omega_1^{(t-1)}, \ldots, \omega_N^{(t-1)})
\]
\[
\text{Draw } \theta_i^{(t)} \text{ from } N(\theta_i^t, \tau_{t-1}^2) \text{ and simulate } s \sim p(S|\theta_i^{(t)})
\]
\[
\text{until } ||s, s_0|| < \delta_t
\]
\[
\omega_i^{(t)} \propto p(\theta_i^{(t)}) / \sum_j \omega_j^{(t-1)} \cdot \varphi \left( \tau_{t-1}^{-1} \cdot (\theta_i^{(t)} - \theta_j^{(t-1)}) \right)
\]
\[
\text{end for}
\]
\[
\text{choose matrix } \tau_t \text{ such that } \tau_t^2/2 = \text{empirical variance matrix of the } \theta_i^{(t)}
\]
\[
\text{end for}
\]

(: \propto \text{ means “set proportional to”, such that } \sum_i \omega_i^{(t)} = 1.)

5.4 Optimizing sets of summary statistics with PLS


“[...] the MCMC-based method is consistently superior to the summary-statistics-based methods and highlights that it is well worth making the effort to obtain full-data inferences if possible.”

[Note that “MCMC-based method” here refers to full-data methods]

“[...] there are advantages to the use of summary statistics, both in the ease of implementation and in the time to obtain the results [...]”

“Further research is needed to find a more rigorous way for choosing summary statistics, including the use of orthogonalization and ‘projection-pursuit’ methods”

Wegmann et al. (2009)
ABC estimations with microsatellite data.

**Wegmann et al. (2009)**

- combine MCMC-ABC with Beaumont et al.’s regression approach to sample from $p(\Theta || S - s || \leq \varepsilon)$.
- apply Box-Cox transformation to each summary statistic with respect to the parameter of interest, based on simulated data
- apply partial least squares (PLS) to find combinations of summary statistics that are informative wrt the parameter of interest
- leave-one-out cross validation to optimize number of PLS components used

Simulation studies show improvements compared to other ABC methods but IMa is still better.

Wegmann et al. “[..] would not recommend using an ABC approach if a full-likelihood method exists [..]”.

**Box-Cox transformation**

$$X^{(\lambda)} = \begin{cases} 
\frac{(X+c)^{\lambda}-1}{\lambda} & \text{for } \lambda \neq 0 \\
\ln(X + c) & \text{for } \lambda = 0 
\end{cases}$$
Idea: fit \(\lambda\) and \(c\) such that the residuals of the regression model \(Y = \alpha + \beta X\) look as normally distributed as possible.

**Comparison PCA vs. PLS**

Let \(S\) be the covariance matrix of the vectors \(x_1, \ldots, x_n\) (with \(x_i = (x_{i1}, \ldots, x_{im})\)) that are normalized, that is \(\mu_{x_i} = 0\) and \(\sigma_{x_i} = 1\). Then, the principal component directions \(v_1, \ldots, v_m\) satisfy:

\[
v_j = \arg \max_{\alpha} \left\{ \text{Var} \left( \sum_i x_i \alpha_i \right) \left| \|\alpha\| = 1, \forall_{\ell < j} \sum_\ell v_\ell^T S \alpha = 0 \right. \right\}
\]

The PLS directions \(\varphi_1, \ldots, \varphi_m\) satisfy:

\[
\varphi_j = \arg \max_{\alpha} \left\{ \text{Cov}^2 \left( y, \sum_i x_i \alpha_i \right) \text{Var} \left( \sum_i x_i \alpha_i \right) \left| \|\alpha\| = 1, \forall_{\ell < j} \varphi_\ell^T S \alpha = 0 \right. \right\}
\]

Note that the condition \(v_\ell^T S \alpha = 0\) just means that the new vector \(\sum_j \alpha_j \cdot x_j\) is orthogonal on the previous ones \(\sum_k v_\ell k x_k\) (for any \(\ell < j\)).

To see this, note that from \(\mu_{x_{x_j}} = 0 = \mu_{x_j}\) follows

\[
S_{(k,j)} = \text{Cov}(x_k, x_j) = \frac{1}{m-1} \sum_i (x_{ki} - \mu_{x_k}) \cdot (x_{ji} - \mu_{x_j}) = \frac{1}{m-1} \sum_i x_{ki} x_{ji}
\]

and thus

\[
v_\ell^T S \alpha = \sum_{k,j} v_\ell k \cdot \sum_i x_{ki} x_{ji} \cdot \alpha_j = \frac{1}{m-1} \left( \sum_k v_\ell k x_k, \sum_k \alpha_j x_j \right).
\]

(Remember that the scalar product \(\langle v, w \rangle = \sum_i v_i w_i\) of two vectors \(v\) and \(w\) has the geometric interpretation \(\langle v, w \rangle = ||v|| \cdot ||w|| \cdot \cos(\gamma)\), where \(\gamma\) is the angle between the vectors. Thus, \(\langle v, w \rangle = 0\) holds if and only if \(v\) and \(w\) are orthogonal on each other.)

The scalar product will also be useful on the next slide, on which the algorithm to compute PLS is shown.

The slope of a regression line with response variable \(y\) and explanatory variable \(x\) (both of length \(m\)) can be expressed as

\[
b = \text{Cov}(x, y) / \sigma_y^2
\]

and the intercept is \(a = \mu_y - b \cdot \mu_x\).

If \(y\) is centered and \(x\) is normalized such that \(\mu_x = \mu_y = 0\) and \(\sigma_x = 1\), we obtain the regression line

\[
y = a + bx = 0 + \frac{\text{Cov}(x, y)}{1} = \frac{\sum_i (x_i - \mu_x) (y_i - \mu_y)}{m-1} x = \frac{\sum_i x_i y_i}{m-1} x.
\]

**Partial least squares (PLS)**

Aim: find combinations of explanatory variables \(x_1, \ldots, x_m\) that have highest covariance with variable \(y\).

let \(y\) be centered and \(x_j\) be normalized, i.e. \(\mu_y = 0 = \mu_{x_j}\), \(\sigma_{x_j} = 1\).

1. \((m-1)\)-fold of univariate regression coefficient: \(\varphi_j := \langle x_j, y \rangle := \sum_i x_{ji} y_i \Rightarrow y \approx \frac{1}{m-1} \cdot \varphi_j \cdot x_j\)

2. first partial least squares direction: \(z_1 := \sum_j \varphi_j \cdot x_j\)
3. first regression coefficient: $\delta := \frac{\langle z_1, y \rangle}{\langle z_1, z_1 \rangle} \Rightarrow y \approx \delta \cdot z_1$

4. now orthogonalize $x_1, x_2, \ldots, x_m$ with respect to $z_1$: $x_j^{(2)} := x_j - \frac{\langle z_1, x_j \rangle}{\langle z_1, z_1 \rangle} \cdot z_1$

5. and compute the residuals: $y^{(2)} := y - \delta \cdot z_1$

repeat 1-5 with $x_j$ and $y$ replaced by $x_j^{(2)}$ and $y^{(2)}$. $\Rightarrow z_2, x_j^{(3)}, y^{(3)}$

iterate to get $z_1, z_2, \ldots, z_m$.

**PLS for multiple response variables**


Several possible generalizations of PLS exist for multiple response variables $y_1, \ldots, y_q$, e.g. SIMPLS:

For all $i = 1, \ldots, m$ let $\varphi_i$ be the vector $\alpha$, for which $z_i := x_1 \alpha_1 + \cdots + x_n \alpha_n$ maximizes

$$\sum_{j=1}^{q} \text{Cov}^2(z_i, y_j)$$

subject to the conditions that $||\alpha|| = 1$ and that $\forall k < i : \langle z_i, z_k \rangle = 0$.

**References**


**Some of the things you should be able to explain**

- Why can’t we just iterate ABC on a data set, always using posteriors from previous run as prior?
- How this is corrected in ABC-PMC
- What is PLS and how can it be applied to improve sets of summary statistics, e.g. for ABC?

6 Jaatha and dadi

6.1 Wild Tomatoes and Jaatha 1.0

**Tomato Data**

*Solanum peruvianum*, Canta, Peru

*Solanum chilense*, Moquegua, Peru

**Complex Demography**
substructure  
population growth  
recent speciation  
introgression?  
recombination within loci  
can we still detect selection?

Jaatha
JSFS associated approximation of the ancestry

Malayalam word for “past”.

Strategy: Compare data to data that has been simulated with various combinations of parameter values.

Demographic Model

\[ \text{growth rate } g = \ln(s)/\tau \]
Summarizing the JSFS

JSFS: \( n \times m^{-2} \) classes

JSFS =
Joint Site Frequency

Comparison of summaries:
doi:10.1371/journal.pone.0018155

How do the 23 summary statistics depend on the parameters?
Linearize on each of the 8x8x8 cuboids.

Simple methods in continuous parameter space
How to get from $E$ to Likelihoods?

Composite Likelihood Approach $\Rightarrow$ 23 summary statistics are independently Poisson distributed.

This means, if $s_1, s_2, \ldots, s_{23}$ are the observed summary statistics and $\lambda_1, \lambda_2, \ldots, \lambda_{23}$ their expectations, the composite likelihood is

$$
\frac{\lambda_1^{s_1} \cdot e^{-\lambda_1}}{s_1!} \cdot \frac{\lambda_2^{s_2} \cdot e^{-\lambda_2}}{s_2!} \cdots \frac{\lambda_{23}^{s_{23}} \cdot e^{-\lambda_{23}}}{s_{23}!}
$$

Runtime

Given model with 4 parameters and sample sizes for two populations, simulate data and fit local linear models. 3-5 days

Analyse dataset with quick method: 1-3 seconds

Analyse dataset with slow method: 15 minutes

Compromise “J-Med”: <15 seconds

References

Tomato data: parameter estimations and bootstrap confidence intervals
7 loci, varying from 0.8 to 1.9 kb in size, sampled 23 individuals (i.e. 46 sequences) per species

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Constant</th>
<th>Growth</th>
<th>Fraction-Growth</th>
<th>noMig</th>
<th>FixedTau</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\hat{\theta}_1$</td>
<td>9.41</td>
<td>10.30</td>
<td>12.56</td>
<td>13.34</td>
<td>12.22</td>
</tr>
<tr>
<td>$\hat{q}$</td>
<td>1.83</td>
<td>4.24</td>
<td>4.29</td>
<td>8.67</td>
<td>4.94</td>
</tr>
<tr>
<td></td>
<td>(1.23-2.69)</td>
<td>(2.58-6.95)</td>
<td>(2.71-6.38)</td>
<td>(5.34-15.00)</td>
<td>(3.28-7.85)</td>
</tr>
<tr>
<td>$\hat{m}$</td>
<td>0.36</td>
<td>0.36</td>
<td>0.73</td>
<td>0.55</td>
<td>0.36</td>
</tr>
<tr>
<td></td>
<td>(0.06-4.89)</td>
<td>(0.09-2.34)</td>
<td>(0.39-1.27)</td>
<td>(0.10-2.03)</td>
<td>(0.22-1.03)</td>
</tr>
<tr>
<td>$\hat{\tau}$</td>
<td>0.41</td>
<td>0.37</td>
<td>0.79</td>
<td>0.14</td>
<td>0.36</td>
</tr>
<tr>
<td></td>
<td>(0.05-1.82)</td>
<td>(0.11-0.93)</td>
<td>(0.37-1.63)</td>
<td>(0.10-0.23)</td>
<td>(0.18-0.98)</td>
</tr>
<tr>
<td>$\hat{s}$</td>
<td>0.05</td>
<td>0.44</td>
<td>0.33</td>
<td>0.18-0.98</td>
<td>(0.11-1.10)</td>
</tr>
</tbody>
</table>

log-likelihood: -189.51 -119.70 -101.58 -133.06 -93.96

Growth model: Tomato estimates vs. simulation study

A  J4–7 Loci

B  J4–1000 Loci

parametric-bootstrap confidence intervals

- Simulate 200 datasets according to inferred parameter values
- Infer parameters for each simulated dataset
- For any parameter $\theta$ let $\hat{\theta}$ be the original estimation and $\theta_{0.025}^*$ and $\theta_{0.975}^*$ the 0.025- and 0.975-quantiles of the estimates for the bootstrap datasets
- parametric-bootstrap confidence interval:

$$[2\hat{\theta} - \theta_{0.975}^*, 2\hat{\theta} - \theta_{0.025}^*]$$
based on the idea that \( \mathcal{L}(\theta - \hat{\theta}) \approx \mathcal{L}(\hat{\theta} - \theta^*) \), where \( \theta^* \) is the estimate from some bootstrap simulation

(some refinements exist, e.g. \( BC_\alpha \) bootstrap intervals)

Simulation-based significance testing

- Simulated data according to NoMig model with ML parameter values
- Estimated parameters from simulated data with other models
- Only few (≈ 5 out of 1000) estimated migration rates were as high as for tomato data
- log likelihood-ratios “Mig-NoMig” < 25 (most < 0) for simulated data, > 30 for tomato data with models “fraction-growth” and “growth”

\( \partial \theta \)

References


- also a composite likelihood approach
- computes expected JSFS by diffusion approximation
- uses full JSFS
- is slower than Jaatha but should estimate much more accurately

100 datasets with 100 loci
Divergence time

Migration rate

Theta

Size ratio

100 datasets with 7 loci
Jaatha vs. dadi vs. IM

Simulation Study

- Growth model, equally-sized founder populations
- 100 loci, no recombination within loci
- $\theta \in [5, 20]$ (per locus)
- size ratio $q \in [0.05, 20]$
- divergence time $\tau \in [0.01, 20]$
- migration rate $m \in [0.05, 5]$
- IM runs for 10 datasets, stopped after 5 weeks
6.2 Jaatha 2.0

Jaatha 2.0

- R package
- Also for more than 4 parameters
- Training data are simulated when needed

References


**Simulations with 7 or 200 loci**

First experiment with infinite-sites model, demographic parameters inspired by tomato data:
Recombination rate between 5 and 20 per locus; 25 sampled sequences per population and locus

Simulation Results with 7 loci

Simulation Results with 200 loci
- 100 loci
- \( \theta, q, \tau, m, \alpha \) estimated simultaneously
- ti/tv ratio fixed and assumed to be known
- 7 extra summary stats for double hits and separate counts of ti and tv within and between pops

- \( \tau_0 \) very small, suggesting ongoing gene flow
- estimation quite imprecise
- infinite-sites estimation substantially different from finite-sites estimations
- However, gene flow is significant (simulation-based composite-likelihood ratio test)
6.3 Application to genome-wide data

NGS data of *Arabidopsis thaliana*

- 1.1 million SNPs (after filtering out ambiguous)
- 12 individuals from Spain, 12 from Italy, 5 from Novosibirsk (outgroup)

Model assumptions

- split of southern European populations, constant migration, constant sizes
- Finite-sites, estimate ti/tv
- separately for first or second codon position or UTR (FS), third codon position (Th), and non-coding (NC).

<table>
<thead>
<tr>
<th></th>
<th>(\tau)</th>
<th>(m)</th>
<th>(\alpha)</th>
<th>(\theta_{site})</th>
</tr>
</thead>
<tbody>
<tr>
<td>complete data set</td>
<td>0.16</td>
<td>3.45</td>
<td>2.87</td>
<td>3.54 \times 10^{-3}</td>
</tr>
<tr>
<td>1st or 2nd codon pos or UTR</td>
<td>0.12</td>
<td>2.81</td>
<td>4.83</td>
<td>2.73 \times 10^{-3}</td>
</tr>
<tr>
<td>3rd codon pos</td>
<td>0.19</td>
<td>3.31</td>
<td>1.53</td>
<td>3.70 \times 10^{-3}</td>
</tr>
<tr>
<td>non-coding</td>
<td>0.18</td>
<td>3.33</td>
<td>2.26</td>
<td>4.31 \times 10^{-3}</td>
</tr>
</tbody>
</table>

Parameter estimates for *A. thaliana* using FSM. Jaatha’s estimates using the HKY model for the mutation rate \(\theta\), time \(\tau\) of the split of both demes, the subsequent migration rate \(m\) between populations, and the rate heterogeneity parameter \(\alpha\). The parameter \(\tau\) is scaled in \(2N_e\) generations, \(m\) is twice the number of immigrants to each deme per generation, and \(\theta\) is \(2N_e\) times the mutation rate per base.
Significance of population structure: for 100 simulated panmictic populations $\tau$ was always estimated smaller.

6.4 Statistics in jaatha beyond jsfs

Summary statistics with linkage

Idea: Group loci by how often the 4-gamete condition is violated

\[ \begin{array}{c}
\text{A..G} \\
\text{A..T} \\
\text{A..G} \\
\text{T..G} \\
\end{array} \quad \begin{array}{c}
\text{A..G} \\
\text{A..T} \\
\text{A..G} \\
\text{T..G} \\
\end{array} \]

\[ \begin{array}{c}
\text{near} \\
\text{far} \\
\end{array} \]

\[ \begin{array}{c}
\text{X: polymorphic site} \\
\text{50%} \\
\text{75%} \\
\end{array} \]

\[ \begin{array}{c|c|c|c}
\text{near/far} & 0-33 & 33-66 & 66-100 \\
\hline
0-33 & & & \\
33-66 & & +1 & \\
66-100 & & & \\
\end{array} \]

Novel summary statistics based on spectrum of loci

Manuscripts in preparation

References

[1] Noémie S. Becker, Paul R. Staab, Dirk Metzler (2018+) Inferring demographic parameters for more than two populations with multidimensional site frequency spectra


6.5 Conclusions

Conclusions

- intra-locus recombination difficult to handle rigorosly but allows for composite-likelihood approximations
- more loci needed for getting reasonable estimates
- small datasets require different methods and different sets of summary statistics than large datasets
- not always appropriate to use time-consuming methods for small datasets
- very large datasets can also be analysed with simple methods if not too many parameters to be estimated
- improving choice of summary statistics or smooth estimators for JSFS may be more important than numerics
Some of the things you should be able to explain

- JSFS
- Composite-likelihood approach and Poisson approximation
- (Computational approaches in jaatha 1.0 and jaatha 2.0)
- Why is the JSFS further summarized in jaatha or ABC?
- (bootstrap confidence interval and simulation-based p-values)
- (Summary statistics based on 4-gamete condition)

7 ARG read from left to right and its approximations

7.1 Why ARG read from left to right is not Markovian

- Lineages can coalesce even if they are not ancestral to the same loci

7.2 SMC, SMC’: Markovian approximations of the ARG

References


7.3 MaCS, SCRM: closer approximations of the ARG

References


Main idea of SCRM and MaCS

If distance $b - a$ is greater than threshold (e.g. 100 kb), neglect possibility of coalescence.

Rationale: recombination will anyway quickly separate the lines.
Main difference between SCRM and MaCS

If distance $b - a$ is smaller than threshold:

SCRM:

MaCS (at least original version):

Simulate recombination in non-ancestral segments when needed.

Neglect recombination in non-ancestral segments.

Simulation in Staab et al. (2015)

- 20 sequences
- sequence length 1000 kb
- $\rho = 4000$ for the entire region (that is $4 \text{ / } \text{kb}$)

Simulation in Staab et al. (2015)

- fastsimcoal implementation of SMC’
- newer versions of fastsimcoal (fastsimcoal2) or MaCS may of course give different results
- not clear how much accuracy is actually needed for ABC
8 Hidden-Markov model approaches for coalescents with recombination

8.1 The Pairwise Sequential Markov Chain (PSMC) Approach

References


- More loci and few samples better than vice versa, so how about sample size 2 but whole-genome?
- Even a single diploid genome contains a lot information on demographic history of the whole population
- (implicitly) estimate coalescence times of many regions
- \( N_e \) at a time in history is inverse of frequency of coalescence at that time.
- Markov model for how pairwise coalescence time varies along the genome

What PSMC results may look like

For actual results see [https://www.nature.com/articles/nature10231](https://www.nature.com/articles/nature10231)

Li and Durbin’s findings for human populations

- Data: diploid genomes of 1 Chinese male, 1 Korean male, 3 Europeans, 2 Yoruba (West-Africa)
- Reconstruct within-population \( N_e \) histories from diploid genomes of individuals and between-population from \( X \) chromosomes of male individuals from the two populations.
- Chinese and European ancestry: very similar population sizes before 10-20 kya, including a bottleneck 10-60 kya.
- gene flow between all populations 20-40 kya.
- seems like West-Africans and non-Africans descended from a homogeneous population at most 100 kya.
Pairwise Sequential Markov Chain (PSMC)

Split pair of input sequences into bins of 100 bp

0: homozygous
1: heterozygous

• Hidden Markov chain of coalescent tree lengths according to SMC
• Coalescent trees emit observed 0-1 sequence.

Let \( \theta = 4N_0\mu \) and \( \rho = 4N_0\tau \), where \( \mu \) and \( \rho \) are per 100 bp.

Emission probabilities for 2-sequence coalescent of length \( s \):

\[
\begin{align*}
0 & : e^{-\theta s} \\
1 & : 1 - e^{-\theta s}
\end{align*}
\]

SMC transition rate from tree length \( s \) to tree length \( t \)

First for \( t < s \):

For the simple case of constant \( N_e = N_0 \):

\[
(1 - e^{-\rho t}) \frac{1}{t} \int_0^t 1 \cdot e^{-(t-u)} du = (1 - e^{-\rho t}) \frac{1 - e^{-t}}{t}
\]

For \( N_e(t) = N_0 \cdot \lambda(t) \):

\[
(1 - e^{-\rho t}) \frac{1}{t} \int_0^t \frac{1}{\lambda(t)} \cdot e^{-\int_u^t \frac{1}{\lambda(v)} dv} du
\]

Note that PSMC uses SMC (not SMC') and thus neglects cases like this.

SMC transition rate from tree length \( s \) to tree length \( t \)

Now \( t > s \) and \( N_e(t) = N_0 \cdot \lambda(t) \):

\[
(1 - e^{-\rho s}) \frac{1}{s} \int_0^s \frac{1}{\lambda(t)} \cdot e^{-\int_u^t \frac{1}{\lambda(v)} dv} du
\]

In the case of \( t = s \) account for the probability \( e^{-\rho s} \) that no recombination takes place.
8.2 Excursus: hidden Markov models (HMMs)

Hidden Markov Models (HMMs) in general

$X_1, X_2, \ldots, X_n$ hidden (=unobserved) Markov chain on finite state space $\mathcal{M}$. $S_1, S_2, \ldots, S_n$ series of “signals” with observations $s_1, s_2, \ldots, s_n$.

$P_{x \rightarrow y}$: transition probability $\Pr(X_i = y \mid X_{i-1} = x)$

$e_x(s)$: emission probability $\Pr(S_i = s \mid X_i = x)$ ($S_i$ depends only on $X_i$)

HMM examples

<table>
<thead>
<tr>
<th>application</th>
<th>hidden</th>
<th>observed</th>
</tr>
</thead>
<tbody>
<tr>
<td>PSMC</td>
<td>Coalscent times</td>
<td>homozygous or heterozygous</td>
</tr>
<tr>
<td>CpG island detection</td>
<td>in island or not</td>
<td>nucleotides</td>
</tr>
<tr>
<td>Structure</td>
<td>which cluster</td>
<td>alleles</td>
</tr>
<tr>
<td>PAC</td>
<td>closest relative haplotype</td>
<td>alleles</td>
</tr>
<tr>
<td>protein profileHMM</td>
<td>sequence position</td>
<td>amino acid</td>
</tr>
<tr>
<td>alignment pairHMM</td>
<td>alignment</td>
<td>pair of sequences</td>
</tr>
<tr>
<td>nanopore sequencing</td>
<td>tuple of nucleotides</td>
<td>electrostatic signal</td>
</tr>
</tbody>
</table>

HMM application examples

CpG island detection

nanopore sequencing

profileHMM of a protein family

Database Center for Life Science (DBCLS)

Creative Commons License

image source: https://commons.wikimedia.org/wiki/File:202001_nanopore_sequencing.svg

pairHMM for sequence alignment
Classical HMM algorithms

**forward algorithm**: Calculate Likelihood of parameters, that is, for given parameter values the probability Pr(S_1 = s_1, S_2 = s_2, ..., S_n = s_n) of the observed sequence s_1, ..., s_n, summing over all possible chains x_1, ..., x_n.

**backward algorithm**: Calculates the same as forward algorithm in another way.

**forward–backward algorithm** Calculates for each i and x, y of the Markov chain state space

\[
\begin{align*}
\Pr(X_i = x) & = \Pr(S_1 = s_1, S_2 = s_2, ..., S_i = s_i, X_i = x) \\
\Pr(X_i = x, X_{i+1} = y) & = \Pr(S_1 = s_1, S_2 = s_2, ..., S_n = s_n)
\end{align*}
\]

**Baum–Welch algorithm**: Fit HMM parameter to given observation s_1, s_2, ..., s_n.

**Viterbi algorithm**: Find most probable chain of hidden states x_1, x_2, ..., x_n for given observation s_1, s_2, ..., s_n (and given parameter values).

**HMM forward algorithm**

\[
f_i(x) = \Pr(S_1 = s_1, S_2 = s_2, ..., S_i = s_i, X_i = x)
\]

\[
f_i(x) = \sum_{y \in M} f_{i-1}(y) \cdot P_{y \rightarrow x} \cdot e_x(s_i)
\]

Time complexity: \(O(|M|^2 \cdot n)\).

(if all transitions \(x \rightarrow y\) for \(x, y \in M\) allowed)

**HMM backward algorithm**

\[
b_i(x) = \Pr(S_{i+1} = s_{i+1}, S_{i+2} = s_{i+2}, ..., S_n = s_n \mid X_i = x)
\]

\[
b_i(x) = \sum_{y \in M} b_{i+1}(y) \cdot e_x(s_i) \
\]

\[
b_n(x) = e_x(s_n)
\]
Pr(S_1 = s_1, S_2 = s_2, ..., S_n = s_n) = \sum_{x \in M} p_x \cdot e_x(s_1) \cdot b_1(x)

b_i(x) = \sum_{y \in M} P_{x \rightarrow y} \cdot e_y(s_{i+1}) \cdot b_{i+1}(y)

combination of forward and backward variables

From Pr(S_1 = s_1, ..., S_n = s_n | X_i = x) = Pr(S_1 = s_1, ..., S_i = s_i | X_i = x) \cdot Pr(S_{i+1} = s_{i+1}, ..., S_n = s_n | X_i = x) follows

Pr(X_i = x | S_1 = s_1, ..., S_n = s_n) = \frac{Pr(X_i = x, S_1 = s_1, ..., S_n = s_n)}{Pr(S_1 = s_1, ..., S_n = s_n)} = \frac{Pr(S_1 = s_1, ..., S_n = s_n)}{Pr(S_1 = s_1, ..., S_n = s_n)}

and

Pr(X_{i-1} = x, X_i = y | S_1 = s_1, ..., S_n = s_n) = \frac{f_{i-1}(x) \cdot P_{x \rightarrow y} \cdot e_y(s_i) \cdot b_i(y)}{Pr(S_1 = s_1, ..., S_n = s_n)}

This allows us to calculate for given s_1, ..., s_n the expected numbers of emissions of any s from any x \in M and the numbers of transitions x \rightarrow y for all x, y \in M, averaged over all hidden chains weighted with their posterior probabilities.

These expectation values are used in the Baum–Welch algorithm, an EM algorithm to estimate transition and emission probabilities (from emissions only; chains are still hidden).

Baum–Welch algorithm

Expectation–Maximization algorithm to estimate HMM parameters from observed data.

Begin with initial HMM transition and emission probability values and repeat the following steps until convergence:

E step: With the current HMM parameters apply forward–backward algo to get

Pr(X_i = x, X_{i+1} = y | s_1, ..., s_n) and Pr(X_i = x | s_1, ..., s_n)

for each step i and all MC states x and y.

• With this calculate the expectation values for the fractions of transitions to y from x and the distribution of emissions from x, e.g.:

\[ \sum_i Pr(X_i = x, X_{i+1} = y | s_1, ..., s_n) / \sum_i Pr(X_i = x | s_1, ..., s_n) \]

M step: Fit the transition probabilities and emission probabilities to the expected relative frequencies and repeat E-step and then M-step with the updated parameters.
Viterbi algorithm

\[
v_i(x) = \max_{(x_1, \ldots, x_{i-1}) \in M^{i-1}} \Pr(S_1 = s_1, S_2 = s_2, \ldots, S_i = s_i, X_1 = x_1, \ldots, X_{i-1} = x_{i-1}, X_i = x)
\]

Allows us to trace back the most probable \( x_1, x_2, \ldots, x_n \) for given \( s_1, s_2, \ldots, s_n \).

\[
v_i(x) = \max_{y \in M} v_{i-1}(y) \cdot P_{y \rightarrow x} \cdot e_x(s_i)
\]

8.3 Back to PSMC

How HMM algorithms are applied in PSMC

- time is binned with boundaries \( 0.1 \cdot e^\frac{\log(1+10^{T_{\text{max}}})}{k} \) for \( i = 0, 1, \ldots, k \)
- thus, each run of the forward, backward has \( O(k^2 \cdot n) \) runtime
- parameter estimation with Baum–Welch, combined with Powell’s numerical optimization algorithm

Possible Problem for PSMC approach

- used data is distribution of nucleotide diversity across genomic regions
- but this distribution may depend also on variation in mutation rates
- Li and Durbin (2011) carry out simulation study
  - mutation rate variation according to human–macaque alignment
  - result is that these rate variations alone would not explain PSMC results
- More simulation studies for robustness in supplement to Li and Durbin (2011)

8.4 MSMC and MSMC2

MSMC

References


- input multiple sequences
- Hidden Markov chain states refer to most recent coalescent events
- Aim to get better resolution for more recent demographic history
- Calculations based on SMC’ (instead of SMC)
Hidden state in MSMC: time an lineages of most recent coalescence

Emissions:

- singleton outside
- singleton inside
- higher-freq. variant

MSMC neglects:

- all dependencies that are neglected in SMC'
- all other information contained in coalescent outside pair (grey lines)
- emissions depend not only on chain state

MSMC2

References


- MSMC for practical purposes limited to 8 haplotypes
- Biases in MSMC due to approximations in the HMM emission rates
- MSMC2: composite likelihood approach using pairwise coalescents

Some of what you should be able to explain

- Differences between SMC, SMC’, MaCS, SCRM and the ARG
- PSMC
  - model assumptions and HMM approach
  - how to draw conclusions
- HMM algorithms
  - forward
  - forward–backward
  - Baum–Welch
  - Viterbi
- basic ideas of MSMC and MSMC2
9 The program STRUCTURE

examples

References


References


9.1 no admixture, no sampling locations

Hardy-Weinberg

<table>
<thead>
<tr>
<th>A: p</th>
<th>a: 1 – p</th>
</tr>
</thead>
<tbody>
<tr>
<td>AA</td>
<td>Aa</td>
</tr>
<tr>
<td>p^2</td>
<td>2p · (1 – p)</td>
</tr>
</tbody>
</table>

Wahlund effect

<table>
<thead>
<tr>
<th>p</th>
<th>1 – p</th>
</tr>
</thead>
<tbody>
<tr>
<td>AA</td>
<td>Aa</td>
</tr>
<tr>
<td>Aa</td>
<td>aa</td>
</tr>
</tbody>
</table>
Linkage disequilibrium due to population structure

\[
\begin{array}{c|c|c}
(A, B) & (A, b) \\
(1 - x) & (1 - y) & (1 - x) \\
\end{array}
\]

\[
\begin{array}{c|c|c}
(a, B) & (a, b) \\
(1 - x) & (1 - y) & (1 - x) \\
\end{array}
\]

Structure: A program for model-based clustering of genotypes (Microsatellites, SNPS, AFLPs, . . .)

\[N\] diploid individuals, \(L\) loci, \(K\) (sub)populations

unknown which individuals belong to which population, even if sampling locations are known, i.e. subpopulations may not correspond to sampling locations.

known is the genotype of individual each \(i\) at locus \(\ell\):

\[X = (x_{i}^{(1,1)}, x_{i}^{(1,2)})_{1 \leq N, \ell \leq L}\]

unknown are the populations from which individual \(i\) originates:

\[Z = (z^{(i)})_{i \leq N}\]

and the frequencies of allele \(j\) at locus \(\ell\) in population \(k\):

\[P = (p_{k\ell j})_{k \leq K, \ell \leq L, j \leq J}\]

Assumption 1: each population is in Hardy-Weinberg equilibrium

Assumption 2: linkage equilibrium between loci

Bayesian approach: approximate sample from

\[
Pr(Z, P \mid X) \propto Pr(Z) \cdot Pr(P) \cdot Pr(X \mid Z, P)
\]

Priors for origin population of individual \(i\):

\[Pr(z^{(i)} = k) = 1/K\]

Dirichlet prior for allele frequencies in each population:

\[p_{k\ell} \sim D(\lambda_1, \lambda_2, \ldots, \lambda_{J_{\ell}})\text{ with } \lambda_1 = \lambda_2 = \cdots = \lambda_{J_{\ell}} = 1\]

(uniform distribution on all distributions)

\[
Pr(X \mid Z, P): \quad Pr(x_{i}^{(i,a)} = j \mid Z, P) = p_{z^{(i)}_{\ell j}}
\]
Dirichlet distribution

If \( Y \sim \mathcal{D}(\alpha_1, \ldots, \alpha_k) \) then

\[
\Pr(Y = (y_1, \ldots, y_k)) = c(\alpha) \prod_{i=1}^{k} y_i^{\alpha_i - 1}
\]

if all \( y_i \geq 0 \) and \( \sum_i y_i = 1 \), else 0.

\[
\mathbb{E}(Y) = \frac{(\alpha_1, \ldots, \alpha_k)}{\sum_i \alpha_i}
\]

100 samples from \( \mathcal{D}(1,1,1) \)

100 samples from \( \mathcal{D}(10,10,10) \)

100 samples from \( \mathcal{D}(0.1,0.1,0.1) \)

100 samples from \( \mathcal{D}(10,20,30) \)

Important property of Dirichlet distributions
Let $N = (n_1, \ldots, n_K)$ multinomially distributed with (unknown) probabilities $P = (p_1, \ldots, p_K)$, i.e.

$$\Pr(N = (n_1, \ldots, n_m)) = \frac{(n_1 + n_2 + \cdots + n_k)!}{n_1! \cdot n_2! \cdots n_k!} \prod_{i=1}^{k} p_i^{n_i}.$$ 

If the prior distribution of $P$ is $\mathcal{D}(\lambda_1, \ldots, \lambda_k)$, then the posterior distribution of $P$ given $N = (n_1, \ldots, n_k)$ is

$$\mathcal{D}(\lambda_1 + n_1, \ldots, \lambda_k + n_k).$$

(Exercise!) MCMC method for sampling from $\Pr(Z, P \mid X)$: Start with $Z^{(0)}$ (e.g. sampled from prior) and iterate 2 steps for $m = 1, 2, 3, \ldots$:

1. Sample $P^{(m)}$ from $\Pr(P \mid X, Z^{(m-1)})$

$$p_{k\ell} \mid X, Z \sim \mathcal{D}(\lambda_1 + n_{k\ell 1}, \ldots, \lambda_J + n_{k\ell J}),$$

where $n_{k\ell j} = \# \{(i, a) \mid x^{(i, a)} = j \text{ and } z(i) = k\}$. (using the important property of the Dirichlet distribution.)

2. Sample $Z^{(m)}$ from $\Pr(Z \mid X, P^{(m)})$

$$\Pr(z(i) = k \mid X, P) = \frac{\Pr(x(i) \mid P, z(i) = k)}{\sum_{k'} \Pr(x(i) \mid P, z(i) = k')},$$

using $\Pr(x(i) \mid P, z(i) = k) = \prod_{\ell=1}^{L} p_{k\ell x^{(i, a)}_{\ell}} \cdot p_{k\ell x^{(i, a)'}_{\ell}}$.

### 9.2 with admixture

**admixture**: present individuals stem from $k$ populations that were admixed recently.

**$Q$:** $(q_k^{(i)})_{i \leq N, k \leq K} = \text{proportion of individual } i\text{'s genome originating from population } k$

**$Z$:** $(z^{(i, a)}_{\ell}) = \text{population of origin of allele copy } x^{(i, a)}_{\ell}$

$$\Pr(x^{(i, a)}_{\ell} = j \mid Z, P) = p_{z^{(i, a)}_{\ell}, j}, \quad \Pr(z^{(i, a)}_{\ell} = k \mid Q) = q_k^{(i)}$$

Prior on $Q$:

$$q^{(i)} = (q_1^{(i)}, \ldots, q_K^{(i)}) \sim \mathcal{D}(\alpha, \ldots, \alpha),$$

where $\alpha$ is also random with prior $\alpha \sim \text{unif([0, } \alpha_{\text{max}}]).$

Note:

$\alpha = 0 \iff \text{no admixture}$

$\alpha \to \infty \iff \text{all completely admixed}$

[.5cm] **Interpretation of bars**

**without admixture**: probabilities of subpopulations to be the origin of individual

**with admixture**: relative contributions of subpopulations to the genome of the individual

68
MCMC for case of admixture

Start with initial $P^{(0)}$, $Q^{(0)}$, $Z^{(0)}$ and $\alpha^{(0)}$ and iterate for $m = 1, 2, \ldots$

1. Sample $P^{(m)}$ and $Q^{(m)}$ from $\Pr(P, Q | X, Z^{(m-1)})$:
   update $q_{k,I}^m$ based on the number of $\ell$ copies of type $j$ that come from population $k$
   $$r_{k,I} = \{(i, a) | x_{I}(i, a) = j \text{ and } z_{I}(i, a) = k\}$$
   and sample $q_{I}^m | X, Z$ according to
   $$\mathcal{D} \left( \alpha + \# \left\{(\ell, a) : z_{I}^{(i,a)} = 1\right\}, \ldots, \alpha + \# \left\{(\ell, a) : z_{I}^{(i,a)} = K\right\} \right)$$

2. Sample $Z^{(m)}$ from $\Pr(Z | X, P^{(m)}, Q^{(m)})$ according to:
   $$\Pr \left( z_{I}^{(i,a)} = k \mid X, P^m \right) = \frac{q_{k}^{(i)} \cdot p_{k}^{(i,a)}}{\sum_{h=1}^{K} q_{h}^{(i)} \cdot p_{h}^{(i,a)}}$$

3. Metropolis Hastings step $\alpha^{(m-1)} \rightarrow \alpha^{(m)}$:
   propose $\alpha' \sim N(\alpha, \text{some } \sigma^2)$, reject immediately if $\alpha' < 0$, else perform MH step.

Inference for $Z, P, Q$ from MCMC samples

for example for $Q$ it seems obvious to estimate
$$E(q_{I} | X) \approx \frac{1}{M} \sum_{m=1}^{M} q_{I}^{(m)},$$
but the theoretical posterior mean is
$$E(q_{I} | X) = \left( \frac{1}{K}, \ldots, \frac{1}{K} \right)$$
due to symmetries in the model (numbering of populations exchangeable).

$\approx$ use modes of $\left( q_{I}^{(1)}, \ldots, q_{I}^{(M)} \right)$ instead of means or use Noah Rosenberg’s software CLUMPP to evaluate STRUCTURE output.

Inference for the number $K$ of populations

$$\Pr(K | X) \propto \Pr(X | K) \cdot \Pr(K)$$
can be approximated using the harmonic mean estimator
$$\Pr(X | K) \approx M \left( \frac{1}{\sum_{i=1}^{M} \Pr(X | K, Z^{(i)}, P^{(i)}, Q^{(i)}, \alpha^{(i)})} \right),$$
but the harmonic mean estimator is known to be imprecise.

Instead, we hope that $-2 \log L(Z, P, Q, \alpha | X)$ is approximately normally distributed and estimate
$$\Pr(X | K) \approx e^{-\hat{\mu}/2 - \hat{\sigma}^2/8}$$
with $\hat{\mu} = \frac{1}{M} \sum_{i=1}^{M} -2 \log \Pr \left( X | Z^{(i)}, P^{(i)}, Q^{(i)}, \alpha^{(i)} \right)$
and $\hat{\sigma}^2 = \frac{1}{M} \sum_{i=1}^{M} \left( -2 \log \Pr \left( X | Z^{(i)}, P^{(i)}, Q^{(i)}, \alpha^{(i)} \right) - \hat{\mu} \right)^2$

Pritchard et al. write about this approximation:
“In fact the assumption underlying [this] are dubious at best, and we do not claim (or believe) that our procedure provides a quantitatively accurate estimate of the posterior distribution of $K$. We see it merely as an ad hoc guide to which models are most consistent to the data, with the main justification being that it seems to give reasonable answers in practice.”

and:

“The inferred value of $K$ may not always have a clear biological interpretation.”

and about the multiple-modes problem:

“[The] Gibbs-sampler did not manage to move between two modes in any of the runs”

Data examples

Bird example: Without using informations on sampling locations, STRUCTURE gave clear clusters corresponding to sampling locations, up to a few exceptions. Neighbor-Joining results did not show clear clusters when labels were removed. [http://www.genetics.org/content/155/2/945/F4.large.jpg](http://www.genetics.org/content/155/2/945/F4.large.jpg) [http://www.genetics.org/content/155/2/945/F3.expansion.html](http://www.genetics.org/content/155/2/945/F3.expansion.html)

Human data: Found $K \geq 2$ corresponding to African and European origin of samples. Evidence for $K > 2$ may indicate substructure.

Some of the things you should be able to explain

- Wahlund effect and its analogon for linkage
- Dirichlet distribution and how they are used in Structure
- How Dirichlet priors lead to Dirichlet posteriors
- MCMC method in structure
- meaning of Structure barplots with and without admixture

9.3 taking sampling locations into account

First attempt: populations correspond to sampling locations with a few migrants in the last few generations.

$q(i)$: sampling location of individual $i$

$\nu$: probability that $i$ is immigrant or offspring of an immigrant in the last $G$ generations, where $G$ is not too large.

$\Rightarrow q^{(i)}_{g(i)} = 1$ with probability $1 - \nu$ and for $t \leq G$:

$q^{(i)}_{g(i)} = 1 - 2^{-t}$ and $q^{(i)}_{j} = 2^{-t}$ with probability $\frac{2^t \nu}{(k-1) \sum_{t=0}^{G} 2^t}$ (neglecting the possibility of more than one migrating ancestor in the last $G$ generations.)

in MCMC: sampling of $q^{(i)}$ is conditioned $P$, $X$ and $Z$.

Falush et al. (2003) allow for LD between loci. Advantages:

1. detection of admixture further back into past
2. inference of population of origin of chromosomal regions
3. more accurate estimate of statistical uncertainty when linked loci are used

Sources of LD:

mixture LD: variation in ancestry among sampled individuals (Prichard et al.)
**admixture LD:** correlation of ancestry along each chromosome causes additional LD between linked markers (Falush et al.)

**background LD:** within population decaying on a much shorter scale, e.g. tens of kb in humans. (not yet in STRUCTURE)

Approach of Falush et al. (2003):
- breakpoints occur as Poisson process at rate $r$
- uniform prior on $\log(r)$
- use HMM to sample from conditional distribution of $Z$
- data allowed to be unphased

more options: correlated allele frequencies between populations according to star-shaped phylogeny of populations with drift rates $F_1, \ldots, F_K$ and ancestral allele frequency distribution $p_A \sim D(\lambda_1, \ldots, \lambda_J)$.

$$p_{kl} | p_A \sim D \left( \frac{p_{Akl} 1 - F_1}{F_1}, \ldots, \frac{p_{Akl} 1 - F_K}{F_K} \right)$$

*(be careful with this model!)*

Approach of Hubisz et al. (2009): Allow uncertainty in the information about sampling location

$$r \sim \text{unif}([0, r_{\text{max}}])$$

$$q^{(i)} \sim D (\alpha_{h1}, \ldots, \alpha_{hK}), \text{ if individual } i \text{ comes from location } h$$

$$\alpha_{hk} \sim \Gamma \left( r \cdot \alpha_{\text{glob}}^k, 1/r \right), \text{ (which entails that the mean is } \alpha_{hk}^{\text{glob}} \right)$$

$$\alpha_{\text{glob}}^k \sim \text{unif}(0, \alpha_{\text{max}})$$

Hubisz et al.: “However, we would still encourage users to run the original models as well, and to check that substantial differences between the results from the new and the old models seem biologically sensible.”

When STRUCTURE has problems
- number of clusters not well-defined when allele frequencies vary slowly across the landscape
- inbreeding or relatedness between individuals

In this case, the software INSTRUCT may help, cf.

**References**


9.4 Faster alternatives to STRUCTURE for large datasets

9.4.1 ADMIXTURE

ADMIXTURE
- is based on the same modeling approach as STRUCTURE
- (faster) ML optimization instead of Bayesian sampling
optimization strategy: similar to Newton’s method

Problem: Huge Hesse matrix (2\textsuperscript{nd} derivatives) as there are many parameters.

\(Q\): \(q_{ik}\) is proportion of individual \(i\) genome coming from population \(k\)

\(F\): \(f_{k\ell}\) is the frequency of allele 1 of locus \(\ell\) in population \(k\) (assuming two alleles per locus).

\(\Rightarrow\) Many second derivatives

\[\frac{\partial^2}{\partial q_{ik}\partial f_{k\ell}}\]

Also the constraints 0 \(\leq f_{kj} \leq 1\), \(q_{ik} > 0\), \(\sum_k q_{ik} = 1\) make optimization a bit tricky.

ADMIXTURE uses Block Relaxation Algorithm

- like Newton method uses first two derivatives
- To optimize \(L(Q,F)\) iterate
  - update \(Q\) for fixed \(F\)
  - update \(F\) for fixed \(Q\)
- no mixed 2\textsuperscript{nd} derivatives \(\frac{\partial^2 L}{\partial q_{ik}\partial f_{ij}}\) needed
- need \(\frac{\partial^2 L}{\partial q_{ik}\partial q_{i'k'}}\) only if \(i = i'\).
- need \(\frac{\partial^2 L}{\partial f_{k\ell}\partial f_{k'\ell'}}\) only if \(\ell = \ell'\).
- optimization problems are convex.

9.4.2 fastSTRUCTURE

fastSTRUCTURE

References


Variational Distributions: tractable family of distributions to approximate posterior.

Variational Bayesian Inference: Instead of sampling from posterior, optimize parameters of variational distributions

Kullback-Leibler Divergence: (\(=\)relative entropy)

\[D_{KL}(q||p) = \mathbb{E}_q \log \frac{q(X)}{p(X)} = \int_x q(x) \log \frac{q(x)}{p(x)} dx\]

Approach: Find variational distribution \(q\) that minimizes \(D_{KL}(q||p)\) to posterior \(p\).

Unrealistic assumption to make variational distributions \(q\) tractable:
Their joint variational distribution density is the product of multinomial probabilities for \(Z\), Dirichlet densities for \(Q\), and beta densities for \(P\).

The parameters of these distributions are optimized.
Also here, the optimization of the parameters of one of distribution, keeping the others fixed, is a convex optimization problem.
9.4.3 snmf() in the Bioconductor R package LEA

The LEA package

http://membres-timc.imag.fr/Olivier.Francois/LEA/index.htm

Installation:

source("https://bioconductor.org/biocLite.R")
biocLite("LEA")

References


(We focus on the sNMF method of Frichon et al., 2014)

Ideas behind sNMF:

- By not assuming Hardy-Weinberg equilibrium
  - we may lose a bit of information but
  - make the method more robust against inbreeding
  - and make the method computationally less demanding.

- Combine efficient solutions from numerics / statistics
  - linear regression / least squares:
    Minimize \( S(q) = \sum_j (y_j - \sum_k q_k V_{kj})^2 \)
    by \( \hat{q} = (V^T V)^{-1} V^T y \)
  - regularization / ridge regression:
    In linear regression avoid overfitting by extreme coefficients by an additional penalty. That is, minimize
    \[
    S(q) = \sum_j (y_j - \sum_k q_k V_{kj})^2 + \alpha \cdot \sum_k q_k^2
    \]
    for some regularization penalty \( \alpha > 0 \).
  - convex optimization:
    minimize a convex function \( f \) on a convex definition range \( D \subseteq \mathbb{R}^n \).

Convex Optimization

\( D \) is convex if \( \forall x \in D, y \in D, \lambda \in [0, 1] : \lambda \cdot x + (1 - \lambda) \cdot y \in D \).

\( f : D \to \mathbb{R} \) is convex if \( \forall x \in D, y \in D, \lambda \in [0, 1] : \)

\[
    f(\lambda \cdot x + (1 - \lambda) \cdot y) \leq \lambda \cdot f(x) + (1 - \lambda) \cdot f(y).
\]

Nice: All local minima of convex functions on convex sets \( D \) are global minima and form a convex set.

Example for convex optimization: Minimize

\[
    S(q) = \sum_j (y_j - \sum_k q_k V_{kj})^2 + \alpha \cdot \sum_k q_k^2
\]

(where \( \alpha > 0 \)) with the side condition that \( \forall k : q_k > 0 \).

This can be solved efficiently by nonnegative matrix factorization (NMF), see
References


How these methods are combined in Frichot et al.’s sNMF.

Notations:

\( j \in \{0, 1, 2\} \) genotype at diploid locus; 1 means heterozygous

\( x_{i\ell}(j) \in \{0, 1\} \) 1 if individual \( i \) has genotype \( j \) at locus \( \ell \).

\( q_{ik} \) fraction of \( i \)'s genome coming from subpopulation \( k \)

\( g_{k\ell}(j) \) frequency of genotype \( j \) at locus \( \ell \) in population \( k \)

Aim: Find \( q = (q_{ik})_{ik} \) and \( g = (g_{k\ell}(j))_{k\ell j} \) that minimize

\[
LS(q, g) = \sum_{i,\ell,j} \left( x_{i\ell}(j) - \sum_k q_{ik} g_{k\ell}(j) \right)^2
\]

Choose some \( \alpha > 0 \), then start with initial \((q,g)\) and iterate the following steps 1 and 2 until you observe convergence:

1. keeping the current \( q \) fixed, update \( g \):
   - (a) minimize (like in linear regression):
     \[
     LS_1(g) = LS(q, g) = \sum_{i,\ell,j} \left( x_{i\ell}(j) - \sum_k q_{ik} g_{k\ell}(j) \right)^2
     \]
   - (b) set all negative \( g_{k\ell}(j) \) to 0
   - (c) \( \forall k, \ell: \) normalize \((g_{k\ell}(0), g_{k\ell}(1), g_{k\ell}(2))\) such that \( \sum_j g_{k\ell}(j) = 1 \).

2. keeping the current \( g \) fixed, update \( q \):
   - (a) Apply NMF to numerically minimize
     \[
     LS_2(q) = \sum_{j\ell i} \left( x_{\ell i}(j) - \sum_k q_{ik} g_{k\ell}(j) \right)^2 + \sum_i \alpha \cdot \left( \sum_k q_{ik} \right)^2
     \]
     with the boundary condition \( \forall j, k: q_{jk} \geq 0 \).
   - (b) normalize \( q \) such that \( \forall i: \sum_k q_{ik} = 1 \).

Some of the things you should be able to explain

- Different types of LD and how they are covered in STRUCTURE
- Limitations in STRUCTURE
- alternative tools and what is different in them
- LEA:
  - why not assuming Hardy-Weinberg
  - ridge regression
  - convex optimization

74
10 The genetic footprints of selection: simulation and detection

We will now consider the effect of selection and adaptation on genealogies. We will discuss how these effects can be simulated, because

1. this is a way to specify the theoretical model and

2. if we know how to simulate data, we can apply ABC and similar methods for statistical inference of model parameters.

Possible scenarios for the case of positive selection (directional selection):

1. A beneficial mutation appears once, spreads in the population and will eventually be fixed
2. there is a balance between mutation and selection
3. selection pressure changes in time and a certain allele is favored for a while and increases in frequency during that time

Other forms of selection:

background selection, also called negative selection

balancing selection can lead to maintenance of two alleles over a long period of time

diversifying selection: new types appear by mutation and have an advantage until the reach a certain frequency

etc.

Basic model of positive selection: Each individual \( i \) in a population of size \( N \) has a fitness \( w_i \), which is the expected number of kids. The \( N \) surviving offspring of the next generation are sampled from the kids of all individuals. Thus, the expected number of surviving offspring of \( i \) is \( \frac{w_i}{\sum_{j=1}^{N} w_j} \).

Let’s assume a simple scenario: haploid population with one type \( A \) of fitness \( 1 + s \) and one type \( a \) of fitness 1.

Moran model

Assume a population of \( 2N \) gametes. An alternative to the Wright-Fisher model is the Model of Moran(1958): Each gamete has a rate of 1 to generate one offspring and replace one randomly chosen gamete. For \( N \to \infty \) and time scaled in units of \( N \) (not \( 2N! \)) generations, the genalogy of a sample from the Moran model converges to the standard Kingman coalescent. Add selection to Moran model:

Type \( A \) produces offspring at rate 1 and type \( a \) at rate \((1 - s)\). This approximates the diploid case with fitness 1 of \( AA \), \( 1 - s \) of \( Aa \), and \((1 - s)^2 \approx 1 - 2s \) of \( aa \). (Note that capital letter \( A \) does not indicate dominance.)

Transition rates of number of allele \( A \) gametes in Moran model with selection:

\[
i \to i + 1 \quad \text{at rate} \quad \frac{(2N - i) \cdot i}{2N} \\
i \to i - 1 \quad \text{at rate} \quad \frac{(2N - i) \cdot i}{2N} \cdot (1 - s)
\]

More facts about Moran model with selection:
**Fixation probability:** If we start with \(i\) gametes of type \(A\), the fixation probability of \(A\) is

\[
\frac{1 - (1 - s)^i}{1 - (1 - s)^{2N}} \approx \frac{1 - e^{-is}}{1 - e^{-2Ns}}
\]

**Fixation time:** Assume that type \(A\) starts with one gamete. Conditioned on the fixation of \(A\), the expectation value of the fixation time is in the limit of large populations is asymptotically

\[
\frac{2}{s} \log N
\]

generations.

For proofs see:

**References**


In mathematical population genetics two cases are considered:

**weak selection:** as \(N \to \infty\), \(s \to 0\) such that \(Ns \to \tilde{s} < \infty\).

**strong selection:** as \(N \to \infty\), \(s\) is stays constant, with the consequence that the fixation time of the advantageous allele is 0 on the time scale of \(N\) generations.

### 10.1 Ancestral Selection Graphs

**References**


**Ancestral Selection Graph (ASG)**

Weak selection: \(2Ns \to \tilde{s}\) as population size \(2N \to \infty\). Each pair of ancestral lineages coalesces at rate 1. At rate \(\theta/2\) lineage of type \(a\) mutates into \(A\) and vice versa. Each lineage \(x\) is hit by “arrow” at rate \(\tilde{s}\). Arrow was shot by random indivdual \(y\) from population. If (further in the past) \(x\) was of type \(a\) and \(y\) of type \(A\), replace (in future direction) \(x\) by type \(A\). To find out whether this applies, trace lineages back into past. At latest when all lineages are coalesced, types of all lineages are determined.

This happens almost surely after finite time because number \(j\) of lineages to trace back jumps to \(j + 1\) at rate \(\tilde{s} \cdot j\) only but jumps to \(j - 1\) at rate \(j \cdot (j - 1)/2\).

**ASG for frequency-dependent selection with advantage of rare alleles**
When lineage $x$ is hit by “replacement arrow” from $y$, it shoots a “check arrow” to some random individual $z$ from the population. It copies the type of $y$ if and only if the type of $z$ is different than that of $y$. Thus, lineages of $x$, $y$, and $z$ have to be traced back. But again all lineages will coalesce in finite time because rate of adding lineages is linear whereas rate of coalescence is quadratic in number of lineages. In structured population one can also assume that the arrows are shot locally to model that selection depends on local frequencies.

### 10.2 Simulating selective sweeps and other kinds of strong selection

![Frequency of advantageous allele](image.png)

In the case of strong selection, coalescent based simulation faces the problem that in time span of length 0 advantageous type becomes fixed, and backward in time all lineages would coalesce at that time. In case of the ancestral recombination graph (ARG) there is even no time for recombination. However, if we model a locus that is far from selected locus, recombination rate is also high and in mathematical models we could also let it go to $\infty$ such that lineages can escape the selective sweep. In the simulation programm MSMS, however, the approach is to first simulate the locus under selection for finite $N$, and then the ARG around (or next to) it conditioned on the frequency trajectory of the selected allele.

### References


Strategy: First simulate the site under selection forward in time with discrete generations and finite $N$. Then generate the ARG backwards in time conditioned on the simulated development of allele frequencies. Allows to specify when selection starts and when it ends (or some condition, e.g. fixation).
MSMS model for selected locus

Works for fitness function of haploids or diploids.

Selection can depend on deme.

Fitness of genotypes $aa$, $aA$ and $AA$ on deme $i$:

$$(1 + s_{aA}^a), (1 + s_{AA}^a), \text{ and } (1 + s_{AA}^A)$$

Also balancing selection possible by choosing $s_{aA}^a < s_{aA}^A > s_{AA}^A$

$m_{ij}$ : fraction of island $j$ immigrants on island $i$

$$m_{ii} := 1 - \sum_{j \neq i} m_{ij}.$$  

$x_i$ : relative frequency of $A$ on island $i$

$\mu$ : mutation rate $a \rightarrow A$

$\nu$ : mutation rate $A \rightarrow a$

$$\eta_i^A := \sum_j m_{ij} x_j \left(1 + (1 - x_j) s_{aA}^A + x_j s_{AA}^A\right)$$

$$\eta_i^a := \sum_j m_{ij} (1 - x_j) \left(1 + x_j s_{aA}^a + (1 - x_j) s_{AA}^a\right)$$

$$x_i' := \frac{(1 - \nu)\eta_i^A + \mu \eta_i^a}{\eta_i^A + \eta_i^a}$$

Then, the number of copies of $A$ on island $i$ in the next generation is drawn from binomial distribution with parameters $(2N_i, x'_i)$. For ARG backwards simulations, continuous time is assumed. For this, each generation from the forward simulation is replaced by suitable time span.

MSMS simulation strategy for ARG

Simulate migration, coalescence, mutation and recombination. As far as possible use that the time to the first event (back in time) of several possible events with exponential waiting time is also exponentially distributed with rate being the sum of the single rates. But take into account that rates vary in time due to population size changes and changes of allele frequencies at locus under selection. Lineages can coalesce only if they have the same type $A$ or $a$ at the selected locus.

E.g. if there are $k$ lineages of type $A$ on island $i$, the total coalescence rate of these lineages is

$$\frac{k \cdot (k - 1)}{4N_i x_i}$$
as long as type $A$ has frequency $x_i$ on island $i$.

Migration and Mutation rate must be corrected for allele frequencies simulated afore. If $m_{ij}$ is the fraction of island $i$ inhabitants that immigrated from island $j$, then the fraction of immigrants from $j$ of type $A$ is $x_j m_{ij}$. Thus, the fraction of immigrants among the type $A$ inhabitants of island $i$ is $x_j m_{ij} / x_i$.

Similarly, lineages of type $A$ are traced back to be mutated from lineages of type $a$ on island $i$ at rate $\mu \cdot (1 - x_i)/x_i$. 

78
Simulating the ARG, given the locus under selection

During the backwards simulation, all lineages have sequences with “active” and “inactive” sections.

Active means:
a mutation in such a region would lead to
a polymorphic site in the sampled sequences.

- If recombination happens, non-ancestral material is deactivated. If a region is active in only one
  lineage, it becomes inactive.
- When a recombination happens in an inactive range, its exact location is usually irrelevant.
- Exception: If the locus under selection is in the inactive region, it matters whether recombination
  happened left or right of it.

We must alway keep track of the type $a$ or $A$ of each lineage at the selected locus, even if this locus
is outside the range for which we simulate the ARG. In particular, when recombination leads to a split
of a lineage, one lineage keeps the locus under selection (which one is clear from the position of the
recombination point). The type of the other lineage is of type $A$ or $a$ with probabilities $x_i$ or $1 - x_i$,
respectively.

There have been plans to make it possible in msms to simulate quite generals scenarios with more than
one locus under selection but it is not clear whether development will go on, see https://github.com/delt0r/msms.

Some of the things you should be able to explain

- Moran model with selection
- Fixation probability and fixation time with selection
- mathematicians’ distiction between weak and strong selection
- Ancestral selection graph and its extension for frequency-dependent selection
- Simulation strategy in MSMS

11 Statistics for detecting genomic footprints of selection

We have already discussed one genetic signal of selection: $dN/dS$.

We will now discuss statistics to detect genomic signals of various kinds of selection processes. These
statistics are just examples; many more statistics can be found in the literature and in several software
packages.

11.1 Detecting selective sweeps

Kimura (1971) has shown for standard neutral model that the expected number of mutated sites with
frequency of derived allele in $[p, p + dp]$ is

$$
\phi_0(p)dp = \frac{\theta}{p}dp.
$$

Fay and Wu (2000) have generalized this to mutations neighboring a sweep with selection strength $s$,
recombination rate $r$ between the sites, initial frequency of $\varepsilon$, and $C := 1 - \varepsilon^{r/s}$. In this case, $\phi_0$ is
replaced by (approximately)

$$
\phi_1(p) = \begin{cases} 
\frac{\theta}{p} - \frac{\theta}{C} & \text{for } 0 < p < C \\
\frac{\theta}{C} & \text{for } 1 - C < p < 1 
\end{cases}
$$
Probability of finding $k$ derived alleles in sample of $n$:

$$P_{n,k} = \int_0^1 \binom{n}{k} p^k (1 - p)^{n-k} \phi(p) dp$$

**References**


Kim and Stephan (2002) propose composite-likelihood ratio statistic. Here, “composite” means that stochastic dependencies (linkage) among neutral sites are neglected, and just the product of the probabilities $P_{n,k}$ for all sites is used.

Nielsen *et al.* (2005) propose a variant of this, which

- is not restricted to one null model; instead average site-frequency spectrum of full chromosome is used.
- provides correction for ascertainment bias

$$L(\Theta) \propto \Pr(D_i | \Theta, A_i) = \frac{\Pr(D_i | \Theta) \cdot \Pr(A_i | D_i, \Theta)}{\Pr(A_i | \Theta)}$$

where $D_i$ is the data at SNP $i$, and $A_i$ is the condition why $i$ is considered.

Software: SweepFinder2 [http://degiorgiogroup.fau.edu/sf2.html](http://degiorgiogroup.fau.edu/sf2.html)

**References**


propose statistic $\omega$ based on LD (linkage disequilibrium) pattern.

Given two loci with alleles $A/a$ and $B/b$ with frequencies $\pi_A, \pi_B, \pi_a, \pi_b$ and frequency $\pi_{AB}$ of haplotype $AB$, one possible measure of LD is

$$r^2 = \frac{(\pi_{AB} - \pi_A \cdot \pi_B)^2}{\pi_A \cdot \pi_B \cdot \pi_a \cdot \pi_b}$$
Kim and Nielsen’s $\omega$

Given $S$ segregating sites, split them into the set $L$ of the first $\ell$ sites and the other $S - \ell$ sites $R$. Then compute

$$\omega_\ell = \frac{\left(\sum_{i,j \in L} r_{ij}^2 + \sum_{i,j \in R} r_{ij}^2\right) / \binom{\ell}{2} + \binom{S - \ell}{2}}{\left(\sum_{i \in L, j \in R} r_{ij}^2\right) / (\ell \cdot (S - \ell))}$$

and set

$$\omega = \max_\ell \omega_\ell.$$

To assess significance of any evidence for selection indicated by such statistics, we need to use a null model that accounts for population structure and demography.

XP-CLR

XP-CLR: cross-population composite-likelihood ratio test

Detects sweeps in one of two closely related species (or populations).

References


XP-CLR

Assume sweep at locus $A$ in population 1. Locus $B$ is linked to locus $A$.

$s$ strength of selection in sweep

$r$ recombination rate between the two loci

$p_2$ allele frequency at locus $B$ in population 2

$w$ parameters of demographic model such as split time, genetic drift rates...

$f(p_1|p_2, w, s, r)$ approximate probability density of allele frequency at locus $B$ in population 1, conditioned on $r$, $s$, $p_2$ and $w$, combining several theoretical results, e.g. by Durrett and Schweinsberg (2004)
**XP-CLR**

Data set consists of sites $i$ that are linked to selected site with $r_i$ and have allele frequency $p_{i,2}$ in population 2 and $m_i/n$ in population 1 (where $n$ is the sample size in population 1).

Composite likelihood approach: neglect linkage among sites $i$

\[
CL(r, w, s) = \prod_{i=1}^{k} \int_{0}^{1} f(p_{1,i} | p_{i,2}, w, s, r_i) \cdot \binom{n}{m_i} \cdot p_{1,i}^{m_i} \cdot (1 - p_{1,i})^{n - m_i} \, dp_{1,i}
\]

The statistic is then:

\[
2 \cdot \left( \max_{s, r, w} \log CL(r, w, s) - \max_{w} \log CL(r, w, 0) \right)
\]

**11.1.1 Stats for detecting incomplete sweeps**

Extended Haplotype Homozygosity

**References**


$EHH(x)$ Among all pairs of sampled sequences the fraction of those that are identical in the range from $x$ cM downstream to $x$ cM upstream of the candidate site.

$iHS$ for incomplete sweeps

**References**


Scale genomic location $x$ in units of $4N_e r$ (for autosomes), where $r$ is the recombination rate and use $EHH$ with linear interpolation between SNPs. Let $a$ and $b$ be the first points up- and downstream of the candidate site where $EHH(x) \leq 0.05$. Then define:

\[
iHH = \int_{a}^{b} EHH(x) \, dx
\]

Calculate $iHH_A$ and $iHH_D$ separately for ancestral and derived allele. Then define:

\[
uiHS = \ln \frac{iHH_A}{iHH_D} \quad \text{(unscaled iHS)}
\]

\[
iHS = \frac{uiHS - \mu_p}{\sigma_p}
\]

In

\[
iHS = \frac{uiHS - \mu_p}{\sigma_p}
\]

$\mu_p$ and $\sigma_p$ are mean and standard deviation of $uiHS$ estimated from SNPs in which the derived allele has the same distribution as in the candidate site.

Software: [http://hgdp.uchicago.edu/Software/](http://hgdp.uchicago.edu/Software/) or R package [rehh](http://hgdp.uchicago.edu/Software/)
idea of Single Density Score (SDS): if rare allele gets under recent positive selection, its tip branch lengths are shorter than those for ancestral allele.

Software: [https://github.com/yairf/SDS](https://github.com/yairf/SDS)

1. Assume there are \( n \) diploid individuals in the sample of unphased data.
2. “singleton” is a derived allele that appears in only one the \( 2n \) sequences of diploid individuals
3. for each diploid individual \( i \) we consider the two sites that are the nearest to the candidate in upstream and downstream direction, respectively, among all singletons that are heterozygous in \( i \). Let \( d_i \) be the distance between these two sites.
4. from the distances \( d_i \) of \( i \) with derived or ancestral alleles first estimate the average tip branch lengths \( \hat{t}_d \) and \( \hat{t}_a \) for both groups
5. 
\[
\text{SDS}^* = \log \frac{\hat{t}_d}{\hat{t}_a}
\]
6. SDS is normalized SDS* with \( \mu \) and \( \sigma \) estimated from SNPs of similar frequency as candidate site

estimating \( \hat{t}_d \) and \( \hat{t}_a \) from \( (d_i)_i \)

- Consider one individual \( i \), assume that the two tip branches leading to its alleles have lengths \( t_{i,1} \) and \( t_{i,2} \).
- let \( U \) and \( D \) be the distances upstream and downstream to the first singletons that are heterozygous in \( i \), such that \( d_i = U + D \).
- If we neglect recombination and assume a mutation rate \( \mu \), then \( U \) and \( D \) are independent and approximately exponentially distributed with rate \( (t_{i,1} + t_{i,2}) \cdot \mu \).
- Thus, conditioned on \( t_{i,1} + t_{i,2} \), \( d_i = U + D \) is approx. \( \Gamma \)-distributed with shape parameter 2 and rate parameter \( (t_{i,1} + t_{i,2}) \cdot \mu \).
- Also the distribution of \( t_{i,j} \) for all \( i \) with ancestral type at the candidate site and that for all \( i \) with the derived type are assumed to be \( \Gamma \) distributions.
- Field et al. found this fitting well with simulation studies
- \( \Gamma \) distribution densities are relatively convenient for likelihood optimization
- Using an empirical branch length distributions can, to some extent, account for sequencing errors

References


propose another statistic for detecting incomplete sweeps and compare it to \( iHS \) and \( nS_L \).
11.1.2 Soft Sweeps

References


Many sweeps detected in European *D. melanogaster* are due to out-of-Africa adaptations. In humans, population size and short time span make it improbable that out-of-Africa adaptations were due to new mutations.

If selection acts on standing variation, that is, the advantageous allele existed before selection began, the sweep signal (“soft sweep”) is less clear. Reason: several haplotypes that carry the advantageous allele and thus increase in frequency may differ in neighboring neutral SNPs.

Methods based on site-frequency spectra (like SweepFinder) or LD based statistics (like $\omega$) may be appropriate to detect sweeps only if they are hard.

Ferrer-Admetlla et al. (2014) propose a haplotype-based statistic $nS_L$

\[ nS_L := \ln \left( \frac{SL_A(k)}{SL_D(k)} \right) \]

where $SL_A(k)$ and $SL_D(k)$ are defined as:

\[ SL_A(k) = \frac{2 \sum_{i<j} L_{ij}(p_k) H_{ik} H_{jk}}{(n-1) \sum_i H_{ik} \sum_j H_{jk}} \]

\[ SL_D(k) = \frac{2 \sum_{i<j} L_{ij}(p_k) H_{ik} H_{jk}}{(n-1) \sum_i H_{ik} \sum_j H_{jk}} \]

Variant: replace $nS_L(k)$ by standardized version

\[ nS_L(k) = \frac{E(nS_L(k)) - nS_L(k)}{\sigma(nS_L(k))} \]

where $E$ and standard deviation $\sigma$ are conditioned on $\sum_i H_{ik}$, the number of sequences that have the derived allele at $k$. That is, estimate mean and sd from other loci with the same number of derived alleles in the sample.

11.1.3 Signals of sweeps and demography

Several studies compare different sweep statistics, for example:

References


compare $iHS$, XP-CLR, $nS_L$ and several other statistics for detecting sweeps in different demographic scenarios.
**Vatsiou et al. (2016)**

Scenarios of population structure/demography

- Four islands, migration between all
- Four islands, stepping-stone
- One population splits into two, later each of them splits into two, resulting in hierarchical island structure
- Stepping-stone with 52 populations and hard sweep in half of the populations of mutant that is detrimental in other half

In first three scenarios: hard or soft sweep in one of the four populations.

**Vatsiou et al. (2016)**

Strategies for setting thresholds ("p values" !?) for sweep signals:

**in main text:** 5% loci with highest values of the statistics.

*limitation:* this will always exist, also if there was no sweep signature by selection

**in online supplement:** use simulations of neutral loci according to same population structure/demography model to set thresholds

*limitation:* true population structure/demography usually unknown. Furthermore two different approaches are possible:

- threshold is value such that only 5% of the simulation show loci with such high (or higher) values
- threshold is value such that 5% of the loci from all simulation reach this (or higher) values. Such thresholds are *not* p values for the null hypothesis "everything neutral".

**Vatsiou et al. (2016)**

Main results:

- XL-PCR and hapFLK are best for performing soft sweeps
- all single statistics had problems when migration rates were higher or for weaker selection or incomplete sweeps
- improvements by combining statistics, e.g. XP-CLR with iHS or nSL.

**Problem:** When population demography is unknown, how can we decide which patterns are significant evidence of selective sweeps?

*naive* idea: demography is the same for all loci outlier must be under selection

*Bottlenecks can create outliers!* (and branch length distribution is long-tailed anyways)
Possible approach

1. Infer population structure and demography from genomic data of putatively neutral loci
2. Use $\omega$ and/or SweepFinder statistic to search for evidence of selection in candidate loci (or genomic scans)
3. Simulate many datasets according to inferred demographic model, each neutral and with same amount of data as in candidate loci (or genomic scan). Account for ascertainment (e.g. by rejection sampling).
4. For each simulated neutral dataset $i$ compute maximum value $s_i$ of statistic.
5. Choose a threshold $s$ for the statistic, such that only e.g. 5% of the $s_i$ are larger.
6. Consider only loci as significant if their statistic value exceeds threshold $s$.

References


propose and explore with simulated data the following procedure and apply it to *Drosophila melanogaster* data, where demography is known from previous studies:

1. Simulate loci according to known population demography with and without selection.
2. Use this simulated data to train a Support Vector Machine (SVM), which is a computational method for discriminant analysis (aka supervised learning). Input data are (slightly modified) $\omega$ and SweepFinder and other statistics based on combining the two, e.g. the distance of the positions where the two methods would locate the site under selection.
3. The trained SVM is then applied to discriminate between loci that have been affected by a selective sweep from neutral loci.

*Still a problem:* How to infer demography if we do not know which loci were really neutral?

Possible approach: Simultaneously infer population demography and fraction of loci affected by sweeps (and other kinds of selection).

11.2 Does the gene list make sense?

Once lists of genes that show evidence of selection have been identified, it is common practice to argue that the gene list makes sense by showing that certain GO categories are significantly overrepresented.

Pavlidis *et al.* (2012) explain why this may not make much sense.

References


Pavlidis *et al.* (2012) simulate completely neutral sequences mimicking the structure of *D. melanogaster* X chromosomes and scanned for sweeps.

False positives for sweeps tended to be clustered on the chromosomes.

As genes of related function can also be clustered on the chromosome, some GO categories were significantly overrepresented.
11.3 Balancing selection

Genetic signatures of balancing selection:
- enrichment of intermediate gene frequencies
- trans-specific polymorphisms
- increased frequency of polymorphic sites

References


- Composite-likelihood ratio test for balancing selection
- Based on modelling the effect on linked neutral loci
- Software BALLET (BALancing selection LikElihood Test)
- Define and examine two different statistics $T_1$ and $T_2$
- Apply method to human data and detect previously found loci but also new ones

$S$ : locus under strong balancing selection with two alleles $A_1$, $A_2$ with maintained frequencies $x$ and $1-x$.

$\rho_i = 2N r_i$, where $N$ is the population size and $r_i$ is the per-generation recombination rate btw. $S$ and locus $i$.

data : $n$ genomes from population, 1 from outgroup (e.g. chimp for humans)

$C$ : estimated genome-wide divergence time btw. in- and outgroup

$L_n(x, \rho_i)$ expectation value for total length of all branches of an ingroup genealogy for samples at site $i$, given $n$, $x$ and $\rho$.

$H_n(x, \rho_i)$ Expected time since the root of the ingroup genealogy at site $i$, given $n$, $x$ and $\rho$.

The probability that a site that is segregating is polymorphic in within the ingroup sample can be approximated by

$$ p_{n, \rho, x} \approx \frac{L_n(x, \rho)}{2C - H_n(x, \rho) + L_n(x, \rho)} $$

$H_n(x, \rho)$ and $L_n(x, \rho)$ can be computed by solving linear equation systems with variables $L_{k,n-k}$ and $H_{k,n-k}$, which are (for fixed $x$ and $\rho$) the expected total ingroup genealogy length and height given a sample with $k A_1$-linked and $n-k A_2$-linkes lineages.

With the total rate

$$ \lambda_{k,n-k} = \frac{(\frac{1}{x})}{x} + \frac{\binom{n}{2} - (\theta_2 + \rho_i) \cdot (1-x)}{x} + \frac{(n-k) \cdot (\theta_1 + \rho_i (1-x))}{(1-x)} $$

we obtain, for example:

$$ L_{k,n-k} = \frac{n}{\lambda_{k,n-k}} + \frac{\binom{k}{2} \cdot L_{k-1,n-k}}{x \cdot \lambda_{k,n-k}} + \frac{\binom{n-k}{2} \cdot L_{k,n-k-1}}{(1-x) \cdot \lambda_{k,n-k}} $$

$$ + \frac{k \cdot (\theta_2 + \rho_i \cdot x) \cdot (1-x) \cdot L_{k-1,n-k+1}}{x \cdot \lambda_{k,n-k}} $$

$$ + \frac{(n-k) \cdot (\theta_1 + \rho_i \cdot (1-x)) \cdot x \cdot L_{k+1,n-k-1}}{(1-x) \cdot \lambda_{k,n-k}} $$
After numerically solving the equations systems for $L_n$ and $H_n$ and computing $p_{n,\rho,x}$ (approximately), the composite likelihood for all can be computed:

$$
\mathcal{L}_1 = \max_x \prod_{i \in M} \left( 1 - p_{n_i,\rho_i,x} \right) \cdot \prod_{i \in U} p_{n_i,\rho_i,x},
$$

where $M$ is the set of segregating sites that are monomorphic within the ingroup and $U$ is the set of sites that are polymorphic in the ingroup.

For the neutral null model, we set

$$
\mathcal{L}_0 = \prod_{i \in M} (1 - \tilde{p}_{n_i}) \cdot \prod_{i \in U} \tilde{p}_{n_i},
$$

where $\tilde{p}_{n_i}$ is the proportion of loci that are in $U$ among all segregating sites with the same sample size $n_i$.

$$
T_1 := 2 \cdot \ln(\mathcal{L}_1 / \mathcal{L}_0)
$$

The statistic $T_2$ is a refinement of $T_1$. For $T_2$ it is not only considered whether a site is polymorphic in the ingroup, but also how many of the sampled sequences show the derived allele.

In simulations $T_2$ works better than $T_1$ but $T_1$ may be advantageous when pooled sequencing is used.

Violations of Hardy-Weinberg equilibrium could also indicate balancing selection, but DeGiorgio et al. propose to filter out loci with strong violations of Hardy-Weinberg equilibrium because this may indicate mistakes in bioinformatic preprocessing (alignment/mapping/assembly).

Some of the things you should be able to explain

- Different types of sweeps
- Several statistics to detect various kinds of selection and the ideas behind these statistics
- problem to distinguish genomic footprints of selection from those of demography and why also bottlenecks can create outliers
- why overrepresentation analysis of GO can be misleading

12 Phasing genotypes and other applications of Li&Stephens’ PAC approach

12.1 Li&Stephens’ PAC approach

12.1.1 Estimating LD and recombination hotspots

Problems of models to estimate local recombination rates:

- **LAMARC** etc. (ARG-based): not feasible for larger parts of the genome
- **Summary-statistics-based**: lose too much information

**some composite-likelihood methods**: Hudson (2001), Fearnhead, Donnelly (2002), McVean (2002) assume fixed recombination rate along the genome
References


Aim: Approximate the joint likelihood surface for the recombination rate and the mutation rate.

Model assumption: panmictic population, constant size $N$

$\theta = 4N\mu$

$\mu$ Mutation rate per generation and chromosome

$\rho = 4Nr$

$r$ Recombination rate per generation and chromosome

Two different mutation modes:

- infinite-sites model
- at each site finitely many types with transition matrix $P_{\alpha\beta}$

$\mathcal{G}$ set of all ancestral histories (containing all mutations) that are consistent with the data $D$, such that $\forall G \in \mathcal{G} \Pr(D|G) = 1$

Importance Sampling: If $G_1, \ldots, G_m$ are sampled independently according to some density $q$ with $\mathcal{G} \subseteq \text{supp}(q)$, then

$$L(\rho, \theta) \approx \int_{\mathcal{G}} P(G|\theta, \rho) dG \approx \frac{1}{M} \sum_{i=1}^{M} \frac{P(G_i|\rho, \theta)}{q(G_i)}$$

What is a good proposal distribution $q$?


$H$ set of already sampled haplotypes

$\alpha$ potential type of $j + 1$st sampled haplotype

$p(\alpha|H)$ will, like in Stephens, Donnelly (2000), be approximated to be used in importance sampling scheme

important: To use approximation $q$ in importance sampling it must be possible to sample according to $q(\cdot|H)$ and to compute $q(\alpha|H)$ for given $\alpha$.

We specify $q(\alpha|H)$ by showing how to sample from it:

initialization: Let $x_1, \ldots, x_s$ be the segregating sites in the $j$ chromosomes in $H$.

recombination: For $i = 1, \ldots, s - 1$ there is a recombination event in the middle between $x_i$ and $x_{i+1}$ in $\alpha$ with probability

$$a_i := \frac{(x_{i+1} - x_i)\rho}{(x_{i+1} - x_i)\rho + j}.$$ 

Let $k$ be the number of recombination and $r = \{r_1, \ldots, r_{k+1}\}$ the resulting fragments.

imputation: For nonancestral sites in $H$ impute types according to their frequency at that site in $H$.

mutations: Each $r_j$ is simulated (independently of any $r_j$) according to Stephens, Donnelly’s (2000) approximation $\hat{\pi}$ for sequence data.
To compute \( q(\alpha|H) \) for the correction in the Importance Sampling formula, we need to sum over all possible combinations of recombinations, imputations, and mutations that would lead to \( \alpha \).

This is done by dynamic programming: compute iteratively

\[
q_i(\alpha) \text{ probability that simulated type will coincide with } \alpha \text{ at first } i \text{ loci.}
\]

\[
q_i(\alpha|\ell, t) \text{ as above, but conditioned that } i\text{th locus is a mutated copy of the } i\text{th locus in } H_\ell \text{ with Poisson}(\theta t) \text{ mutations.}
\]

For this, the following approximation is used:

\[
q_i(\alpha) \approx \sum_{m=1}^{k} \sum_{b=1}^{j} w_m q_i(\alpha|b, t_m/j)/j,
\]

where \( w_1, \ldots, w_k \) and \( t_1, \ldots, t_k \) are the weights and points from the Gauß quadrature \( \int_0^{\infty} e^{-t} f(t) dt \approx \sum_{m=1}^{k} w_m f(t_m) \).

To compute \( q_i(\alpha|\ell, t) \) from previously computed \( q_{i-1}(\alpha|\ell, t) \) and \( q_{i-1}(\alpha) \) first compute the transition matrix for time \( t \):

\[
Q(t) = \exp \left( \theta t (P - I)/s \right),
\]

where \( P \) as before is the transition matrix given that a mutation happens.

If \( H_\ell \) is ancestral at locus \( i \) and has type \( \beta \) there, set

\[
R := Q_{\beta, \alpha_i}(t),
\]

and otherwise

\[
R := (\pi_i Q(t))_{\alpha_i},
\]

where \( \pi_i \) is the vector of proportions of types in \( H \) at position \( i \). Then:

\[
q_i(\alpha|\ell, t) = [(1 - a_{i-1}) \cdot q_{i-1}(\alpha|\ell, t) + a_{i-1} \cdot q_{i-1}(\alpha)] \cdot R.
\]

Using these regression formulas in a dynamic-programming approach, \( q(\alpha|H) \) can be computed and used to compute the proposal probability.

In the Importance Sampling step, the proposal probability is compared to the original ARG probability (ARG=ancestral recombination graph) and corrected accordingly to approximate the likelihood function for \( \rho \) and \( \theta \) in the ARG model.

Li and Stephens’ PAC approach, in contrast, replace the ARG model by a simpler model.

**Li & Stephens’ approach to analyze patterns of LD**

**References**


ideas:

- relate LD directly to underlying recombination process
- Sometimes, block-like LD structure is reported. True or artifact of LD mapping? Allow for both.
- consider all loci simultaneously, not pairwise
- should be computationally tractable even for complete chromosomes
Li & Stephens’ PAC approach

$h_1, h_2, \ldots, h_n$: haplotypes sampled from panmictic population with constant size and random mating

$\rho$: recombination parameter (may be a vector if recombination rate varies within the region of interest)

Product of Approximate Conditionals (PAC)

$$\text{Pr}(h_1, \ldots, h_n | \rho) = \text{Pr}(h_1) \cdot \text{Pr}(h_2 | h_1, \rho) \cdot \ldots \cdot \text{Pr}(h_n | h_1, \ldots, h_{n-1}, \rho)$$

approximate $\text{Pr}(h_k | h_1, \ldots, h_{k-1}, \rho)$ by simpler $q(h_k | h_1, \ldots, h_{k-1}, \rho)$.

Properties of $\text{Pr}(h_k | h_1, \ldots, h_{k-1}, \rho)$

1. $h_k$ is more likely to match another haplotype if the latter is frequent among $h_1, h_2, \ldots, h_{k-1}$
2. the probability of seeing a novel haplotype decreases as $k$ increases
3. the probability of seeing a novel haplotype increases with $\theta = 4N_e\mu$.
4. if a new haplotype does not exactly match any previous one, it will differ from one of those only by a small number of mutations.
5. effect of recombination: the next haplotype will be composed by segments which are similar to segments in previously sampled haplotypes. These segments tend to be longer if recombination rates are low.

Assume the sampled haplotypes $h_1, h_2, \ldots, h_n$ are typed at $S$ biallelic loci (e.g. SNPs).

$$q(h_1) = \left( \frac{1}{2} \right)^S$$

For the definition of $q(h_{k+1} | h_1, h_2, \ldots, h_k)$ let $X_i := j$ if at the $i$-th locus, the closest relative of $h_{k+1}$ among $h_1, \ldots, h_k$ is $h_j$.

$d_i$: distance between loci $i$ and $i + 1$

c_i: recombination rate between loci $i$ and $i + 1$ per site and per generation

$$\rho_i = 4N_e c_i$$

The simplifying assumption is then that $X_1, X_2, \ldots, X_S$ is a Markov chain on $\{1, \ldots, k\}$ with $\text{Pr}(X_1 = j) = 1/k$ and

$$\text{Pr}(X_{i+1} = j | X_i = \ell) = \begin{cases} (1 - e^{-\rho_i d_i / k})/k & \text{if } j \neq \ell \\ e^{-\rho_i d_i / k} + (1 - e^{-\rho_i d_i / k})/k & \text{if } j = \ell \end{cases}$$

Mutations

For SNP data we assume that each locus is hit by one mutation, such that

$$\tilde{\theta} := 1 \left/ \sum_{m=1}^{n-1} \frac{1}{m} \right.$$ is assumed to be the corrected rate of mutations per SNP site. Note that this does not exclude double hits (just some bias if double hits are frequent.)

Then, with probability $\frac{k}{k+\tilde{\theta}}$ the copy has the same type as the original

and with probability $\frac{\tilde{\theta}}{(k+\tilde{\theta})}$ the haplotype has the other of the two possible alleles.

Compute $q(h_{k+1} | h_1, \ldots, h_k)$ by HMM forward algo:

$h_{k+1, \leq j} := (h_{k+1,1}, \ldots, h_{k+1,j}) := $ types of the first $j$ sites in $h_{k+1}$
\( \alpha_j(x) := \Pr(h_{k+1,j}, X_j = x|h_1, \ldots, h_k) \)

(note that with mutations any \( X_1, \ldots, X_S \) can emit \( h_k \))

Then,

\[ q(h_{k+1}|h_1, \ldots, h_k) = \sum_{x=1}^{k} \alpha_S(x). \]

“dynamic programming”: we can compute all \( \alpha_j(x) \) by the recursion

\[
\alpha_{j+1}(x) = \Pr(h_{k+1,j+1}|X_{j+1} = x, h_1, \ldots, h_k) \cdot \sum_{x'=1}^{k} \alpha_j(x') \cdot \Pr(X_{j+1} = x|X_j = x')
\]

\[
= \Pr(h_{k+1,j+1}|X_{j+1} = x, h_{x,j+1}) \cdot \left( e^{-\rho_j d_j/k} \cdot \alpha_j(x) + \left(1 - e^{-\rho_j d_j/k}\right) \cdot \frac{1}{k} \sum_{x'=1}^{k} \alpha_j(x') \right)
\]

Remember the usual HMM algorithms!

**HMM forward algorithm**

\[ f_i(x) = \Pr(S_1 = s_1, S_2 = s_2, \ldots, S_i = s_i, X_i = x) \]

\[
\begin{align*}
S_1 & S_2 S_3 S_4 S_5 \\
\emptyset & \emptyset \emptyset \emptyset \emptyset \emptyset \\
\emptyset & \emptyset \emptyset \emptyset \emptyset \emptyset \\
\emptyset & \emptyset \emptyset \emptyset \emptyset \emptyset \\
\emptyset & \emptyset \emptyset \emptyset \emptyset \emptyset \\
\emptyset & \emptyset \emptyset \emptyset \emptyset \emptyset \\
\end{align*}
\]

\[ f_i(x) = \sum_{y \in \mathcal{M}} f_{i-1}(y) \cdot P_{y \rightarrow x} \cdot e_x(s_i) \]

\[ \Pr(S_1 = s_1, S_2 = s_2, \ldots, S_n = s_n) = \sum_{x \in \mathcal{M}} f_n(x) \]

**Li & Stephens’ bias correction**

Simulations show that estimations of \( \rho \) based on \( q \) are biased.

For bias-correction replace \( \rho_j \) in the computation of \( \Pr(X_{j+1} = x'|X_j = x) \) by

\[ \rho_j \cdot e^{a + b \log_{10} \rho_j}, \]

where \( a \) and \( b \) are fitted to simulated data, taking the numbers of haplotypes and segregating sites into account.

Models for \( \rho \) considered by Li and Stephens

1. constant \( \rho \)
2. single-hotspot model
3. all recombination rates \( \rho_1, \rho_2, \ldots, \rho_{S-1} \) may differ

Software by Matthew Stephens using PAC: Hotspotter, PHASE

**References**

12.1.2 Population splitting and recombination

References


- two populations split $G$ generations ago, $F = G/(2N)$.
- no ongoing geneflow
- for simplicity: assume that both populations and the ancestral population have size $N$
- Copying occurs in daughter population ($S = d$) and in ancestral population ($S = a$)

Again, the PAC approach is used and we have to approximate the probability of a haplotype $h_{k_1+k_2+1}$ given already sampled haplotype $h_1, \ldots, h_{k_1+k_2}$, of which $k_1$ were sampled on island 1 and $k_2$ on island 2.

Let $z_i \in \{1, 2\}$ indicate the island where $h_i$ was sampled, $z_* := z_{k_1+k_2+1}$, and $X_\ell$ indicates the $h_i$ that is the closest relative to $h_{k_1+k_2+1}$ at site $\ell$.

What we need to specify as model assumptions:
1. Probability of hidden copying states ($S_\ell, X_\ell$) at a single site $\ell$.
2. Probability of new allelic state conditioned on the state of the copied allele and the level $S_\ell$.
3. Transition probabilities between the hidden copying state at adjacent states (in case of linked loci).

**Point 1:** $\Pr(X_\ell = i|S_\ell = d)$, unlinked case

In the case of unlinked sites, we obtain

$$
\Pr(X_\ell = i|S_\ell = d) = \begin{cases} 
\frac{1}{k_*} & \text{if } z_* = z_i \\
0 & \text{else}
\end{cases}
$$

$$
\Pr(X_\ell = i|S_\ell = a) = \mathbb{E}\left( \frac{J_{z_i}}{J_1 + J_2} \right) \cdot \frac{1}{k_*},
$$

Where $k_*$ is the no. of lineages sampled from pop. $z_*$ so far and $J_i$ is the number of ancestral lineages that enter the ancestral pop. from pop. $i$. To compute the expectation first compute for all $j_i < k_i$ the probabilities that $k_i$ lineages coalesce down to $j_i$ lineages in $G$ generations. These values are also needed to compute $\Pr(S_\ell = d)$.

**Point 2:** Mutation probability; unlinked case

Simplification: For time $T_{coal}$ of coalescence use expectation

$$
t_s = \mathbb{E}(T_{coal}|S, k_1, k_2, F)
$$

Then:

$$
u(h_{k_1+k_2+1}|h_i, s) = \Pr(h_{k_1+k_2+1}|S_\ell = s, X_\ell = i, k_1, k_2, F) = \begin{cases} 
1 - e^{-\theta t_s} & \text{if } h_{k_1+k_2+1} \neq h_i \\
e^{-\theta t_s} & \text{if } h_{k_1+k_2+1} = h_i
\end{cases}
$$

where $\theta$ is corrected for using only polymorphic sites as in Li&Stephens.

Thus, we approximate $\Pr(h_{k_1+k_2+1}|h_1, \ldots, h_{k_1+k_2})$ by

$$
\sum_{s \in \{a, d\}} p(S = s) \cdot \sum_{i=1}^{k_1+k_2} u(h_{k_1+k_2+1}|h_i, s) \cdot p(X = i|S = s)
$$

93
Point 3: now for the case of (loosely) linked loci

- Now \((S_1, X_1), \ldots, (S_L, X_L)\) are not independent.
- Simplify applying Markov model, such that HMM algorithms are applicable
- Computing transition probabilities

\[
p(S_{\ell+1} = s', X_{\ell+1} = i' | S_\ell = s, X_\ell = i)
= p(S_{\ell+1} = s' | S_\ell = s) \cdot p(X_{\ell+1} = i' | S_{\ell+1} = s') + \delta_{ii'} \cdot \delta_{ss'} \cdot p(NR | S_\ell),
\]

where \(NR\) stands for “no recombination” is tricky, several simplifying approximation are applied, e.g.:
- if \(A\) is the event that a recombination happens on the new lineage in the daughter population, then

\[
p(S_{\ell+1} = d | S_\ell = a) = p(A) \cdot p(S = d | A)
\approx (1 - e^{-\mu F}) \cdot p(S = d)
\]

Simulation study
- works well in case of unlinked loci
- estimates of \(F\) biased for version with linked loci
- not well understood where this bias comes from, but suggest a bias correction

- Discuss how method could be extended to models with gene flow

12.1.3 Diversifying selection and recombination

References


Apply Bayesian variant of PAC to infer from population genetic data which regions are under diversifying selection and which are under purifying selection.

\(\omega = d_N/d_S\) fraction of rates of nonsynonymous vs. synonymous mutations
diversifying selection corresponds to large \(\omega\) and

purifying selection to small \(\omega\).

Software: omegaMap [http://www.danielwilson.me.uk/omegaMap.html](http://www.danielwilson.me.uk/omegaMap.html)

**NY98 Codon mutation model**

Nielsen and Yang (1998)

Mutation rate \(q_{ij} = \pi_j \cdot \mu_{ij}\), where \(i\) and \(j\) are codons, \(i \neq j\) or one of then is an insertion/deletion (indel), \(\pi_j\) is the frequency of \(j\) and

\[
\mu_{ij} = \begin{cases} 
1 & \text{for synonymous transversion} \\
\kappa & \text{for synonymous transition} \\
\omega & \text{for nonsynonymous transversion} \\
\omega\kappa & \text{for nonsynonymous transition} \\
\omega\phi & \text{if exactly one of } i \text{ and } j \text{ is an indel} \\
0 & \text{otherwise}
\end{cases}
\]

(original NY98 is without indels)

Model for \(\omega\) along the gene:

There are \(B\) transition points \(s_1, \ldots, s_B\), such that \(\forall j : \omega\) is constantly \(\omega_j\) between \(s_j\) and \(s_{j+1}\).
\( p_\omega \) Probability of transition point between two codons.

\( \omega_j \) are independent of each other and have prior \( \exp(\lambda) \)

Similar model for change of recombination rate \( \rho \); independent of \( \omega \) configuration.

\( H \) haplotypes sampled from population

\( \Theta \) model parameters, including all \( \omega_j \) and \( \rho_j \) and change points.

**MCMC** sample parameter values according to

\[ P(\Theta|H) \propto P(H|\Theta) \cdot P(\Theta) \]

**PAC** with HMM forward algorithm is applied to approximate \( P(H|\Theta) \) via PAC approximations of

\[ p(H_{k+1}|H_1, H_2, \ldots, H_k, \Theta) \]

**MCMC moves**

To propose e.g. \( \mu' \) as a replacement of current \( \mu \), choose \( U \sim \text{unif}(-1,1) \), and set \( \mu' = \mu \exp(U) \).

Accept or reject with MH step.

Same for \( \kappa, \omega_j, \rho_j \).

MCMC step to shift block change point.

Reversible Jump steps to update blocks:

- split block
- merge block

\( \lambda, \phi, p_\omega, p_\rho \) are specified by user to specify prior.

**Application example**

79 alleles of porB locus of *Neisseria meningitidis*

permutation test shows significant correlation of LD and distance between sites. ⇒ Phylogenetic methods not appropriate.

Found four sections in the gene where high \( \omega \) values are probable, indicating diversifying selection, whereas almost everywhere else, \( \omega < 1 \), indicating purifying selection.

Indeed, regions with large \( \omega \) are loops exposed to immune system of host, such that diversifying selection is plausible, and other regions form beta sheet barrel, which explains functional constraints. (nice picture in paper!)

**Model without recombination** leads to different results, but

**Model Criticism** via **posterior predictive \( P \)-value** shows that model without recombination fits the data poorly. This means, if \( D \) is some statistic of the data and \( D_H \)' is the statistic for a dataset \( H' \) simulated under the PAC model used for inference, then the **posterior predictive \( P \)-value** is:

\[ p = \int P(D_{H'} \geq D_H|\Theta, H)P(\Theta|H)d\Theta \approx \frac{1}{M} \sum_{i=1}^{M} I(D_{H'_i} \geq D_H) \]

Wilson and McVean perform simulation studies for several conditions to assess how well their method works.

This is very important for heuristic approaches like PAC because it is otherwise not clear how accurate these methods are even if sampling from some approximate posterior approximate confidence intervals are computed.
Some of what you should be able to explain

- Basic approach of Li&Stephen’s PAC
- Simplifying assumptions in PAC
- How PAC fits into HMM methodology
- How PAC can be applied to infer
  - local recombination rates
  - population demography
  - sections in genes under different kinds of selection

12.1.4 Excursus: Stephens and Donnelly’s Importance Sampling

References


improved Griffiths und Tavaré’s Importance sampling scheme for the case of the classical (unstructured) coalescent.

A history $\mathcal{H}$ is a sequence $(H_{-n}, H_{-(m-1)}, \ldots, H_0)$, where $H_{-i}$ is the unordered list of types of the ancestral lineages, $i$ events (mutations and coalescent events) before present. Thus,

- $H_{i-1} = H_i - \alpha + \beta$ stands for a mutation from $\alpha$ to $\beta$ (back into past; note that $i < 0$), and
- $H_{i-1} = H_i - \alpha$ for a coalescence of two lineages of type $\alpha$.
- $P_{\alpha\beta}$ probability that an $\alpha$ that is hit by a mutation becomes a $\beta$.
- $n_\alpha$ number of lineages in $H_{i-1}$ of type $\alpha$.

$$n = \sum_\alpha n_\alpha,$$

$$\Pr(H_i \mid H_{i-1}) = \begin{cases} \frac{n_\alpha \cdot \theta^i}{n^{i+1}} P_{\alpha\beta} & \text{if } H_i = H_{i-1} - \alpha + \beta \\ \frac{n_\alpha}{n^{i+1}} & \text{if } H_i = H_{i-1} + \alpha \\ 0 & \text{otherwise} \end{cases}$$

$\pi_\theta(.)$: distribution of genotype vector $A_n$ in a sample of size $n$. Note that $A_n$ is an ordered list.

$$\pi_\theta(A_n \mid H) = \pi_\theta(A_n \mid H_0) = \begin{cases} (\prod_\alpha n_\alpha!) / n! & \text{if } H_0 \text{ compatible with } A_n \\ 0 & \text{otherwise} \end{cases}$$

If histories $\mathcal{H}^{(1)}, \mathcal{H}^{(2)}, \ldots, \mathcal{H}^{(M)}$ are generated independently according to the proposal distribution $Q_{\theta_0}(.)$, the importance sampling formula implies:

$$L(\theta) \approx \frac{1}{M} \sum_{i=1}^{M} \pi_\theta(A_n \mid \mathcal{H}^{(i)}) \cdot \frac{P_\theta(\mathcal{H}^{(i)})}{Q_{\theta_0}(\mathcal{H}^{(i)})}$$
Theorem 3

Let $q_{\theta} \{ H_{i-1} \mid H_{i} \}$ be the type of lineage $H_{i}$ and $q_{\theta}(H_{i-1} \mid H_{i}) \propto p_{\theta}(H_{i} \mid H_{i-1})$.

Let $\mathcal{M}$ be the class of proposal distributions, for which $H_{i-1}, H_{i-2}, \ldots$ is Markovian with start in $H_{0}$ and

\[
\text{supp}(q_{\theta}(\cdot \mid H_{i})) := \{ H_{i-1} : q_{\theta}(H_{i-1} \mid H_{i}) > 0 \} = \{ H_{i-1} : p_{\theta}(H_{i} \mid H_{i-1}) > 0 \}.
\]

Optimal would be $Q_{\theta}(H) = P_{\theta}(H \mid A_{n})$, because

\[
\frac{\pi_{\theta}(A_{n} \mid H) \cdot P_{\theta}(H)}{Q_{\theta}(H)} = \frac{P_{\theta}(H \cap A_{n})}{P_{\theta}(H \mid A_{n})} = \pi_{\theta}(A_{n}) = L(\theta)
\]

\[\text{Theorem 3} \]

Let $\pi_{\theta}(\alpha \mid A_{n}) = \frac{\pi_{\theta}(\alpha)}{\pi_{\theta}(A_{n})}$ be the conditioned probability that the $n + 1$-st allele sampled from the population is of type $\alpha$, given that the first $n$ types are given by $A_{n}$. The optimal proposal distribution $Q_{\theta}^{*}$ belongs to $\mathcal{M}$ and is defined by

\[
q_{\theta}^{*}(H_{i-1} \mid H_{i}) = \begin{cases} 
\frac{\theta \cdot n_{\alpha}}{n \alpha} \pi_{\theta}(H_{i-1}, \beta) \pi_{\theta}(\alpha, H_{i-1}) P_{\beta \alpha} & \text{für } H_{i-1} = H_{i} - \alpha + \beta \\
\frac{n_{\alpha} \cdot (n_{\alpha} - 1)}{n \alpha \pi(\beta, H_{i-1})} & \text{für } H_{i-1} = H_{i} - \alpha
\end{cases}
\]

\[\text{Proof}\]

Consider the case $H_{i-1} = H_{i} - \alpha + \beta$

Let $a_{k}(t)$ be the type of lineage $k$ at time $t$. Assume $\delta > 0$ and let $Y_{m}$ be the event that in the last $\delta$ time units a mutation from $a_{k}(t - \delta) = \beta$ to $a_{k}(t) = \alpha$ occurred.

We obtain:

\[
\Pr\{Y_{m} \cap A_{k}(t - \delta) = (\alpha_{1}, \ldots, \alpha_{k-1}, \beta) \mid A_{k}(t) = (\alpha_{1}, \ldots, \alpha_{k-1}, \alpha)\} = \frac{\pi(\alpha_{1}, \ldots, \alpha_{k-1}, \beta) \cdot \delta \cdot \theta \cdot P_{\beta \alpha} / 2}{\pi(\alpha_{1}, \ldots, \alpha_{k-1}, \alpha)} + o(\delta)
\]

\[
= \delta \cdot \theta \cdot \pi(\beta, A_{k} - \alpha) / 2 \pi(\alpha, A_{k} - \alpha) \cdot P_{\beta \alpha} + o(\delta)
\]

This implies the result if we let $\delta$ go to 0, multiply by $n_{\alpha}$ (as instead of $\alpha_{k}$ any other $\alpha$ could be affected, and $H_{i}$ is unordered) and divide by the total rate.

The proof for $H_{i-1} = H_{i} - \alpha$ is analogous.

\[\square\]

\[\text{But}\]

In general, $\pi(\alpha \mid A_{n})$ are hard to compute and we cannot use $Q_{\theta}^{*}$.

\[\text{Ansatz}\]

If $\pi(\alpha \mid A_{n})$ cannot be calculated, approximate it and use the approximations in the formulas in the theorem.

\[\text{Definition 1}\]

\[
\tilde{\pi}(\beta \mid A_{n}) := \sum_{\alpha \in E} \sum_{m=0}^{\infty} \frac{n_{\alpha}}{n} \left( \frac{\theta}{n + \theta} \right)^{m} \cdot \frac{n}{n + \theta} (P^{m})_{\alpha \beta}.
\]

This probability distribution can be approximated as follows: Choose a purely randomly individual from $A_{n}$ and mutate it according to $P$ geometrically often with parameter $\frac{\theta}{n + \theta}$.  

97
properties of \( \hat{\pi} \):

(a) For parent-independent mutation: \( \hat{\pi}(\cdot \mid A_n) = \pi(\cdot \mid A_n) \).

(b) For reversible \( P \) with \( n = 1 \): \( \hat{\pi}(\cdot \mid A_n) = \pi(\cdot \mid A_n) \).

(c) The distribution \( \hat{\pi}(\cdot \mid A_n) \) fulfills

\[
\hat{\pi}(\beta \mid A_n) = \sum_{\alpha} \frac{n_{\alpha}}{n} M^{(n)}_{\alpha\beta} \quad (*)
\]

for suitable \( M^{(n)} \). Thus, it can be simulated by drawing a random lineage and draw the type according to a distribution that depends only on \( n \) and on the type of the drawn lineage. (In the case of \( \hat{\pi} \) holds \( M^{(n)} = (1 - \lambda_n)(I - \lambda_n P)^{-1} \) with \( \lambda_n = \frac{\theta}{n+\theta} \).)

more properties of \( \hat{\pi} \):

(d) \( \hat{\pi} \) is the only distribution that fulfills (\( \ast \)) and (b) and

\[
\hat{\pi}(\beta \mid A_n) = \sum_{\alpha} \hat{\pi}(\alpha \mid A_n) \cdot \hat{\pi}(\beta \mid (A_n, \alpha)) \quad (**)\]

This means: Given the first \( n \) sampled alleles, the \( n + 1 \)st has the same distribution as the \( n + 2 \)nd.

(e) \( \hat{\pi}(\cdot \mid A_n) \) is the stationary distribution of a Markov chain with transition matrix

\[
T_{\alpha\beta} = \frac{\theta}{n+\theta} P_{\alpha\beta} + \frac{n_{\alpha}}{n+\theta}
\]

Proofs

(a) For parent-independent mutation \( P_{\alpha\beta} = P_\beta \) holds \( P = P^m \) and thus:

\[
\pi(\beta \mid A_n) = \frac{n_\beta + \theta P_\beta}{n + \theta} = \hat{\pi}(\beta \mid A_n)
\]

(b) Let \( X \) and \( Y \) be the types of the leaves, \( R \) the type of the root, \( m_1 \) the number of mutations between \( R \) und \( X \) and \( m_2 \) that of the mutation between \( R \) and \( Y \). Then:

\[
\Pr(Y = \beta \mid R = \gamma) = (P^{m_2})_{\gamma\beta} \\
\Pr(R = \beta \mid X = \alpha) = (P^{m_1})_{\alpha\beta} \\
\Pr(Y = \beta \mid X = \alpha) = (P^{m_1 + m_2})_{\alpha\beta}
\]

The total number of mutations between \( X \) and \( Y \) is geometrically distributed with parameter \( \frac{\theta}{n+\theta} \)

(e)

\[
\hat{\pi}(\beta \mid A_n) = \sum_{\alpha} \sum_{m=0}^{\infty} \frac{n_{\alpha}}{n} \left( \frac{\theta}{n + \theta} \right)^m \frac{n}{n + \theta} (P^m)_{\alpha\beta} \\
= \sum_{\alpha} \sum_{m=0}^{\infty} \frac{n_{\alpha}}{n} (1 - \lambda_n) [(\lambda_n P)^m]_{\alpha\beta} \\
= \sum_{\alpha} \frac{n_{\alpha}}{n} (1 - \lambda_n) [(I - \lambda_n P)^{-1}]_{\alpha\beta}
\]

The last equation follows from the geometric sum formula of matrices.

\[ \sum_{m=0}^{\infty} M^m = (I - M)^{-1}. \]
proof of (d) continued

As this holds for all vectors \( \frac{n_a}{n}, \ldots, \frac{n_a}{n} \), we conclude:

\[
(n + 1)M^{(n)} = n \cdot M^{(n+1)} + M^{(n)} \cdot M^{(n+1)}
\]

From this recursion and the initial value \( M^{(1)} = (1 - \lambda_1)(I - \lambda_1 P)^{-1} \) set by (b), follows \( M^{(n)} = (1 - \lambda_n)(I - \lambda_n P)^{-1} \). This implies \( \hat{\pi} = \tilde{\pi} \).

We define the proposal distribution \( Q_{\theta}^{SD} \) with \( \tilde{q} \) like \( Q_{\theta}^{\alpha} \) with \( q \) by replacing \( \pi \) by the approximation \( \tilde{\pi} \).

**Theorem 4**

\[
\sum_H \tilde{q}_\theta(H \mid H_i) = 1
\]

and \( \tilde{q}_\theta(\cdot \mid H_i) \) can be simulated as follows:

1. Choose a purely random \( \alpha \in H_i \).
2. For all \( \beta \) compute \( \tilde{\pi}(\beta \mid H_i - \alpha) \)
3. \( H_{i-1} := \begin{cases} H_i - \alpha + \beta & \text{with probability } \alpha \tilde{\pi}(\beta \mid H_i - \alpha) \cdot P_{\beta \alpha} \\ H_i - \alpha & \text{with probability } \alpha n_{\alpha} - 1 \end{cases} \)

Thus, \( \tilde{\pi}(\beta \mid H_i - \alpha) \) must be computed only for a few pairs \( (\alpha, \beta) \). First sample \( \alpha \) and then decide whether it mutated to beta \( \beta \) or coalesces with another \( \alpha \). It is efficient to compute \( \tilde{\pi}(\beta \mid H_i - \alpha) \) and to simulate \( Q_{\theta}^{SD} \).

**Proof:**

The probability that a mutation of a type \( \alpha \) is involved, is

\[
p_m(\alpha) = \frac{1}{n(n - 1 + \theta)} \sum_\beta \theta \frac{\tilde{\pi}(\beta \mid H_i - \alpha)}{\pi(\alpha \mid H_i - \alpha)} P_{\beta \alpha}.
\]

The probability that two lineages of type \( \alpha \) coalesce, is:

\[
p_c(\alpha) = \frac{n_\alpha(n_\alpha - 1)}{n(n - 1 + \theta)} \cdot \frac{1}{\pi(\alpha \mid H_i - \alpha)}
\]

This implies \( p_m(\alpha) + p_c(\alpha) = 1 \).
What to do with sequence data??

For nucleotide (or protein) sequences of length $\ell$ there are $4^\ell$ (or $20^\ell$) different possible genotypes $\alpha = (\alpha_1, \ldots, \alpha_\ell)$, and the transition matrix $(P_{\alpha\beta})_{\alpha\beta}$ could be very large.

$\theta/2$: mutation rate per site.

For $\hat{\pi}(\cdot \mid A_n)$ draw a geometrically distributed number $m$ of mutations with parameter $\frac{\ell\theta}{n+\theta}$ and spread them randomly on the sites.

Equivalent: draw $\exp(1)$-distributed time $t$ and then for each site $i$ a Poisson($t\theta/n$) distributed number $m_i$ of mutations. This implies $\hat{\pi}(\beta \mid A_n) = \sum_{\alpha \in A_n} \frac{n_\alpha}{n} \int \exp(-t) F_{\alpha_1\beta_1}(\theta, t, n) \cdots F_{\alpha_\ell\beta_\ell}(\theta, t, n) \, dt$

with

$$F_{\alpha_\ell\beta_\ell}(\theta, t, n) = \sum_{m=0}^{\infty} \frac{(\theta t/n)^m}{m!} \exp(-\theta t/n)(P_m)_{\alpha_\ell\beta_\ell}.$$ 

Stephens and Donnelly suggest to approximate the integral with Gauß quadrature (siehe Press et al. (1992)) to obtain

$$\hat{\pi}(\beta \mid A_n) = \sum_{\alpha \in A_n} \sum_{i=1}^s \frac{n_\alpha}{n} w_i F_{\alpha_1\beta_1}(\theta, t_i, n) \cdots F_{\alpha_\ell\beta_\ell}(\theta, t_i, n)$$

for certain $s, w_i$ and $t_i$. The $F_{\alpha_\ell\beta_\ell}(\theta, t, n) = \sum_{m=0}^{\infty}$ can be approximated by finite sums.

12.2 Phasing

Why phasing?

Many sequence datasets from diploid (polyploid) organisms are unphased. For example, it is known that some individual has an A and a T at one locus, and a G and a C at another locus on the same chromosome, but not wheter the A is on the same haplotype (chromosome copy) as the C or as the G.

$\overline{[A, T]} \overline{[C, G]} \Rightarrow \overline{A C} \quad \text{or} \quad \overline{A G}$

Estimating this (“phasing the data”) can be important, e.g. because Linkage Disequilibrium (LD) is informative about

- population structure
- epistatis
- selective sweeps
- whether a gene locus is associated with a trait of interest or just physically linked to a relevant locus

Clark’s Algorithm

- parsimonious approach to minimize the total number of haplotype classes observed in the sample
- greedy algorithm
- starting with individuals that are homozygous at all loci or at all up to one

$[0, 0], [0, 1], [0, 0], [1, 1] \Rightarrow \overline{0 1 0 0}$

- successively searches individuals that can be phased such that one or both haplotypes is identical to already inferred one.

$[0, 1], [0, 1], [0, 1], [1, 1] \Rightarrow \overline{0 1 0 0}$

- final result depends on input order
12.2.1 Excoffier and Slatkin’s EM algorithm

References


"phenotype": multilocus genotype with unknown phase, e.g.

\[ \text{genotype}= -0-1-0-1- \quad \Rightarrow \quad \text{phenotype}= [0, 0], [0, 1], [1, 0], [1, 1] \] (unordered pair) (unordered pairs)

\( P_i \): phenotype probability

\( n_i \): absolute frequency of phenotype \( i \) in sample, \( n = \sum_i n_i \)

\[ \Pr(\text{sample} | P_1, P_2, \ldots, P_m) = \frac{n!}{n_1! \cdot n_2! \cdots n_m!} \cdot P_1^{n_1} \cdot P_2^{n_2} \cdots P_m^{n_m} \]

one aim:

estimate population frequencies \( p_1, p_2, \ldots \) of haplotype classes \( h_1, h_2, \ldots \).

Expectation Maximization (EM) algorithm

Iterate E step and M step:

E step Use current estimates of \( p_1, p_2, \ldots \) to compute expected frequencies \( f_{k\ell} \) of all genotypes \((k, \ell)\) \( (with \ k \leq \ell) \) in the sample, given the sampled phenotypes. For this, let \( I_{k\ell, j} \) be the indicator function that \([k, \ell]\) leads to phenotype \( j \) (i.e. \( I_{k\ell, j} = 1 \) in this case and 0 otherwise), and \( \delta_{k\ell} \) be the indicator function of \( k = \ell \). Then

\[ P_j = \sum_k \sum_\ell p_k p_\ell \cdot I_{k\ell,j} \]

and

\[ f_{k\ell} = \sum_j I_{k\ell,j} \cdot \frac{n_j}{n} \cdot \frac{p_k p_\ell}{P_j} \cdot 2 \cdot \left( \frac{1}{2} \right)^{\delta_{k\ell}}. \]

M step Use expected genotype frequencies in sample to estimate haplotype class probabilities \( p_i \) (=frequencies in population).

\[ p_i = f_{ii} + \frac{1}{2} \cdot \left( \sum_{k=1}^{i-1} f_{ki} + \sum_{k=i+1}^{m} f_{ik} \right) \]

Excoffier and Slatkin use Fisher Information to estimate variance of the estimators, and use estimated \( p_i \) to infer haplotypes.

12.2.2 Excursus: EM algorithm

EM algorithm in general

References


\( X \) observed data
$U$ unobserved data

$\theta$ parameter to be estimated

$\ell$ log likelihood

$$\ell(\theta; x, u) = \log P_{\theta}(X = x, U = u)$$

$P$ Probability or probability density

$$\ell(\theta; u \mid x) := \log P_{\theta}(U = u \mid X = x)$$

$U$ unobserved

$$\ell(\theta; x, U) = \ell(\theta; u \mid x) + \ell(\theta; x)$$

$\ell(\theta; x, U)$ is a random variable

$$Q_{\theta'}(\theta) := \mathbb{E}_{\theta'}(\ell(\theta; x, U) \mid x)$$

$$C_{\theta'}(\theta) = \mathbb{E}_{\theta'}(\ell(\theta; U \mid x) \mid x)$$

$$\ell(\theta) := \ell(\theta; x) = Q_{\theta'}(\theta) - C_{\theta'}(\theta)$$

To estimate $\theta$ iterate the following steps:

**E step** with current estimate $\theta'$ compute the function $Q_{\theta'} : \theta \mapsto Q_{\theta'}(\theta)$

**M step**

$$\theta^{\text{new}} := \arg \max_{\theta} Q_{\theta'}(\theta)$$

Iterate E step with $\theta'$ replaced by $\theta^{\text{new}}$.

Note that from

$$\ell(\theta) = Q_{\theta'}(\theta) - C_{\theta'}(\theta)$$

follows that

$$Q_{\theta'}(\theta^{\text{new}}) \geq Q_{\theta'}(\theta')$$

implies

$$\ell(\theta^{\text{new}}) - \ell(\theta') \geq C_{\theta'}(\theta') - C_{\theta'}(\theta^{\text{new}})$$

$$= \int P_{\theta'}(U = u \mid x) \cdot \log \frac{P_{\theta'}(U = u \mid x)}{P_{\theta^{\text{new}}'}(U = u \mid x)} du \geq 0$$

Note that the integral is a Kullback-Leibler Divergence, which is according to Gibbs’ inequality always $\geq 0$, and $= 0$ only if the two distributions are equal.

$$\sum_i p_i \cdot \log \frac{p_i}{q_i} = - \sum_i p_i \cdot \log \frac{q_i}{p_i} \geq - \sum_i p_i \cdot \left( \frac{q_i}{p_i} - 1 \right) = - \sum_i q_i + \sum_i p_i = -1 + 1 = 0$$

Therefore, an EM step will never decrease the likelihood (which is not true, e.g., for Newton optimization steps).

Why is Excoffier and Slatkin’s EM algorithm a special case of this?

$x$ “phenotypes”

$U$ genotypes

$\theta$ haplotype frequencies $p_1, p_2, \ldots$
\[ \mathbb{E}_{\theta'}(\ell(\theta; x, U)|x) = ? \]

If the phenotypes \( x \) are in accordance with the genotypes \( u \), then

\[
\ell(\theta; x, u) = \log(P_{\theta}(u)) = \log \left( \frac{n!}{n_1! \cdots n_m!} \right) + \sum_i \log \left( 2p_{u(i,1)}p_{u(i,2)} \cdot \left( \frac{1}{2} \right)^{\delta_{u(i,1),x(i,2)}} \right)
\]

\[
Q_{\theta'}(\theta) = \mathbb{E}_{\theta'}(\ell(\theta; x, U)|x)
\]

\[
= \log \left( \frac{n!}{n_1! \cdots n_m!} \right) + \sum_i \mathbb{E}_{\theta'} \left( \log \left( 2p_{U(i,1)}p_{U(i,2)} \cdot \left( \frac{1}{2} \right)^{\delta_{U(i,1),x(i,2)}} \right) \right) \bigg| _{x_i}
\]

The conditional expectation in the last line is, by definition,

\[
\sum_{[k, \ell] \in P_i} \mathbb{P}_{\theta'}(U = [k, \ell]|x_i) \cdot \log \left( \frac{2p_kp_{\ell} \cdot 0.5^{\delta_{k\ell}}}{\sum_{[k', \ell'] \in P_i} 2p_{k'}p_{\ell'} \cdot 0.5^{\delta_{k'\ell'}}} \right)
\]

Where the sum is taken over the set \( P_i \) of all (unordered) haplotype pairs \([k, \ell]\) that are in accordance with phenotype \( i \).

With

\[
P_{\theta'}(U = [k, \ell]|x_i) = \frac{2p_kp_{\ell} \cdot 0.5^{\delta_{k\ell}}}{\sum_{[k', \ell'] \in P_i} 2p_{k'}p_{\ell'} \cdot 0.5^{\delta_{k'\ell'}}},
\]

where \( \theta' = (p'_1, p'_2, ...) \).

Putting it all together and rearranging the sums, we obtain

\[
Q_{\theta'}(\theta) = \sum_k \sum_{i=1}^n \frac{p'_k \sum_{\ell} I_{k,\ell}p'_\ell}{\sum_{k'} \sum_{\ell'} I_{k',\ell'}p'_{k'}p'_{\ell'}} \log p_k + \text{const}
\]

where const is a term that does not depend on any \( p_k \). Thus, \( Q_{\theta'}(\theta) \) is optimized by setting

\[
p_k \propto \sum_{i=1}^n \frac{\sum_{\ell} I_{k,\ell}p'_\ell}{\sum_{k'} \sum_{\ell'} I_{k',\ell'}p'_{k'}p'_{\ell'}}
\]

because, in general, the distribution \( p_1, p_2, \ldots \) that maximizes \( \sum_i n_i \log p_i = p_i / \sum n_j \). This follows from the information inequality

\[
\sum p_i \log p_i > \sum p_i \log q_i,
\]

which is equivalent to

\[
\sum p_i \log \frac{p_i}{q_i} > 0
\]

(always assuming that distributions \( p \) and \( q \) are not equal).

Note that, indeed,

\[
p_k \propto \sum_{i=1}^n \frac{\sum_{\ell} I_{k,\ell}p'_\ell}{\sum_{k'} \sum_{\ell'} I_{k',\ell'}p'_{k'}p'_{\ell'}}
\]

is the same as the M step in Excoffier and Slatkin’s EM algorithm.
12.2.3 Basic algorithms in PHASE

References


\[ G = (G_1, \ldots, G_n) \] observed genotypes of \( n \) individuals

\[ H_i = (h_{i1}, h_{i2}) \] unknown (unordered) haplotypes of individual \( i \)

Gibbs sampling with target distribution \( \Pr(H|G) \): Start with initial guess for \( H \) and iterate the following steps.

- choose individual \( i \) purely randomly from all ambiguous individuals
- sample updated \( H_i \) from \( \Pr(H_i|G, H_{-i}) \), where \( H_{-i} \) is \( H \) without \( H_i \).

Problem: \( \Pr(H_i|G, H_{-i}) \) depends on genetic and demographic models, e.g. on priors of haplotype frequencies

\[ \Pr(H_i|G, H_{-i}) \propto \Pr(H_i|H_{-i}) \propto \Pr(h_{i1}|H_{-i}) \cdot \Pr(h_{i2}|H_{-i}, h_{i1}) \]

\( \Pr(h_{i1}|H_{-i}) \) is only easy in parent-independent mutation model, which is usually unrealistic.

Stephens, Smith and Donnelly (2001) discuss two possible approximations, a “naive” one and their preferred one.

The naive Gibbs sampler

assumes parent-independent mutation

\[ \Pr(h|H) = \frac{r_h + \theta v_h}{r + \theta} \]

\( r_h \) number of haplotypes of type \( h \) in \( H \)
\( r \) total number of haplotypes in \( H \)
\( v_h \) in case of mutation this is the probability that it leads to \( h \)
\( \theta \) population-scaled mutation rate

If individual \( i \) has \( k \) heterozygous loci, \( 2^{k-1} \) different haplotypes \( h \) are possible. If this may be too many, just set \( v_h = 1/M \), where \( M \) is the number of possible haplotypes.

The naive algorithm

1. pick individual \( i \) uniformly, let \( k \) be its number of heterogeneous loci; let \( \{h_1, \ldots, h_m\} \) be the other individuals’ haplotypes.
2. for \( j = 1, \ldots, m \) do
   if \( H_i \) could be \( (h_j, h') \) then
     if \( h' \) is some \( h_k \in \{h_1, \ldots, h_m\} \) then
       \[ p_j = (r_j + \frac{\theta}{M})(r_k + \frac{\theta}{M}) - \left( \frac{\theta}{M} \right)^2 \]
     else
       \[ p_j = r_j \frac{\theta}{M} \]
     end if
   else
     \[ p_j = 0 \]
   end if
end for
3. With prob \( \frac{2^k \left( \frac{\theta}{M} \right)^2}{\sum_j p_j + 2^k \left( \frac{\theta}{M} \right)^2} \) reconstruct \( H_i \) completely at random.
   Else: Choose \( H_i = (h_j, h') \) with probability \( p_j / \sum_k p_k \).
The basic standard algorithm in PHASE

The basic standard algorithm in PHASE uses an approximation proposed by Stephens and Donnelly (2000):

\[ Pr(h|H) \approx \sum_{\alpha} \sum_{s=0}^{\infty} \frac{r_{\alpha}}{r} \left( \frac{\theta}{r + \theta} \right)^s \frac{r}{r + \theta} (P^s)_{\alpha h} \]

- \( r_{\alpha} \) number of haplotypes of type \( \alpha \) in \( H \)
- \( r \) total number of haplotypes in \( H \)
- \( \theta \) population-scaled mutation rate (see next slide)
- \( P \) transition matrix between types, given a mutation happens
- \( s \) number of mutations

The basic standard algorithm in PHASE

- For polymorphic sites, assume only one mutation happened and set
  \[ \theta = \frac{1}{\log 2n} \]
- Problem: For sequence data, \( P \) will be huge. In this case use Gaussian quadrature (see also next section).
- For microsatellite data assume a stepwise mutation model with 50 alleles and set
  \[ \theta_j = \frac{1}{2} \left( \frac{1}{1 + H} - 1 \right), \]
  where \( H \) is the observed heterozygousity at that locus.

The basic standard algorithm in PHASE

Start with initial phasing and iterate the following steps

1. Choose individual \( i \) uniformly
2. Select subset \( S \) of (e.g. 5) ambiguous loci \( i \)
3. Phase the loci in \( S \) in individual \( i \) conditioned on the current phase of all other loci and of all loci in the other individuals.

References


introduce a few improvements:

- in each step the genomes of all individuals are subdivided into blocks of the same number of loci (6, 7, or 8, with probs. 0.3, 0.3, 0.4). Then, a block is chosen for all individuals in random order and the loci of this block are updated (conditioned on all other individual and on all other loci in the focal individual).
- in a certain fraction of individuals, it is allowed that only one haplotype is a copy of another haplotype in the data. This fraction is reduced down to 0 during the MCMC procedure.
- After the blockwise MCMC, haplotype frequencies are estimated for each block and blocks are iteratively ligated with adjacent blocks into larger blocks.
12.2.4 PAC in PHASE

References


• Use information about order and distance between marker positions
• recombination rates may vary and are estimated
• applicable also when LD is “blocklike”
• imputation of missing data

\[ n \text{ number of individuals} \]
\[ L \text{ number of loci} \]
\[ G = (G_1, \ldots, G_n) \text{ genotypes; observed up to missing loci} \]
\[ H = (H_1, \ldots, H_n) \text{ haplotypes; to be reconstructed} \]
\[ H_{-i} = (H_1, \ldots, H_{i-1}, H_{i+1}, \ldots, H_n) \]
\[ \rho = (\rho_1, \ldots, \rho_{L-1}) \text{ recombination rates between loci} \]
\[ \rho_\ell = \frac{4N_e c_\ell}{d_\ell} \]

\( c_\ell \) recombination probability per generation between loci \( \ell \) and \( \ell + 1 \); to be estimated
\( d_\ell \) known distance between loci \( \ell \) and \( \ell + 1 \)

strategy of PAC approach in PHASE

Start with initial \( H \) and \( \rho \) the following steps many times:
1. for each \( i \) update \( H_i \) by sampling from \( \Pr(H_i|G_i, H_{-i}, \rho) \)
2. propose change of \( \rho \) and accept or reject with Metropolis-Hastings (MH) step
3. update ordering \( \nu \) of individuals with MH step for order-dependent PAC probabilities

Needed in these steps:
\[ \Pr(H_i = (h, h')|H_{-i}, \rho) \propto (2 - \delta_{hh'}) \cdot p(h'|H_{-i}, \rho) \cdot p(h|H_{-i}, h', \rho) \]

(where \( p(h|H_{-i}, h', \rho) \) will be approximated by \( p(h|H_{-i}, \rho) \); note that \( 2 - \delta_{hh'} = 2 \cdot \left(\frac{1}{2}\right)^{\delta_{hh'}} \))

Simplifying assumption in the computation of \( p(h|h_1, \ldots, h_k, \rho) \):
• when a locus in \( h \) is copied from some \( h_i \) only two possible coalescence times are allowed (\( t_1 = 0.586/k, t_2 = 3.414/k \)) and taken with probabilities \( w_1 = 0.854 \) and \( w_2 = 0.146 \). This is a Gaβ quadrature approximation of the exponential distribution.
• if \( X_\ell \) is the allele from which locus \( \ell \) in \( h \) is copied and \( T_\ell \) the corresponding coalescence time, then \( (X_1, T_1), (X_2, T_2), \ldots \) is a Markov chain with \( \Pr(X_1 = x, T_1 = t_r) = w_r/k \) and transition probabilities \( \Pr(X_{\ell+1} = x', T_{\ell+1} = t_r'|X_\ell = x, T_\ell = t_r) = \)
\[ (1 - e^{-\rho_\ell d_\ell/k}) \cdot w_r/k + \delta_{xx'}\delta_{rr'}e^{-\rho_\ell d_\ell/k}. \]

Thus, HMM algorithms can be applied again.
\[
\Pr(h_{k+1} = a | X_t = x, T_t = t, h_1, \ldots, h_k, r) = \sum_m \frac{(\theta t)^m}{m!} e^{-\theta t} (P_m)_{h_x,ta}
\]

Proposals for step 1 are haplotypes that are composed by blocks as described in Stephens and Donnelly (2003), leading to a list of promising haplotypes compatible with \( G_i \).

For these haplotypes probabilities are computed with forward algorithm and one of them is chosen randomly according to the computed probabilities.

For imputation of missing types, probabilities are computed with forward-backward algorithm and types are sampled accordingly.

**performance studies**

**haplotype inference:**

**dataset1** 40 X chromosomes from unrelated males, paired into 20 pseudo-individuals, 8 regions of 87–327 kb and 45–165 segregating sites

**dataset2** autosomal data from 129 children with known phase (as parents were also genotyped),

**result** PHASE with recombination PAC model best overall and for most regions.

**imputing missing data:**

**data** 50 genes sequenced for 24 humans of African descent and 23 of European descent, 15–230 segregating sites per gene.

**simulation** remove 5% of the data (in addition to 4.6% that was actually missing), either single alleles or the genotypes.

**result** PHASE with recombination PAC model always best

**References**

[CB+04] Crawford, Bhagale, Li, Hellenthal, Rieder, Nickerson, Stephens (2004) Evidence for substantial fine-scale variation in recombination rates across the human genome *nature genetics*

[CB+04] Myers, Freeman, Auton, Donnelly, McVean (2008) A common sequence motif associated with recombination hot spots and genome instability in humans *nature genetics*

### 12.3 Phasing large genomic datasets

#### 12.3.1 fastPHASE

**References**


If \( n \) haplotyps are to be reconstructed (that is, from \( n/2 \) sampled individual) at \( M \) marker positions, than the complexity of HMM algorithms in PHASE is \( \mathcal{O}(n^3 M) \).

fastPHASE reduces this to \( \mathcal{O}(nM) \).

Instead of sampling sections of haplotypes from copies of other haplotypes, all section are sampled from \( K \) clusters, similar to STRUCTURE.
First consider clustering method of haplotypes, where cluster just as is a set of closely related haplotypes.

Then extend for phasing with in Hardy-Weinberg Equilibrium (HWE) within clusters. First: consider local clustering method for haplotypes.

Given $h = (h_1, \ldots, h_n)$ haplotypes with $M$ biallelic $\{0, 1\}$ (can be relaxed) marker positions.

$z_{im} \in \{1, \ldots, K\}$ origin of $h_{im}$, (marker position $m$ in $h_i$). $z_i = (z_{i1}, \ldots, z_{iM})$ modeled as a Markov chain with

$$p(z_{i1} = k) = \alpha_k$$

and $p_m(k \to k') :=$

$$p(z_{im} = k' | z_{i(m-1)} = k, \alpha, r) = (1 - e^{-r_m d_m}) \cdot \alpha_{k'} + \delta_{k'k} \cdot e^{-r_m d_m},$$

where $d_m$ is the distance between markers $m-1$ and $m$, and the recombination parameters $r = (r_2, \ldots, r_M)$ as well as $\alpha = (\alpha_{km})$ are to be estimated.

Now for the emission probabilities:

$$p(h_i | z_i, q) = \prod_{m=1}^{M} p(h_{im} | z_{im}, q) = \prod_{m=1}^{M} q_{z_{im}m} \cdot (1 - q_{z_{im}m})^{1-h_{im}},$$

where $q_{km}$ is the frequency of allele 1 at marker $m$ in cluster $k$.

Again, we obtain an HMM, parameter estimation can be done with EM, assignements of haplotype sections to clusters e.g. with Viterbi-Algorithm or Bayesian sampling tracing back contributions in the forward algorithm.

Now assume that unphased genotypes $g = (g_1, \ldots, g_n)$ are given, $g_{im} \in \{0, 1, 2\}$ is the genotype at marker $m$ in individual $i$. Now assume HWE in each cluster. Let $\tilde{z}_{im}$ be the unordered pair of clusters of origin of $g_{im}$:

$$p(\tilde{z}_{i1} = \{k_1, k_2\}) = (2 - \delta_{k_1k_2}) \alpha_{k_1} \alpha_{k_2}$$

and assume that $\tilde{z}_i = (\tilde{z}_{i1}, \ldots, \tilde{z}_{iM})$ is a Markov chain with transition probabilities $p_m(\{k_1, k_2\} \to \{k'_1, k'_2\}) = \frac{p_m(k_1 \to k'_1) \cdot p_m(k_2 \to k'_2) + (1 - \delta_{k_1k_2}) \delta_{k'_1k'_2}}{p_m(k_1 \to k'_1) \cdot p_m(k_2 \to k'_2)}$.

Emission probabilities:

$$p(g_{im} | \tilde{z}_{im} = \{k_1, k_2\}, q) = \left\{ \begin{array}{ll} (1 - q_{k_1m})(1 - q_{k_2m}) & \text{if } g_{im} = 0 \\ q_{k_2m}(1 - q_{k_1m}) + q_{k_1m}q_{k_2m} & \text{if } g_{im} = 1 \\ q_{k_1m}q_{k_2m} & \text{if } g_{im} = 2 \end{array} \right.$$
12.3.2 Phasing with Beagle software package

References


For an initial guess of the haplotypes first construct a directed acyclic graph (DAG), in which
• each edge has a level $m$ corresponding to marker position $m$
• and a label corresponding to an allele occurring at marker position $m$,
• and for each of the occurring haplotypes $h_i = (h_{i1}, \ldots, h_{iM})$ there is a path from the start node to the end node such that the labels of the edges are $h_{i1}, \ldots, h_{iM}$.
• (If a node has incoming edges of level $m$ than all its outgoing edges are of level $m+1$, and vice versa.)

Method of graph construction described in paper by S.R. Browning (2006)

Then construct an HMM whose possible states at step $m$ are ordered pairs of DAG edges of the same level $m$. Transition probabilities:

$$P((e_1, e_2) \rightarrow (e_3, e_4)) = P(e_1 \rightarrow e_3) \cdot P(e_2 \rightarrow e_4),$$

where

$$P(e_1 \rightarrow e_j) = \frac{|\{\text{haplotypes whose path contains } e_i \text{ and } e_j\}|}{|\{\text{haplotypes whose path contains } e_i\}|}$$

Emission probability: 1 if genotype at marker position $m$ is compatible with labels of edges belonging to state, otherwise 0.

Now use “diploid HMM” to sample for each individual several haplotypes (in Beagle software 4 haplotype pairs per individual). Pool these haplotypes to construct DAG for next iteration. For sampling use forward algorithm restricted on states corresponding to states of the focal individual, and random tracebacks, with probabilities always proportional to current state. In last iterations use Viterbi paths instead of random paths.

12.3.3 IMPUTE version 2

References


Similar to PAC-approach in PHASE, but is made for situation when reference haplotype data is available. Reference haplotypes and unphased genotypes are used together in phasing update step. For runtime efficiency untyped SNPs are imputed in haplotype HMM framework rather than in diploid HMM.

For acceleration restrict set of possible haplotypes in each iteration to those that are similar to existing ones.
12.3.4 MaCH

References


Similar to fastPHASE, but uses a larger number of haplotype templates instead of few haplotype groupings. In emission probabilities use error parameter $\varepsilon_j$ that can depend on position $j$ and covers sequencing error, gene conversion,…

12.3.5 polyHAP

References


Similar HMM approach like fastPHASE but for polyploid data. Computationally very demanding because states are unordered lists stating how many alleles have been sampled from how many clusters. Thus, many possible transitions between hidden states are considered.