Computational Methods in Population Genetics

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1 Examples





2 Wright Fisher model and Kingman's Coalescent

Basic assumptions of the Wright Fisher model

- non-overlapping generations
- $\bullet\,$ constant population size
- \bullet panmictic
- neutral (i.e. no selection)
- no recombination
- N diploid individuals \rightsquigarrow population of 2N haploid alleles (in case of autosomal DNA)

Wright Fisher model

Each allele chooses an ancestor in the generation before. $_{\scriptscriptstyle\rm Generation}$



Samples are assumed to be taken purely randomly from the population.



This induces a specific random distribution for the genealogies of the sampled alleles.



Haploid population of size N_e

Average time until two ancestral lineages coalesce: N_e generations. Scale time: (1 time unit) = (N_e generations) \Rightarrow pairwise coalescence rate = 1 μ := mutation rate per generation

$$\theta := 2N_e \cdot \mu$$

is the expected number of mutations between 2 random individuals Let $N_e \longrightarrow \infty$



typical coalescent trees for n = 8:



simulated coalescent tree with n = 500:



3 Estimators for θ and Tajima's π

Two estimators of θ

 θ_{π} ("Tajima's π ") Average number of pairwise differences.

$$\theta_W$$
 ("Watterson's θ ") = $\frac{\text{number of mutations}}{\sum_{i=1}^{k-1} 1/i}$

Both are unbiased estimators of θ , i.e. $\mathbb{E}\theta_W = \mathbb{E}\theta_{\pi} = \theta$.

Example: Ward et al. (1991) sampled 360 bp sequences from mtDNA control region of n = 63 Nuu Chah Nulth and observed 26 mutations.

$$\theta_W = \frac{26}{\sum_{i=1}^{63} 1/i} = 5.5123$$

This corresponds to 0.0153 Mutations per base and per $2 \cdot N_e$ generations. Assuming a mutation rate $\hat{\mu} \approx 6.6 \cdot 10^{-6}$ per generation per site this leads to an effective population size of

$$\widehat{N_e} = \frac{\theta_W/360}{2\cdot\widehat{\mu}} \approx 1150 \text{ females}$$

How precise is this estimation?

$$\operatorname{var}(\theta_W) = \frac{\theta}{\sum_{i=1}^{n} 1/i} + \theta^2 \cdot \frac{\sum_{i=1}^{n} 1/i^2}{\left(\sum_{i=1}^{n} 1/i\right)^2}$$

Theorem 1 Any unbiased estimator of θ has variance at least

$$\frac{\theta}{\sum_{k=1}^{n-1}\frac{1}{k+\theta}}.$$

(Here, we assume that the estimation is based on a single locus without recombination).

For the Nuu Chah Nulth data we get:

$$\theta_W = 5.5123$$

 $\sigma_{\theta_W} = 3.42$

Confidence range? (2σ -rule would leed to negative values...)

Conclusion: N_e could perhaps also be 200 or 3000 females. How can we improve this estimate? Sample more individuals? How many individuals n would we need to get $\sigma_{\theta_W} = 0.1 \cdot \theta$? From the formula for $\operatorname{var} \theta_W$ follows that we need $n \approx 2 \cdot e^{100/\theta}$. For $\theta = 5$, this is $n \approx 10^9$. For $\theta = 1$, this is $n \approx 10^{43}$. number of water molecules on earth $\approx 10^{47}$ number of seconds since big bang $\approx 4.3 \cdot 10^{17}$

Solution: sample many loci!

References

[Fel06] J. Felsenstein (2006) Accuracy of Coalescent Likelihood Estimates: Do We Need More Sites, More Sequences, Or More Loci? Mol. Biol. Evol., 23.3: 691–700.

How to sample if

- one read is 600 bp long
- costs for developing a new locus is 40\$
- costs for collecting a sample is 10 or 0.10\$
- costs for a single read is 6\$
- you can spend 1000\$
- true θ is 1.8 (per locus)

Optimal sampling scheme: n = 7 or n = 8, respectively, individuals and 11 loci. With this sampling scheme we get:

$$\sigma_{\theta_W} \approx 0.2 \cdot \theta$$
 and $\sigma_{\theta_{\pi}} \approx 0.22 \cdot \theta$

(all this is based on infinite-sites assumptions)



4 Outline of methods

4.1 ML with Importance Sampling

The Likelihood

 $\psi = (\psi_i)_i$ vector of model parameters

 ${\cal D}\,$ sequence data

$$L_D(\psi) = \Pr_{\psi}(D) = \int_{\text{all Genealogies } G} \Pr_{\psi}(D \mid G) \cdot P_{\psi}(dG).$$

Importance Sampling

Draw G_1, \ldots, G_k (approx.) i.i.d. with density Q and approximate

$$\int \Pr_{\psi}(D \mid G) \ P_{\psi}(dG) \approx \frac{1}{k} \sum_{i=1}^{k} \frac{\Pr_{\psi}(D \mid G_i) \cdot P_{\psi}(G_i)}{Q(G_i)}.$$

efficient for ψ with

$$\Pr_{\psi}(D \mid G_i) \cdot P_{\psi}(G_i) \approx Q(G_i)$$

Methods differ in their choice of Q.

Griffiths & Tavaré (1994)

Q: Generate G backwards in time, greedy proportional to coalescence and mutation probabilities. Choose between all allowed events.

Good for infinite sites models, inefficient if back-mutations are allowed.

4.2 MCMC for frequentists and Bayesians

Felsenstein, Kuhner, Yamato, Beerli,...

For some initial ψ_0 , sample Genealogies G approx. i.i.d. according to $\Pr_{\psi_0}(G \mid D)$ by Metropolis-Hastings MCMC.

Coalescent is a natural prior for G! Two flavours:

for frequentists: use G_1, \ldots, G_k for Importance Sampling

Optimize approx. Likelihood $\rightarrow \psi_1$

Iterate with ψ_0 replaced by ψ_1

for Baysians: Then sample ψ conditioned on Genealogies and iterate to do Gibbs-sampling from $\Pr(\psi, G \mid D)$.

Problems of full-data methods

- usual runtime for one dataset: several weeks or months
- complex software, development takes years
- most programs not flexible, hard to write extensions

4.3 Approximate Bayesian Computation (ABC)

Pritchard et al. (1999)

Approximate Bayesian Computation

- 1. Select summary statistics $S = (S_i)_i$ and compute their values $s = (s_i)_i$ for given data set
- 2. Choose tolerance δ
- 3. repeat until k accepted ψ' :
 - Simulate ψ' from prior distribution of ψ
 - Simulate genealogy G according to $\Pr_{\psi'}(G)$.
 - Simulate data and compute values s^\prime of S
 - accept ψ' if $||s s'|| \le \delta$

Only possible if a few summary statistics suffice. We will later discuss refinements and extensions of this approach.

Beaumont, Zhang, Balding (2002)

"[...] the MCMC-based method is consistently superior to the summary-statistics-based methods and highlights that it is well worth making the effort to obtain full-data inferences if possible."

"[...] there are advantages to the use of summary statistics, both in the ease of implementation and in the time to obtain the results [...]"

"Further research is needed to find a more rigorous way for choosing summary statistics, including the use of orthogonalization and 'projection-pursuit' methods"

5 Importance sampling for genealogies

D: data set of DNA sequences sampled from a population. In case of a structured population sampling locations are known.

Aim: Estimate parameters $\Theta := (\theta_i, M_{ij})_{ij}$.

Maximum-Likelihood (ML) approach: Find the set of parameter values that maximizes the likelihood:

$$\Theta := \arg\max_{\Theta} \mathsf{Pr}_{\Theta}(D)$$

How to compute the likelihood?

$$L_D(\Theta) = \Pr_{\Theta}(D) = \sum_{G} \Pr_{\Theta}(G) \cdot \Pr_{\Theta}(D \mid G).$$

More precisely:

$$L_D(\Theta) = \mathsf{Pr}_{\Theta}(D) = \int_{\text{all genealogies } G} \mathsf{Pr}_{\Theta}(D \mid G) \ P_{\Theta}(G) dG$$

where $P_{\Theta}(G)$ is the density of the (structured) coalescent distribution at the genealogy G.

What does this mean?

And what is dG?

Let's first ask: What is the dx in

$$\int_0^1 x^2 dx \qquad ?$$

dx is used in an ambigous way. This is sloppy but intuitive.

It means "a small environment around x", but also the size of this environment.

To explain this we be a little bit less sloppy for a few minutes and write dx for the environment and dx for its size.

For some small $n \in \mathbb{N}$ and $x \in \mathbb{R}$ we can define $dx = [x - \frac{1}{2n}, x + \frac{1}{2n}]$. Then, dx = 1/n. We can approximate $\int_0^1 x^2 dx$ by

$$\sum_{x \in \{\frac{1}{n}, \frac{2}{n}, \dots, \frac{n}{n}\}} x^2 \cdot \frac{1}{n} = \sum_{x \in \{\frac{1}{n}, \frac{2}{n}, \dots, \frac{n}{n}\}} x^2 \cdot dx \xrightarrow{n \to \infty} \int_0^1 x^2 dx$$

dx is always meant to be "infinitesimally small", i.e. $dx \to 0$

3

What is a probability density?

P(x) is the probability density of a random variable X in x if

$$\Pr(X \in \mathsf{d}x) \approx P(x) \cdot dx$$

and the " \approx " becomes a "=" for "infinitesimally small" dx. This is again sloppy and intuitive. It actually means that

$$\lim_{dx \to 0} \frac{\Pr(X \in \mathsf{d}x)}{dx} = P(x)$$

It then follows that

$$\Pr(X \in [a, b]) = \int_{a}^{b} P(x) dx.$$

Examples

The density of the exponential distribution with rate λ at x is

$$\lambda e^{-\lambda x}$$
.

The density of the normal distribution with mean value μ and standard deviation σ is

$$\frac{1}{\sigma\sqrt{2\pi}} \cdot e^{-\frac{(x-\mu)^2}{2\sigma^2}}.$$

Now for dG

Let dG be a small environment around the genealogy G. This means, dG consists of all genealogies G' that have the same topology as G and if τ_1, \ldots, τ_n are the points in time where coalescent events or migrations of lineages or the like occurr in G, and τ'_1, \ldots, τ'_n are the corresponding points in time for G', then

$$\forall_{k \le n} |\tau_k - \tau'_k| \le \varepsilon.$$

Thus, the volume dG of dG can be defined to be $(2\varepsilon)^n$. The density $P_{\Theta}(G)$ is then defined by

$$\Pr_{\Theta}(G' \in dG) \approx P_{\Theta}(G) \cdot dG$$

where $\Pr_{\Theta}(G' \in \mathsf{d}G)$ is the probability that a genealogy G' that was generated according to the probability distribution of a structured coalecent with parameter values Θ results to be in the environment $\mathrm{d}G$ of G, or, more precisely:

$$\frac{\Pr_{\Theta}(G' \in \mathsf{d}G)}{dG} \stackrel{dG \to 0}{\longrightarrow} P_{\Theta}(G)$$

The equation

$$L_D(\Theta) = \mathsf{Pr}_{\Theta}(D) = \int_{\text{all genealogies}} \mathsf{Pr}_{\Theta}(D \mid G) \ P_{\Theta}(G) dG$$

should now make some more sense to us. But how can we compute it? We use Importance Sampling.

How can we compute the integral $\int_a^b h(x) dx$ of this function h?

I



Approximation by a step function: If x_1, \ldots, x_k are the means of the partition intervals and $c = \frac{b-a}{k}$ is their width, then

$$\int_{a}^{b} h(x) dx \approx \sum_{i=1}^{k} c \cdot h(x_i) = \frac{b-a}{k} \sum_{i=1}^{k} h(x_i)$$



Maybe save some time by just taking a sample of k values h(x).

$$\int_{a}^{b} h(x) \, dx \approx \frac{b-a}{k} \sum_{i=1}^{k} h(X_i) = \frac{1}{k} \sum_{i=1}^{k} \frac{h(X_i)}{\frac{1}{b-a}}.$$

V

Maybe we know a function f that approximates h

We can sample more from the relevant range but we have to correct this by the Importance-Sampling formula:

$$\int h(x) \, dx \approx \frac{1}{k} \sum_{i=1}^{k} \frac{h(X_i)}{q(X_i)}$$

where X_1, \ldots, X_k are independent samples from a distribution whose density q is proportional to f. The closer f is to h, the better the approximation.

Sketch of proof of the IS formula

$$\begin{split} \int_{a}^{b} h(x)dx &= \int_{a}^{b} \frac{h(x)}{q(x)} \cdot q(x)dx \\ &= \mathbb{E}_{q} \frac{h(X)}{q(X)} \\ &= \frac{1}{k} \cdot \sum_{i=1}^{k} \frac{h(X_{i})}{q(X_{i})}, \end{split}$$

where \mathbb{E}_q is the expectation value under the assumption that X has probability density q, and X_1, \ldots, X_k are independently sampled with probability density q.

Importance Sampling for computing the likelihood of for a range of parameter values Θ : Generate genealogies G_1, \ldots, G_k (more or less) independently according to a probability density $Q(G_i)$. Then,

$$L_D(\Theta) = \int_{\text{all genealogies } G} \Pr(D|G) \cdot P_{\Theta}(G) dG$$
$$\approx \frac{1}{k} \sum_{i=1}^k \frac{\Pr_{\Theta}(D|G_i) \cdot P_{\Theta}(G_i)}{Q(G_i)}.$$

Method differ in their choice of Q and will be most efficient if

$$Q(G) \approx \Pr_{\Theta}(D|G) \cdot P_{\Theta}(G)$$

Griffiths und Tavaré 6

References

[1] Griffiths und Tavaré (1994) Ancestral Inference in Population Genetics Statistical Science 9(3): 307-319. http://www.stats.ox.ac.uk/~griff/software.html

Start with an initial guess Θ_0 . Define the history of a sample to be $H = (H_1, H_2, \ldots, H_\ell)$, where the historical events H_k can be

- 1. lineages i and j coalesce
- 2. mutation on lineage i
- 3. lineage i from island a traces back to island b

and H_1, H_2, \ldots, H_ℓ goes from present to past. For the Importance Sampling procedure, many histories $H^{(1)}, H^{(2)}, \ldots, H^{(M)}$ are generated. For each history $H^{(i)}$ are sampled $H_1^{(i)}, H_2^{(i)}, \ldots$ step by step from the tips to the root of the tree. Given the data, not all events are possible. E.g., lineages cannot coalesce if they are of different allelic type. If the infinite-site mutation model is used (to make the Griffith-Tavaré scheme efficient), not all mutations are



Let $b_{ij}(\theta_0)$ be the probability of the *j*th event $h = H_j^{(i)}$ in the *i*th sampled history $H^{(i)}$ and let $(a_{ijk}(\theta_0))_k$ be the series of rates of all events that would have been allowed for this step. Then, the prob-

ability to choose h was $b_{ij}(\theta_0) / \sum_k a_{ijk}(\theta_0)$. Thus, $\prod_j b_{ij}(\theta_0) / \sum_k a_{ijk}(\theta_0)$ is the importance-sampling probability $Q_{\theta_0}(H^{(i)})$ of the entire history $H^{(i)}$. According to the importance-sampling formula we get for all θ that are not too far from θ_0 :

$$L_{(D)}(\theta) \approx \frac{1}{M} \sum_{i=1}^{M} \prod_{j} \frac{b_{ij}(\theta) \cdot \sum_{k} a_{ijk}(\theta_0)}{\sum_{k} a_{ijk}(\theta) \cdot b_{ij}(\theta_0)}$$

- Advantage over MCMC: Histories are sampled really independent of each other.
- Disadvantage: For finite-sites models many different mutation events are allowed in each step, which makes the method very inefficient. Stephens and Donnelly (2000) found a solution for this, which we will discuss later in the semester.

7 Lamarc (and Migrate)

Rate parameters and time scales For autosomal DNA:

	per	per $2N_i$	per $1/\mu$				
	generation	generations	generations				
mutation rate	μ	$\frac{\theta_i}{2} = 2N_i\mu$	1				
migration rate of							
ances tral lineage from \boldsymbol{i}	m_{ij}	$\gamma_{ij} = 2N_i m_{ij}$	$M_{ij} = \frac{m_{ij}}{\mu} = \frac{2\gamma_{ij}}{\theta_i}$				
tracing back to j			P 1				
coalescence							
on island i	$1/(2N_i)$	1	$\frac{1}{2N_i\mu} = \frac{2}{\theta_i}$				

Number of alleles on island i that choose their parent allele on island j:

 $2N_i \cdot m_{ij} = \gamma_{ij}$

Combining IS with MCMC

References

- M. Kuhner, J. Yamato, J. Felsenstein (1995) Estimating effective population size and mutation rate from sequence data using Metropolis-Hasings sampling. *Genetics* 140: 1421–1430
- [2] P. Beerli, J. Felsenstein (2001) Maximum likelihood estimation of a migration matrix and effective population sizes in n subpopulations by using a coalescent approach. PNAS 98.8: 4563–4568
 - MIGRATE-N http://popgen.sc.fsu.edu/Migrate/Migrate-n.html
 - LAMARC http://evolution.genetics.washington.edu/lamarc/lamarc.html

LAMARC strategy

Begin with initial parameter guess $\Theta_0 = (\theta_1^{(0)}, \theta_2^{(0)}, \dots, M_{12}^{(0)}, M_{12}^{(0)}, M_{23}^{(0)}, \dots)$, repeat the following steps for $i = 0, 1, 2, \dots, m-1$

1. Metropolis-Hastings MCMC sampling of genealogies G_1, G_2, \ldots, G_k (approx.) according to the posterior density $p_{\Theta_i}(G|D)$ given the data D. What is Metropolis-Hastings MCMC?

2. importance sampling:

$$\frac{L_D(\Theta)}{L_D(\Theta_i)} \approx \frac{1}{k} \sum_{j=1}^k \frac{p_{\Theta}(G_j)}{p_{\Theta_i}(G_j)} =: F_{\Theta_i}(\Theta)$$

Why is this justified as importance sampling?

3. $\Theta_{i+1} := \arg \max_{\Theta} F_{\Theta_i}(\Theta)$

and hope that $\Theta_m \approx \widehat{\Theta} = \arg \max_{\Theta} L_D(\Theta)$

Justification of step 2

$$\frac{L_D(\Theta)}{L_D(\Theta_i)} \approx \frac{\frac{1}{k} \sum_{j=1}^k \frac{\Pr_{\Theta}(D|G_j) \cdot p_{\Theta}(G_j)}{p_{\Theta_i}(G_j|D)}}{\Pr_{\Theta_i}(D)} \quad \text{(importance sampling)}$$

$$= \frac{1}{k} \sum_{j=1}^k \frac{\Pr_{\Theta}(D|G_j) \cdot p_{\Theta}(G_j)}{p_{\Theta_i}(G_j|D) \cdot \Pr_{\Theta_i}(D)}$$

$$= \frac{1}{k} \sum_{j=1}^k \frac{\Pr_{\Theta}(D|G_j) \cdot p_{\Theta}(G_j)}{p_{\Theta_i}(G_j,D)}$$

$$= \frac{1}{k} \sum_{j=1}^k \frac{\Pr_{\Theta}(D|G_j) \cdot p_{\Theta}(G_j)}{\Pr_{\Theta_i}(D|G_j) \cdot p_{\Theta_i}(G_j)} = \frac{1}{k} \sum_{j=1}^k \frac{p_{\Theta}(G_j)}{p_{\Theta_i}(G_j)}$$

The last equation follows from $\Pr_{\Theta}(D|G_j) = \Pr_{\Theta_i}(D|G_j)$, which holds since the mutation rate is always 1 and thus the D is independent of Θ when G is given.

Markov-Chain Monte Carlo (MCMC)

MCMC: construct Markov chain $X_0, X_1, X_2, ...$ with stationary distribution $Pr(G \mid D)$ and let it converge.

Markov property:

$$\forall_{i,x}: \Pr(X_{i+1} = x | X_i) = \Pr(X_{i+1} = x | X_i, X_{i-1}, \dots, X_0)$$

In words: The probabilty for the next state may depend on the current state but not additionally on the past.

"Equilibrium" or "Stationary distribution" p:

$$\forall_{i,x}: \quad p(x) = \sum_{y} p(y) \cdot \Pr(X_{i+1} = x | X_i = y)$$

In words: If you choose an element of the state space according to p and go one step, the probability to be in x is p(x) not only in the first step but also in the second step and consequently in any further step. When you are once in equilibrium, you'll be forever.

Theorem 2 If $X_0, X_1, X_2...$ is a aperiodic, irreducible Markov chain on a finite state space S with equilibrium p, it will converge against the equilibrium p in the following sense:

$$\forall_{x,y}: \quad \Pr\left(X_n = x | X_0 = y\right) \xrightarrow{n \to \infty} p(x)$$

Irreducible means:

$$\forall_{x,y} \exists_i \forall_m : \quad \Pr(X_{i+m} = x | X_m = y) > 0$$

Aperiodic means:

$$\mathcal{M}_{x,y,m}: \quad \gcd\left(\{k \in \mathbb{N} | \Pr(X_{k+m} = x | X_m = y) > 0\}\right) = 1,$$

where gcd means "greatest common divisor".

(let's watch a Tcl/Tk simulation of a Markov chain) "Equilibrium" or "Stationary distribution" p:

$$\forall_{i,x}: \quad p(x) = \sum_{y} p(y) \cdot \Pr(X_{i+1} = x | X_i = y)$$

Stronger condition than equilibrium: reversibility (or "detailed balance")

$$p(x) \cdot \Pr(X_{i+1} = y | X_i = x) = p(y) \cdot \Pr(X_{i+1} = x | X_i = y)$$

In words: If you start in equilibrium, and it is reversible, a move from x to y is as probable as a move from y to x.

Alternative explanation: If you watch a movie of the process starting in a reversible equilibrium, the probability of what you see does not change if you watch the movie backwards.

Given the probability distribution $\Pr(.|D)$, how can we construct a Markov chain that converges against it?

One possibility: Metropolis-Hastings

Given current state $X_i = x$ propose y with Prob. $Q(x \to y)$ Accept proposal $X_{i+1} := y$ with probability

$$\min\left\{1, \frac{Q(y \to x) \cdot \Pr(y \mid D)}{Q(x \to y) \cdot \Pr(x \mid D)}\right\}$$

otherwise $X_{i+1} := X_i$

(All this also works with continuous state space, with some probabilities replaced by densities.)

Why Metropolis-Hastings works

Let's assume that $\frac{Q(y \to x) \cdot \Pr(y \mid D)}{Q(x \to y) \cdot \Pr(x \mid D)} \leq 1$. (Otherwise swap x and y in the following argument). Then, if we start in x, the probability $Pr(x \to y)$ to move to y (i.e. first propose and then accept this) is

$$Q(x \to y) \cdot \frac{Q(y \to x) \cdot \Pr(y \mid D)}{Q(x \to y) \cdot \Pr(x \mid D)} = Q(y \to x) \frac{\Pr(y \mid D)}{\Pr(x \mid D)}$$

If we start in y, the probability $Pr(y \to x)$ to move to x is

$$Q(y \to x) \cdot 1$$
,

since our assumption implies $\frac{Q(x \to y) \cdot \Pr(x \mid D)}{Q(y \to x) \cdot \Pr(y \mid D)} \ge 1$. This implies that the reversibility condition

$$\Pr(x \mid D) \cdot \Pr(x \to y) = \Pr(y \mid D) \cdot \Pr(y \to x)$$

is fulfilled. This implies that Pr(. | D) is an equilibrium of the Markov chain that we have just constructed, and the latter will converge against it. (let's watch a simulation in R)

Applying Metropolis-Hastings

- You are never in equilibrium (your target distribution), but you can get close if you run enough steps.
- You can take more than one sample from the same chain, but you should run enough steps between the sampling steps to make the sampled objects only weakly dependent.
- Your initial state may be "far from equilibrium" (i.e. very improbable). So you should run the chain long enough before you start sampling ("burn-in").

Lamarc's Metropolis-Hastings step

Target distribution density: $p_{\Theta}(G|D)$, where Θ is the current set of parameter values, G is the genealogy and D is the data.

Proposal chain: Remove a randomly picked branch and let the ancestral lineage of the isolated subtree coalesce with the rest accoring to Θ .

$$\frac{Q(G' \to G)}{Q(G \to G')} = \frac{p_{\Theta}(G)}{p_{\Theta}(G')}$$

 \Rightarrow The MH acceptance probability is:

 \Rightarrow

$$\min\left\{1, \frac{Q(G' \to G) \cdot p_{\Theta}(G'|D)}{Q(G \to G') \cdot p_{\Theta}(G|D)}\right\} = \min\left\{1, \frac{p_{\Theta}(G) \cdot p_{\Theta}(G', D)/Pr(D)}{p_{\Theta}(G') \cdot p_{\Theta}(G, D)/Pr(D)}\right\}$$

$$= \min\left\{1, \frac{p_{\Theta}(G) \cdot \Pr(D|G') \cdot p_{\Theta}(G')}{p_{\Theta}(G') \cdot \Pr(D|G) \cdot p_{\Theta}(G)}\right\}$$

$$= \min\left\{1, \frac{\Pr(D|G')}{\Pr(D|G)}\right\}$$

How to compute Pr(D|G)? Felsenstein's pruning!

We assume that all sites evolve independent of each other. \Rightarrow

$$\Pr(D|G) = \prod_{i} \Pr(D_i|G),$$

where D_i is the *i*-th column in the alignment.

How to compute $\Pr(D_i|G)$? For any nucleotides (or amino acids) x, y let p_x be the frequency of x and $\Pr_{x \to y}(\ell)$ be the probability that a child node has type y, given that the parent node had type x and the branch between the two nodes has length ℓ . Let's first assume that D_i knows the nucleotides at the inner nodes of G:



Jukes-Cantor model for DNA evolution

- All nucleotide frequencies are $p_A = p_C = p_G = p_T = 0.25$.
- "mutation events" happen at rate λ and let the site forget its current type and select a new one randomly from {A,C,G,T}. (New one can be the same as old one.)

$$\Rightarrow$$

$$\Pr_{x \to y}(\ell) = \begin{cases} = (1 - e^{-\lambda\ell}) \cdot \frac{1}{4} & \text{if } x \neq y \\ = e^{-\lambda\ell} + (1 - e^{-\lambda\ell}) \cdot \frac{1}{4} & \text{if } x = y \end{cases}$$

(More sophisticated sequence evolution models in the phylogenetics part of the lecture.)

Felsenstein's pruning algorithm

How to compute $\Pr(D_i|G)$ if (as usual) the data do only contain the nucleotides for the tips of the tree?

For any node k of the genealogy and any nucleotide (or amino acid) x define $w_k(x)$ to be the probability that, given the nucleotide (or a.a.) in k is x, the tipps that stem from k get the nucleotides (or a.a.) given in D_i . Then

$$\Pr(D_i|G) = \sum_{x \in \{A,C,G,T\}} p_x \cdot w_r(x),$$

where r is the root of the genealogy, and for any node k with child nodes i and j and corresponding branch lengths ℓ_i and ℓ_j we get:

$$w_k(x) = \left(\sum_{y \in \{A, C, G, T\}} \Pr_{x \to y}(\ell_i) \cdot w_i(y)\right) \cdot \left(\sum_{z \in \{A, C, G, T\}} \Pr_{x \to y}(\ell_j) \cdot w_j(z)\right)$$

Felsenstein's pruning algorithm

If b is a tip of G, then $w_b(x)$ is 1 if x is the nucleotide at b in D_i , and $w_b(x)$ is 0 otherwise.

With the recursion for $w_k(x)$ given above, we can compute $w_k(x)$ for all x and all k starting with the tips and ending in the root r.

From the $w_r(.)$ we can compute $\Pr(D_i|G)$.

Ancestral Recombination Graph



When recombination occurs, ancestral lineages for the left and the right part of the sequence split up. Each site has a tree-shaped ancestry, and these trees have complex stochastic dependencies. LAMARC can also sample Ancestral Recombination Graphs instead of trees.

References

- I. J. Wilson, D. J. Balding (1998) Genealogical inference from microsatellite data. Genetics 150: 499-510
 - assign data to inner nodes
 - when choosing new parent node take mutation probs into account
 - more intelligent proposals but larger state space
 - may be superior for microsatellite data

LAMARC Search Strategies

initial chains: several short chains to optimize driving values

final chain: longer chain to narrow the final interval

burn-in: discard e.g. first 5% of each chain

symptom of too few chains: parameters are still changing directionally

symptom of too short chains: parameters leap wildly from chain to chain



$(MC)^3 = MCMCMC$

=Metropolis-Coupled MCMC= MCMC with "heated chains".

If $\beta_i \in (0,1]$ is heat parameter for chain *i*, then chain *i* samples from distribution $p^{\beta_i} : x \mapsto \beta_i$ $p^{\beta_i}(x)$ const, with $\beta_1 = 1$.

The usual MH acceptance prob. for chain i is

$$\min\left\{1, \frac{p(y)^{\beta_i}}{p(x)^{\beta_i}} \cdot \frac{Q_{y \to x}}{Q_{x \to y}}\right\}.$$

Sometimes a swap between the current state x_i of chain i and the current state x_j of chain j is proposed. The acceptance with probability

$$\min\left\{1, \frac{p(x_i)^{\beta_i}}{p(x_j)^{\beta_i}} \cdot \frac{p(x_j)^{\beta_j}}{p(x_i)^{\beta_j}}\right\}$$

fulfills the requirements of both chaines (check this!).

Bayesian Lamarc

Aim: sample parameter values Θ (and Genealogies) according to the posterior probability distribution $\Pr(\Theta|D)$ (or $\Pr(\Theta, G|D)$) given the data D.

- needs priors $Pr(\Theta)$ for the parameters
- Gibbs sampling scheme: iterate uptdate of the Θ , given D and G, and update of G, given Θ and D.

Gibbs samping

Assume we want to sample from a joint distribution Pr(A = a, B = b) of two random variables, and for each pair of possible values (a, b) for (A, B) we have Markov chains with transition probabilities $P_{b \to b'}^{(A=a)}$ and $P_{a \to a'}^{(B=b)}$ that converge against $\Pr(B = b|A = a)$ and $\Pr(A = a|B = b)$. Then, any Markov chain with transition law

$$P_{(a,b)\to(a',b')} = \begin{cases} \frac{1}{2} P_{a\to a}^{(B=b)} + \frac{1}{2} P_{b\to b}^{(A=a)} & \text{if} \quad a = a' \quad \text{and} \quad b = b' \\\\ \frac{1}{2} P_{a\to a'}^{(B=b)} & \text{if} \quad a \neq a' \quad \text{and} \quad b = b' \\\\ \frac{1}{2} P_{b\to b'}^{(A=a)} & \text{if} \quad a = a' \quad \text{and} \quad b \neq b' \\\\ 0 & \text{else} \end{cases}$$

Priors in Bayesian Lamarc

When new values for Θ are to be proposed,

- e.g. the new values of θ and the recombination rate are chosen according to a exponential prior that is uniform on the log scaled interval $[10^{-5}, 10]$ and the
- growth rate g is chosen uniformly from [-500, 1000].
- For the MH acceptance step use a U that is uniform on [0, 1] and accept if



8 IM, IMa, IMa2

References

- Nielsen, R. and J. Wakeley 2001. Distinguishing migration from isolation: a Markov chain Monte Carlo approach. *Genetics* 158:885-896
- [2] Hey, J., and R. Nielsen. 2004. Multilocus methods for estimating population sizes, migration rates and divergence time, with applications to the divergence of Drosophila pseudoobscura and D. persimilis. *Genetics* 167:747-760
- [3] Hey, J., and R. Nielsen. 2007. Integration within the Felsenstein equation for improved Markov chain Monte Carlo methods in population genetics. PNAS 104:27852790.
- [4] Hey J. 2010. Isolation with Migration Models for More Than Two Populations. Mol Biol Evol 27: 905-20



Asymptotics and rescaled parameters:

$$N_i \rightarrow \infty \qquad 2N_i m_i \rightarrow M_i$$

$$N_2/N_1 \rightarrow r \qquad 4N_1 \mu \rightarrow \theta$$

$$N_A/N_1 \rightarrow a \qquad t/(2N_1) \rightarrow \tau$$

$$\Theta = (\theta, r, a, \tau, M_1, M_2)$$

IM is an implementation of a Bayesian sampler with flat priors, e.g.

$$\begin{array}{rcl} M_i & \sim & {\sf Unif}([0,10]), & \tau & \sim & {\sf Unif}([0,10]) \\ \log(r) & \sim & {\sf Unif}([-10,10]), & & \log(a) & \sim & {\sf Unif}([-10,10]) \end{array}$$

Proposals G^* for genealogy updates like in Lamarc with MH acceptance probability

$$\min\left\{1, \frac{\Pr(D|\Theta_i, G^*)}{\Pr(D|\Theta_i, G_i)}\right\},\,$$

where G_i is the current genealogy and Θ_i is the current vector of parameter values in MCMC step *i*.

Proposals for parameter updates: Given the current value λ of some parameter, the new value is proposed from $\text{Unif}[\lambda - \Delta, \lambda + \Delta]$. MH acceptance probability:

$$\min\left\{1, \frac{p(G_i|\Theta^*)}{p(G_i|\Theta_i)}\right\}$$

IM can handle datasets of unlinked loci (but NO intralocus-recombination!).

 $D = (D^1, \ldots, D^n), D^i$: data from locus *i*. $G = (G^1, \ldots, G^n), G^i$: genealogy of locus *i* (including topology, branch lengths, migration times, coalescent times)

$$p(\Theta|D) = \frac{p(\Theta)}{\Pr(D)} \cdot \prod_{i=1}^{n} \int_{G^{i}} \Pr(D^{i}|G^{i}, \Theta) \cdot p(G^{i}|\Theta) dG^{i}$$

additional parameters: locus-specific mutation scalars u_i with constraint $\prod_i u_i = 1$. Updating (u_1, \ldots, u_n) : choose *i* and *j* and propose

$$u_i^* = x \cdot u_i$$
 and $u_j^* = u_j/x$,

where $\log(x) \sim \text{Unif}(-\delta, \delta)$.

In IMa, some MCMC steps are replaced by faster numerical computation. We discuss this first in a 1-population model with sample size m.

- Let τ_k be the time while the number of lineages is k, measured in $1/\mu$ generations.
- \Rightarrow coalescence rate is $2/\theta$
- $\Rightarrow p(G|\Theta) = \left(\frac{2}{\theta}\right)^{m-1} \cdot \exp(-2 \cdot f_m/\theta),$
- where $f_m := \sum_{i=2}^m \tau_i \cdot i \cdot (i-1)$

Assume a flat prior $\theta \sim \mathsf{Unif}(0, \theta_{max})$. This implies

$$p(G) = \int_0^{\theta_{\max}} p(\theta) \cdot p(G|\theta) d\theta = \frac{2}{\theta_{\max} f_m^{m-2}} \cdot \Gamma(m-2, 2f_m/\theta_{\max}),$$

where $\Gamma(a,b) = \int_b^\infty x^{a-1} e^{-x} dx$ is the "incomplete Gamma-function".

This implies

$$p(\theta|G) = \frac{p(G|\theta) \cdot p(\theta)}{p(G)} = \frac{\left(2f_m/\theta\right)^{m-2} \exp\left(-2f_m/\theta\right)}{\theta \cdot \Gamma(m-2, 2f_m/\theta_{\max})}$$

Hence, given f_m , the posterior probability can be computed and the expression above gives a smooth curve.

- works in a similar way for models with subpopulations with migration
- for the split time τ a standard MH step is required
- population growth not allowed in IMa (other than IM)
- "branch sliding" proposals for G: move randomly chosen branch a random distance. Current migration events are removed and replaced by a Poisson number of migration events conditioned on odd or even.

Likelihood Ratio Testing with IMa

Let

 $\widehat{\Theta}_0 = \arg \max p(\Theta|D)$ in the general model

and

 $\widehat{\Theta}_r = \arg \max p(\Theta|D)$ in a restricted model, e.g. without migration.

Since we use uniform priors for all parameters (some log-scaled), we get

$$\frac{p(\Theta_0|D)}{p(\Theta_r|D)} = \frac{\Pr(D|\Theta_0) \cdot p(\Theta_0)}{\Pr(D|\Theta_r) \cdot p(\Theta_r)} = \frac{L_D(\Theta_0)}{L_D(\Theta_r)}$$

Hence, $\widehat{\Lambda} = \log\left(\frac{\widehat{p}(\Theta_0|D)}{\widehat{p}(\Theta_r|D)}\right)$ is an approximation of the log likelihood-ratio and thus, $2\widehat{\Lambda}$ is approximately χ^2_d -distributed under the null hypothesis of the restricted model, where d is the number of additional parameters in the general model. However, this approximation is only appropriate for extremely large datasets. IMa assesses the significance of $\widehat{\Lambda}$ by comparing it to values of $\widehat{\Lambda}$ from simulations based on the null hypothesis (restricted model).

Bayes factors

Other authors use so-called Bayes factors to decide between two models M_1 and M_2 :

$$B_{M_1,M_2} = \frac{\Pr(D|M_1)}{\Pr(D|M_2)},$$

where

$$Pr(D|M) = \int p(D, \Theta|M) d\Theta$$
$$= \int Pr(D|M, \Theta) \cdot p(\Theta|M) d\Theta$$
$$\approx \left(\frac{1}{m} \sum_{j=1}^{m} \frac{1}{Pr(D|\Theta_j, M)}\right)^{-1}$$

where $\Theta_1, \ldots, \Theta_m$ are the samples from an MCMC run.

Why harmonic mean estimator for Pr(D)?

Let $\theta_1, \ldots, \theta_m$ be (approx.) independent samples according to $p(\theta|D)$. Then,

$$1 = \int p(\theta) d\theta \approx \frac{1}{m} \sum_{i=1}^{m} \frac{p(\theta_i)}{p(\theta_i|D)} \quad \text{(importance sampling)}$$
$$= \frac{1}{m} \sum_{i=1}^{m} \frac{p(\theta_i)}{\frac{\Pr(D|\theta_i) \cdot p(\theta_i)}{\Pr(D)}} \quad \text{(Bayes formula)}$$
$$= \Pr(D) \cdot \frac{1}{m} \sum_{i=1}^{m} \frac{1}{\Pr(D|\theta_i)}.$$

$$\Rightarrow$$

$$\Pr(D) \approx \frac{1}{\frac{1}{m} \sum_{i=1}^{m} \frac{1}{\Pr(D|\theta_i)}}$$

Advantages of Bayes factors:

- can also support the restriced model while tests can only support the general model by statistically rejecting the restricted one.
- can also compare non-nested models

Problems:

- Prior has influence even for large amount of data
- harmonic mean estimator can have infinite variance (more sophisticated methods exist)
- Tests and Bayesian model selection can lead to opposite results (Lindley's paradox).

9 Approximate Bayesian Computation (ABC)

Problems of full-data methods:

- usual runtime for one dataset: several weeks or months
- complex software, development takes years
- most programs not flexible, hard to write extensions

References

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Pritchard et al. (1999)

- Compute MRCA of human Y chromosome in population models with growth.
- Find strong signal of population expansion in all populations.
- Explanations: recent expansion from a small ancestral population in the last 120,000 years or natural selection on the Y chromosome.
- data: 8 microsatellite loci from 445 humans
- Try various microsatellite mutation models
- Use summary statistics:
 - 1. mean accross loci in the variance of repeat numbers
 - 2. mean effective heterozygosity
 - 3. number of distinct haplotypes

Pritchard et al. (1999)

Approximate Bayesian Computation

- 1. Select summary statistics $S = (S_i)_i$ and compute their values $s = (s_i)_i$ for given data set
- 2. Choose tolerance δ
- 3. repeat until k accepted parameter combinations Θ' :
 - (a) Simulate Θ' from prior distribution of Θ
 - (b) Simulate genealogy G according to $Pr_{\Theta'}(G)$.
 - (c) Simulate data and compute values s' of S
 - (d) accept Θ' if $||s s'|| \le \delta$

Only possible if a few summary statistics suffice. Otherwise acceptance will be rare. Ideas of Beaumont, Zhang, Balding (2002):

• combine ABC with local regression:



• Accept in a wider range but put a smaller weight on s' if |s - s'| is large.



Epanechnikov-Kernel

$$K_{\delta}(t) = \begin{cases} c \cdot \left(1 - \left(\frac{t}{\delta}\right)^2\right) / \delta & \text{for} \quad t \le \delta \\ 0 & \text{for} \quad t > \delta \end{cases}$$

where c is a the normalizing constant:

$$c = 1 \left/ \int_{-\delta}^{\delta} \left(1 - \left(\frac{x}{\delta}\right)^2 \right) / \delta \, dx \right.$$



Epanechnikov-Kernels with

 $\delta = 1$ and $\delta = 2$

Beaumont, Zhang, Balding (2002)

Simulate pairs $(\Theta^{(i)}, s^{(i)})$ and fit local regression model, i.e. find α and β to minimize

$$\sum_{i} \left(\Theta^{(i)} - \alpha - (s^{(i)} - s)^T \beta \right)^2 \cdot K_{\delta}(\|s^{(i)} - s\|),$$

where $||v|| = \sqrt{\sum_i v_i^2}$ (or some other vector norm). Consider

$$\Theta_*^{(i)} = \Theta^{(i)} - (s^{(i)} - s)^T \hat{\beta}$$

as random sample from $\Pr(\Theta \mid S = s)$.

Posterior density estimation:

$$\widehat{p}(\Theta_0 \mid S = s) = \frac{\sum_i K_\Delta(\Theta_*^{(i)} - \Theta_0) \cdot K_\delta(\|s - s^{(i)}\|)}{\sum_j K_\delta(\|s - s^{(j)}\|)}$$

where $\Delta = \text{density estimation bandwidth}$.

Solution of the local regression problem

 $\Theta^{(j)} = \begin{pmatrix} \Theta_1^{(j)} \\ \Theta_2^{(j)} \\ \vdots \\ \Theta_m^{(j)} \end{pmatrix}$: Values of the *j*-th parameter from *m* simulations, Solution for *j*-th parameter: $(\widehat{\alpha}, \widehat{\beta_1}, \dots, \widehat{\beta_k}) = (X^T W X)^{-1} X^T W \Theta^{(j)}$, where $s = (s^{(1)}, \ldots, s^{(k)})$: Vector of summary statistics for observed data, $s = (s^{(1)}, \dots, s^{(n)}): \text{ Vector of summary statistics for observed data,} \\ s_i = (s^{(1)}_i, \dots, s^{(k)}_i): \text{ Vector of summary statistics from } i\text{-th simulation,} \\ X = \begin{pmatrix} 1 & s^{(1)}_1 - s^{(1)} & \cdots & s^{(k)}_1 - s^{(k)} \\ 1 & s^{(1)}_2 - s^{(1)} & \cdots & s^{(k)}_2 - s^{(k)} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & s^{(1)}_m - s^{(1)} & \cdots & s^{(m)}_m - s^{(k)} \end{pmatrix} \text{ and} \\ W \text{ is diagonal matrix with diagonal entries } K_{\delta}(||s_1 - s||), \dots, K_{\delta}(||s_m - s||).$

Beaumont, Zhang, Balding (2002)

ABC with local regression

- 1. Select summary statistics $S = (S_i)_i$ and compute their values $s = (s_i)_i$ for given data set
- 2. Choose tolerance δ and bandwidth Δ
- 3. repeat for i = 1, ..., m:
 - (a) Simulate $\Theta^{(i)}$ from prior distribution of Θ
 - (b) Simulate genealogy G according to $Pr_{\Theta^{(i)}}(G)$.
 - (c) Simulate data and compute values $s^{(i)}$ of S

4.
$$(\widehat{\alpha}, \widehat{\beta}) = \arg\min_{\alpha, \beta} \sum_{i=1}^{m} \left(\Theta_i - \alpha - (s^i - s)^T \beta \right)^2 \cdot K_{\delta}(||s^i - s||)$$

5. $\Theta_*^{(i)} := \Theta^{(i)} - (s^{(i)} - s)^T \widehat{\beta}$

6. Approximate $p(\Theta|S = s)$ by

$$\frac{\sum_{i} K_{\Delta}(\Theta_*^{(i)} - \Theta) \cdot K_{\delta}(\|s - s^{(i)}\|)}{\sum_{i} K_{\delta}(\|s - s^{(j)}\|)}$$

Summary statistics used by Beaumont et al. (2002) for microsatellite data:

- 1. mean accross loci in the variance of repeat numbers
- 2. mean effective heterozygosity
- 3. number of distinct haplotypes
- 4. mean accross loci of kurtosis of repeat numbers
- 5. variance accross loci of variance of repeat numbers
- 6. mean accross loci of maximum allele-frequency
- 7. multivariate kurtosis
- 8. linkage disequilibrium (LD) measured with Hudson's Δ^2

Marjoram et al. (2003) MCMC without likelihoods

Aim: For given data D with summary statistics S = s sample paramter vectors according to $p(\Theta \mid ||S - s|| \le \varepsilon)$.

- 1. If current parameter estimation is Θ' , propose Θ^* with probability $Q_{\Theta'\to\Theta^*}$
- 2. Simulate data D^* according to Θ^* and compute their summary statistics s^* .
- 3. If $||s^* s|| > \varepsilon$ reject proposal, else accept with probability

$$\min\left\{1, \frac{p(\Theta^*) \cdot Q_{\Theta^* \to \Theta'}}{p(\Theta') \cdot Q_{\Theta' \to \Theta^*}}\right\}.$$

4. repeat steps 1 to 4.

Application example: Nuu Chah Nulth data, n=63 samples of HVR-I.

Estimate θ and time to the MRCA based on F84 substitution model.

Summary statistics: number of variable sites and number of haplotypes.

Simple approach: when updating parameters, generate entirely new tree. (will usually be rejected \rightsquigarrow inefficient.)

Compromise: keep some information about the tree an modify it slightly for next step:

- 1. tree topology
- 2. times of coalescence events
- 3. number of mutations between two coalescents events

Beaumont, Zhang, Balding (2002)

- "[...] the MCMC-based method is consistently superior to the summary-statistics-based methods and highlights that it is well worth making the effort to obtain full-data inferences if possible."
- "[...] there are advantages to the use of summary statistics, both in the ease of implementation and in the time to obtain the results [...]"

"Further research is needed to find a more rigorous way for choosing summary statistics, including the use of orthogonalization and 'projection-pursuit' methods"

Wegmann et al. (2009)



ABC estimations with microsatellite data.

Wegmann et al. (2009)

- combine MCMC-ABC with Beaumont et al.'s regression approach to sample from $p(\Theta |||S-s|| \le \varepsilon)$.
- apply Box-Cox transformation to each summary statistic with respect to the parameter of interest, based on simulated data
- apply partial least squares (PLS) to find combinations of summary statistics that are informative wrt the parameter of interest

• leave-one-out cross validation to optimize number of PLS components used

Simulation studies show improvements compared to other ABC methods but IMa is still better.

Wegmann et al. "[..] would not recommend using an ABC approach if a full-likelihood method exists [..]".

Box-Cox transformation

$$X^{(\lambda)} = \begin{cases} \frac{(X+c)^{\lambda}-1}{\lambda} & \text{for } \lambda \neq 0\\ \\ \ln(X+c) & \text{for } \lambda = 0 \end{cases}$$

Idea: fit λ and c such that the residuals of the regression model $Y = \alpha + \beta X$ look as normally distributed as possible.

Comparison PCA vs. PLS

Let S be the covariance matrix of the vectors x_1, \ldots, x_n (with $x_i = (x_{i1}, \ldots, x_{im})$) that are normalized, that is $\mu_{x_i} = 0$ and $\sigma_{x_i} = 1$. Then, the principal component directions v_1, \ldots, v_m satisfy:

$$v_j = \arg \max_{\alpha} \left\{ \operatorname{Var}\left(\sum_i x_i \alpha_i\right) \mid ||\alpha|| = 1, \forall_{\ell < j} \ v_{\ell}^T S \alpha = 0 \right\}$$

The PLS directions $\varphi_1, \ldots, \varphi_m$ satisfy: $\varphi_j = \arg \max_{\alpha} \left\{ \operatorname{Cor}^2(y, \sum_i x_i \alpha_i) \operatorname{Var}(\sum_i x_i \alpha_i) \mid ||\alpha|| = 1, \forall_{\ell < j} : \varphi_\ell^T S \alpha = 0 \right\} = \arg \max_{\alpha} \left\{ \operatorname{Cov}^2(y, \sum_i x_i \alpha_i) \mid ||\alpha|| = 1, \forall_{\ell < j} : \varphi_\ell^T S \alpha = 0 \right\}$ are maximum and the set of the condition $v_\ell^T S \alpha = 0$ just means that the new vector $\sum_j \alpha_j \cdot x_j$ ist orthogonal on the set of the condition of the condition of the set of the condition of the condition of the condition of the set of the condition of the set of the condition of the

previous ones $\sum_k v_{\ell,k} x_k$ (for any $\ell < j$).

To see this, note that from $\mu_{x_k} = 0 = \mu_{x_j}$ follows

$$S_{(k,j)} = \text{Cov}(x_k, x_j) = \frac{1}{m-1} \sum_{i} (x_{ki} - \mu_{x_k}) \cdot (x_{ji} - \mu_{x_j}) = \frac{\sum_{i} x_{ki} x_{ji}}{m-1}$$

and thus

$$v_{\ell}^{T}S\alpha = \sum_{k,j} v_{\ell,k} \frac{\sum_{i} x_{ki} x_{ji}}{m-1} \cdot \alpha_{j} = \frac{1}{m-1} \left\langle \sum_{k} v_{\ell,k} x_{k} , \sum_{k} \alpha_{j} x_{j} \right\rangle.$$

(Remember that the scalar product $\langle v, w \rangle = \sum_{i} v_i w_i$ of two vectors v and w has the geometric interpretation $\langle v, w \rangle = ||v|| \cdot ||w|| \cdot \cos(\gamma)$, where γ is the angle between the vectors. Thus, $\langle v, w \rangle = 0$ holds if and only if v and w are orthogonal on each other.)

The scalar product will also be useful on the next slide, on which the algorithm to compute PLS is shown.

The slope of a regression line with response variable y and explanatory variable x (both of length m) can be expressed as

$$b = \operatorname{Cov}(x, y) / \sigma_x^2$$

and the intercept is $a = \mu_y - b \cdot \mu_x$.

If y is centered and x is normalized such that $\mu_x = \mu_y = 0$ and $\sigma_x = 1$, we obtain the regression line

$$y = a + bx = 0 + \frac{\operatorname{Cov}(x, y)}{1}x = \frac{\sum (x_i - \mu_x)(y_i - \mu_y)}{m - 1}x$$
$$= \frac{\sum x_i y_i}{m - 1}x = \frac{\langle x, y \rangle}{m - 1}x.$$

partial least squares (PLS)

Aim: find combinations of explanatory variables x_1, \ldots, x_m that have highest covariance with variable y.

let y be centered and x_j be normalized, i.e. $\mu_y = 0$, $\mu_{x_j} = 0$, $\sigma_{x_j} = 1$.

- 1. ((m-1)-fold of) univariate regression coefficient: $\varphi_j := \langle x_j, y \rangle := \sum_i x_{ji} y_i \qquad \Rightarrow y \approx \frac{1}{m-1} \cdot \varphi_j \cdot x_j$
- 2. first partial least squares direction: $z_1 := \sum_j \varphi_j \cdot x_j$
- 3. first regression coefficient: $\delta := \frac{\langle z_1, y \rangle}{\langle z_1, z_1 \rangle} \implies y \approx \delta \cdot z_1$
- 4. now orthogonalize x_1, x_2, \ldots, x_m with respect to z_1 : $x_j^{(2)} := x_j \frac{\langle z_1, x_j \rangle}{\langle z_1, z_1 \rangle} \cdot z_1$
- 5. and compute the residuals: $y^{(2)} := y \delta \cdot z_1$

repeat 1-5 with x_j and y replaced by $x_j^{(2)}$ and $y^{(2)}$. $\rightsquigarrow z_2, x_j^{(3)}, y^{(3)}$

iterate to get z_1, z_2, \ldots, z_m .

PLS for multiple response variables

Wegmann *et al.* (2009) PLS for multiple response variables (here: summary statistics), implemented in the command plsr in the R package pls.

Several possible generalizations of PLS exist for multiple response variables y_1, \ldots, y_q , e.g. SIMPLS: For all $i = 1, \ldots, m$ let φ_i be the vector α , for which $z_i := x_1 \alpha_1 + \cdots + x_n \alpha_n$ maximizes

$$\sum_{j=1}^{q} \operatorname{Cov}^2(z_i, y_j)$$

subject to the conditions that $||\alpha|| = 1$ and that $\forall_{k < i} : \langle z_i, z_k \rangle = 0$.

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10 Jaatha

10.1 Motivation: Wild Tomatoes

Tomato Data

Solanum peruvianum, Canta, Peru

Solanum chilense, Moquegua, Peru

Complex Demography



Jaatha

JSFS associated approximation of the ancestry

Malayalam word for "past".



Strategy: Compare data to data that has been simulated with various combinations of parameter values.



Demographic Model



Summarizing the JSFS JSFS: n*m-2 classes

How do the 23 summary statistics depend on the parameters? Linearize on each of the 8x8x8 cuboids.

Simple methods in continuous parameter space



How to get from \mathbb{E} to Likelihoods?

Composite Likelihood Approach \Rightarrow 23 summary statistics are independently Poisson distributed.

This means, if s_1, s_2, \ldots, s_{23} are the observed summary statistics and $\lambda_1, \lambda_2, \ldots, \lambda_{23}$ their expectations, the composite likelihood is

$$\frac{\lambda_1^{s_1} \cdot e^{-\lambda_1}}{s_1!} \cdot \frac{\lambda_2^{s_2} \cdot e^{-\lambda_2}}{s_2!} \cdots \frac{\lambda_{23}^{s_{23}} \cdot e^{-\lambda_{23}}}{s_{23}!}$$

Runtime

Given model with 4 parameters and sample sizes for two populations, simulate data and fit local linear models. 3-5 days

Analyse dataset with quick method: 1-3 seconds

Analyse dataset with slow method: 15 minutes

Compromise "J-Med": <15 seconds

L. Naduvilezhath, L. Rose, D. Metzler (2011) Jaatha: A Fast Composite Likelihood Approach to Estimate Demographic parameters. *Molecular Ecology*, **20(13)**: 2709–2723

10.2 Some results for wild tomatoes

Demographic Models





Tomato data: parameter estimations and bootstrap confidence intervals

7 loci, varying from 0.8 to 1.9 kb in size, sampled 23 individuals (i.e. 46 sequences) per species

Parameter	Constant	Growth	Fraction- $Growth$	noMig	fixed Tau
$\widehat{\theta}_1$	9.41	10.30	12.56	13.34	12.22
	(7.14 - 12.59)	(8.29 - 13.02)	(9.61 - 16.38)	(10.29 - 17.35)	(9.37 - 15.09)
\widehat{q}	1.83	4.24	4.29	8.67	4.94
	(1.23 - 2.69)	(2.58-6.95)	(2.71-6.38)	(5.34 - 15.00)	(3.28 - 7.85)
\widehat{m}	0.36	0.36	0.73	0	0.55
	(0.06-4.89)	(0.09-2.34)	(0.39 - 1.27)		(0.22 - 1.03)
$\hat{\tau}$	0.41	0.37	0.79	0.14	0.36
	(0.05 - 1.82)	(0.11 - 0.93)	(0.37 - 1.63)	(0.10 - 0.23)	
\widehat{s}	\widehat{q}	1	0.05	0.44	0.33
				(0.18 - 0.98)	(0.11 - 1.10)
log-likelihood	-189.51	-119.70	-101.58	-133.06	-93.96

Growth model: Tomato estimates vs. simulation study \$A\$ J4–7 Loci

B J4-1000 Loci



parametric bootstrap

- Simulated data according to NoMig model with ML parameter values
- Estimated parameters from simulated data with other models
- Only few (≈ 5 out of 1000) estimated migration rates were as high as for tomato data

• log likelihood-ratios "Mig-NoMig" $<25~({\rm most}<0)$ for simulated data, >30 for tomato data with models "fraction-growth" and "growth"

Jaatha vs. $\partial a \partial i$

References

- R.N. Gutenkunst, R.D. Hernandez, S.H. Williamson, C.D. Bustamante (2009) Inferring the joint demographic history of multiple populations from multidimensional SNP frequency data *PLoS Genetics*
 - also a composite likelihood approach
 - computes expected JSFS by diffusion approximation
 - uses full JSFS
 - is slower than Jaatha but should estimate much more accurately

100 datasets with 100 loci





100 datasets with 7 loci





Jaatha vs. $\partial a \partial i$ vs. IM

Simulation Study

- Growth model, equally-sized founder populations
- 100 loci, no recombination within loci
- $\theta \in [5, 20]$ (per locus)
- size ratio $q \in [0.05, 20]$
- divergence time $\tau \in [0.01, 20]$
- migration rate $m \in [0.05, 5]$
- IM runs for 10 datasets, stopped after 5 weeks





10.3 Jaatha 2.0

Jaatha 2.0

- R package
- Also for more than 4 parameters
- Training data are simulated when needed

Lisha A. Mathew, Paul R. Staab, Laura E. Rose, Dirk Metzler (2013) Why to account for finite sites in population genetic studies and how to do this with Jaatha 2.0. *Ecology and Evolution*



Simulations with 7 or 200 loci

First experiment with infinite-sites model, demographic parameters inspired by tomato data:



Recombination rate between 5 and 20 per locus; 25 sampled sequences per population and locus

Simulation Results with 7 loci



Simulation Results with 200 loci


7 demographic parameters,

- τ_0 very small, suggesting ongoing gene flow
- estimation quite imprecise
- infinite-sites estimation substantially different from finite-sites estimations
- However, gene flow is significant (simulation-based composite-likelihood ratio test)



estimate grey line: finite-sites estimate grey dots: simulation with 7 loci cirles: simulation with 200 loci triangles: τ_m estimated ≥ 15



10.4 Application to NGS data of Arabidopsis thaliana NGS data

- 1.1 million SNPs (after filtering out ambiguous)
- 12 individuals from Spain, 12 from Italy, 5 from Novosibirsk (outgroup)

Model assumptions

- split of southern European populations, constant migration, constant sizes
- Finite-sites, estimate ti/tv
- separately for first or second codon position or UTR (FS), third codon position (Th), and non-coding (NC).

	au	m	α	$ heta_{site}$
complete data set	0.16	3.45	2.87	$3.54 \cdot 10^{-3}$
1^{st} or 2^{nd} codon pos or UTR	0.12	2.81	4.83	$2.73 \cdot 10^{-3}$
$3^{\rm rd}$ codon pos	0.19	3.31	1.53	$3.70 \cdot 10^{-3}$
non-coding	0.18	3.33	2.26	$4.31 \cdot 10^{-3}$

Parameter estimates for A. thaliana using FSM. Jaatha's estimates using the HKY model for the mutation rate θ , time τ of the split of both demes, the subsequent migration rate m between populations, and the rate heterogeneity parameter α . The parameter τ is scaled in $2N_e$ generations, m is twice the number of immigrants to each deme per generation, and θ is $2N_e$ times the mutation rate per base.

Significance of population structure: for 100 simulated panmic tic populations τ was always estimated smaller.

10.5 Microsatellites

Jaatha for microsatellites?



still under development

10.6 Estimating JSFS expectations

Fitting only the middle area



- Keep border as it is
- Use a learning method that depends on the position and the parameters in the middle area

Smooth GLM fit of JSFS



Taking sums



Fitting a function

10.7 Conclusions

Conclusions

- intra-locus recombination difficult to handle rigorosly but allows for composite-likelihood approximations
- more loci needed for getting reasonable estimates
- small datasets require different methods and different sets of summary statistics than large datasets
- not always appropriate to use time-consuming methods for small datasets
- very large datasets can also be analysed with simple methods if not too many parameters to be estimated
- improving choice of summary statistics or smooth estimators for JSFS may be more important than numerics

Next steps

- improve methods to optimize sets of summary statistics or other estimators for for data arrays
- efficient simulator for approximate ancestral recombination graph
- generate Next-Generation Sequencing (NGS) data (with Laura Rose)
- built-in error correction for NGS data
- meta-parameter models for genome-scale data
- find sets of summary statistics to detect balancing selection

11 The program STRUCTURE

examples

References

- M. Linnenbrink, J. Wang, E.A. Hardouin, S. Künzel, D. Metzler, J.F. Baines (2013) The role of biogeography in shaping diversity of the intestinal microbiota in house mice Molecular Ecology 22(7): 1904–1916. (have a look at Fig 1)
- B.M. vonHoldt et al. (2011) A genome-wide perspective on the evolutionary history of enigmatic wolf-like canids Genome Research 21(8): 1294-1305. http://www.ncbi.nlm.nih.gov/pmc/ articles/PMC3149496/figure/F4/



References

- [PSD00] Pritchard, Stephens, Donnelly (2000) Inference of Population Structure Using Multilocus Genotype Data Genetics 155: 945–959
- [FSP03] Falush, Stephens, Pritchard (2003) Inference of Population Structure Using Multilocus Genotype Data: Linked Loci and Correlated Allele Frequencies. Genetics 164: 1567–1587
- [FSP07] Falush, Stephens, Pritchard (2007) Inference of population structure using multilocus genotype data: dominant markers and null alleles. *Mol. Ecol. Notes*
- [HFSP09] Hubisz, Falush, Stephens, Pritchard (2009) Inferring weak population structure with the assistance of sample group information. *Mol. Ecol. Resources* **9**: 1322–1332

11.1 no admixture, no sampling locations

Structure: A program for model-based clustering of genotypes (Microsatellites, SNPS, AFLPs, ...)

N diploid individuals, L loci, K (sub)populations

unknown which individuals belong to which population, even if sampling locations are known, i.e. subpopulations may not correspond to sampling locations.

known is the genotype of individual each i at locus $\ell :$

$$X = (x_{\ell}^{(i,1)}, x_{\ell}^{(i,2)})_{i \le N, \ell \le I}$$

unknown are the populations from which individual i originates:

$$Z = (z^{(i)})_{i < N}$$

and the frequencies of allele j at locus ℓ in population k:

$$P = (p_{k\ell j})_{k \le K, \ell \le L, j \le J_{\ell}}$$

Assumption 1: each population is in Hardy-Weinberg equilibrium

Assumption 2: linkage equilibrium between loci

Bayesian approach: approximate sample from

$$\Pr(Z, P \mid X) \propto \Pr(Z) \cdot \Pr(P) \cdot \Pr(X \mid Z, P)$$

Priors for origin population of individual *i*:

$$\Pr(z^{(i)} = k) = 1/K$$

Dirichlet prior for allele frequencies in each population:

$$p_{k\ell} \sim \mathcal{D}(\lambda_1, \lambda_2, \dots, \lambda_{J_\ell})$$
 with $\lambda_1 = \lambda_2 = \dots = \lambda_{J_\ell} = 1$

(uniform distribution on all distributions)

 $\Pr(X|Z, P)$:

$$\Pr(x_{\ell}^{(i,a)} = j) = p_{z^{(i)}\ell j}$$

Dirichlet distribution If $Y \sim \mathcal{D}(\alpha_1, \dots, \alpha_k)$ then

$$\Pr(Y = (y_1, \dots, y_k)) = c(\alpha) \cdot \prod_{i=1}^k y_i^{\alpha_i - 1}$$

if all $y_i \ge 0$ and $\sum_i y_i = 1$, else 0.

$$\mathbb{E}(Y) = \frac{(\alpha_1, \dots, \alpha_k)}{\sum_i \alpha_i}$$

100 samples from D(10,10,10)

100 samples from D(1,1,1)



Important property of Dirichlet distributions Let $N = (n_1, \ldots, n_K)$ multinomially distributed with (unknown) probabilities $P = (p_1, \ldots, p_K)$, i.e.

$$\Pr(N = (n_1, \dots, n_m)) = \frac{(n_1 + n_2 + \dots + n_k)!}{n_1! \cdot n_2! \cdots n_k!} \prod_{i=1}^k p_i^{n_i}.$$

If the prior distribution of P is $\mathcal{D}(\lambda_1, \ldots, \lambda_k)$, then the posterior distribution of P given $N = (n_1, \ldots, n_k)$ is

$$\mathcal{D}(\lambda_1+n_1,\ldots,\lambda_k+n_k).$$

(Exercise!)

MCMC method for sampling from Pr(Z, P|X): Start with $Z^{(0)}$ (e.g. sampled from prior) and iterate 2 steps for $m = 1, 2, 3, \ldots$:

1. Sample $P^{(m)}$ from $\Pr(P|X, Z^{(m-1)})$

$$p_{k\ell}|X, Z \sim \mathcal{D}(\lambda_1 + n_{k/\ell}, \dots, \lambda_{J_\ell} + n_{k/J_\ell}),$$

where $n_{k/j} = \# \left\{ (i,a) | x_{\ell}^{(i,a)} = j \text{ and } z^{(i)} = k \right\}$. (using the important property of the Dirichlet distribution.)

2. Sample $Z^{(m)}$ from $\Pr(Z|X, Z^{(m-1)}, P^{(m)})$

$$\Pr(z^{(i)} = k | X, P) = \frac{\Pr(x^{(i)} | P, z^{(i)} = k)}{\sum_{k'=1}^{K} \Pr(x^{(i)} | P, z^{(i)} = k')},$$

using $\Pr(x^{(i)}|P, z^{(i)} = k) = \prod_{\ell=1}^{L} p_{k\ell x_{\ell}^{(i,1)}} \cdot p_{k\ell x_{\ell}^{(i,2)}}.$

11.2 with admixture

admixture: present individuals stem from k populations that were admixed recently.

 $\begin{aligned} Q: & \left(q_k^{(j)}\right)_{j \le N, k \le K} = \text{ proportion of individual } j\text{'s genome originating from population } k \\ Z: & \left(z_\ell^{(i,a)}\right) = \text{ population of origin of allele copy } x_\ell^{(i,a)} \end{aligned}$

$$\Pr\left(x_{\ell}^{(i,a)} = j \,\middle|\, Z, P, Q\right) = p_{z_{\ell}, l_{j}}^{(i,a)}, \qquad \Pr\left(z_{\ell}^{(i,a)} = k \,\middle|\, P, Q\right) = q_{k}^{(i)}$$

Prior on Q:

$$q^{(i)} = \left(q_1^{(i)}, \dots, q_k^{(i)}\right) \sim \mathcal{D}(\alpha, \dots, \alpha),$$

where α is also random with prior $\alpha \sim \operatorname{unif}([0, \alpha_{\max}])$.

Note:





[.5cm] Interpretation of bars

without admixture: probabilities of subpopulations to be the origin of individual

with admixture: relative contributions of subpopulations to the genome of the individual

MCMC for case of admixture

Start with initial $P^{(0)}$, $Q^{(0)}$, $Z^{(0)}$ and $\alpha^{(0)}$ and iterate for m = 1, 2, ...:

1. Sample $P^{(m)}$ and $Q^{(m)}$ from $\Pr(P, Q|X, Z^{(m-1)})$:

update $p_{z_{\ell},\ell_i}^{(i,a)}$ based on the number of ℓ copies of type j that come from population k

$$n_{klj} = \left\{ (i,a) | x_{\ell}^{(i,a)} = j \text{ and } z_{\ell}^{(i,a)} = k \right\}$$

and sample $q^{(i)}|X, Z$ according to

$$\mathcal{D}\left(\alpha + \#\left\{(\ell, a) : z_{\ell}^{(i, a)} = 1\right\}, \dots, \alpha + \#\left\{(\ell, a) : z_{\ell}^{(i, a)} = K\right\}\right)$$

2. Sample $Z^{(m)}$ from $\Pr(Z|X, P^{(m)}, Q^{(m)})$ according to:

$$\Pr\left(\left.z_{\ell}^{(i,a)} = k\right|X, P\right) = \frac{q_{k}^{(i)} \cdot p_{k\ell x_{\ell}^{(i,a)}}}{\sum_{h=1}^{K} q_{h}^{(i)} \cdot p_{h\ell x_{\ell}^{(i,a)}}}$$

3. Metroplis Hastings step $\alpha^{(m-1)} \rightsquigarrow \alpha^{(m)}$:

propose $\alpha' \sim \mathcal{N}(\alpha, \text{some } \sigma^2)$, reject immediately if $\alpha' < 0$, else perform MH step.

Inference for Z, P, Q from MCMC samples

for example for Q it seems obvious to estimate

$$\mathbb{E}(q_i|X) \approx \frac{1}{M} \sum_{m=1}^{M} q_i^{(m)},$$

but the theoretical posterior mean is

$$\mathbb{E}(q_i|X) = \left(\frac{1}{K}, \dots, \frac{1}{K}\right)$$

due to symmetries in the model (numbering of populations exchangeable).

 \rightsquigarrow use modes of $\left(q_i^{(1)}, \ldots, q_i^{(M)}\right)_i$ instead of means or use Noah Rosenberg's software CLUMPP to evaluate STRUCTURE output.

Inference for the number K of populations

$$\Pr(K|X) \propto \Pr(X|K) \cdot \Pr(K)$$

can be approximated using the harmonic mean estimator

$$\Pr(X|K) \approx M \left/ \sum_{i=1}^{M} \frac{1}{\Pr\left(X \mid K, Z^{(i)}, P^{(i)}, Q^{(i)}, \alpha^{(i)}\right)} \right.$$

but the harmonic mean estimator is know to be imprecise.

Instead, we hope that $-2\log L(Z, P, Q, \alpha | X)$ is approximately normally distributed and estimate

$$\Pr(X|K) \approx e^{-\widehat{\mu}/2 - \widehat{\sigma}^2/8}$$

with $\widehat{\mu} = \frac{1}{M} \sum_{i=1}^{M} -2 \log \Pr\left(X | Z^{(i)}, P^{(i)}, Q^{(i)}, \alpha^{(i)}\right)$ and $\widehat{\sigma}^2 = \frac{1}{M} \sum_{i=1}^{M} \left(-2 \log \Pr\left(X | Z^{(i)}, P^{(i)}, Q^{(i)}, \alpha^{(i)}\right) - \widehat{\mu}\right)^2$ Pritchard et al. write about this approximation:

"In fact the assumption underlying [this] are dubious at best, and we do not claim (or believe) that our procedure provides a quantitatively accurate estimate of the posterior distribution of K. We see it merely as an ad hoc guide to which models are most consistent to the data, with the main justification being that it seems to give reasonable answers in practice."

and:

"The inferred value of K may not always have a clear biological interpretation."

and about the multiple-modes problem:

"[The] Gibbs-sampler did not manage to move between two modes in any of the runs"

Data examples

Bird example: Without using informations on sampling locations, STRUCTURE gave clear clusters corresponding to sampling locations, up to a few exceptions. Neighbor-Joining results did not show clear clusters when labels were removed.

```
http://www.genetics.org/content/155/2/945/F4.large.jpg
http://www.genetics.org/content/155/2/945/F3.expansion.html
```

Human data: Found $K \ge 2$ corresponding to African and European oringin of samples. Evidence for K > 2 may indicate substructure.

11.3 taking sampling locations into account

First attempt: populations correspond to sampling locations with a few migrants in the last few generations.

g(i): sampling location of individual i

 ν : probability that *i* is immigrant or offspring of an immigrant in the last *G* generations, where *G* is not too large.

$$\Rightarrow q_{a(i)}^{(i)} = 1$$
 with probability $1 - \nu$ and for $t \leq G$:

 $q_{g(i)}^{(i)} = 1 - 2^{-t}$ and $q_j^{(i)} = 2^{-t}$ with probability $\frac{2^t \nu}{(k-1)\sum_{T=0}^{G} 2^T}$ (neglecting the possibility of more than one migranting ancestor in the last G generations.)

in MCMC: sampling of $q^{(i)}$ is conditioned on X and P, and not on X and Z. Falush et al. (2003) allow for LD between loci. Advantages:

- 1. detection of admixture further back into past
- 2. inference of population of origin of chromosomal regions
- 3. more accurate estimate of statistical uncertainty when linked loci are used

Sources of LD:

mixture LD: variation in ancestry among sampled individuals (Prichard et al.)

- admixture LD: correlation of ancestry along each chromosome causes additional LD between linked markers (Falush et al.)
- **background LD:** within population decaying on a much shorter scale, e.g. tens of kb in humans. (not yet in STRUCTURE)

Approach of Falush et al. (2003):

- breakpoints occur as Poisson process at rate r
- uniform prior on $\log(r)$
- use HMM to sample from conditional distribution of Z
- data allowed to be unphased

more options: correlated allele frequencies between populations accordingt to star-shaped phylogeny of populations with drift rates F_1, \ldots, F_K and ancestral allele frequency distribution $p_A \sim \mathcal{D}(\lambda_1, \ldots, \lambda_{J_\ell})$.

$$p_{k\ell.}|p_A \sim \mathcal{D}\left(p_{A\ell 1} \frac{1-F_1}{F_1}, \dots, p_{A\ell K} \frac{1-F_K}{F_K}\right)$$

(be careful with this model!)

Approach of Hubisz et al. (2009): Allow uncertainty in the information about sampling location

$$r \sim \operatorname{unif}([0, r_{\max}]) \quad (\text{informativeness of sampling location})$$

$$q^{(i)} \sim \mathcal{D}(\alpha_{h_1}, \dots, \alpha_{h_K}), \quad \text{if individual } i \text{ comes from location } h$$

$$\alpha_{h_k} \sim \Gamma\left(r \cdot \alpha_k^{\text{glob}}, 1/r\right), \quad (\text{which entails that the mean is } \alpha_k^{\text{glob}})$$

$$\alpha_k^{\text{glob}} \sim \operatorname{unif}(0, \alpha_{\max})$$

Hubisz et al.: "However, we would still encourage users to run the original models as well, and to check that substantial differences between the results from the new and the old models seem biologically sensible."

When STRUCTURE has problems

- number of clusters not well-defined when allele frequencies vary slowly accross the landscape
- inbreeding or relatedness between individuals

In this case, the software INSTRUCT may help, cf.

References

[GWB07] H. Gao, S. Williamson, S.D. Bustamante (2007) An MCMC Approach for Joint Inference of Population Structure and Inbreeding Rates from Multi-Locus Genotype Data. *Genetics (online)*

11.4 Faster alternatives to STRUCTURE for large datasets

11.4.1 ADMIXTURE

ADMIXTURE

- is based on the same modeling approach as STRUCTURE
- (faster) ML optimization instead of Bayesian sampling

References

[GWB07] D.H. Alexander, J. Novembre, K. Lange (2009) Fast Model-Based Estimation of Ancestry in Unrelated Individuals Genome Res. 19: 1655–1664

optimization strategy: similar to Newton's method

Problem: Huge Hesse matrix (2nd derivatives) as there are many parameters.

Q: q_{ik} is proportion of individual *i* genome coming from population *k*

F: $f_{k\ell}$ is the frequency of allele 1 of locus ℓ in population k (assuming two alleles per locus).

 \Rightarrow Many second derivatives

$$rac{\partial^2}{\partial q_{ik}\partial f_{k\ell}}$$

Also the constraints $0 \le f_{kj} \le 1$, $q_{ik} > 0$, $\sum_k q_{ik} = 1$ make optimization a bit tricky.

ADMIXTURE uses Block Relaxation Algorithm

- like Newton method uses first two derivatives
- To optimize L(Q, F) iterate
 - update Q for fixed F
 - update F for fixed Q
- no mixed 2nd derivatives $\frac{\partial^2 L}{\partial q_{ik} \partial f_{k'\ell}}$ needed
- need $\frac{\partial^2 L}{\partial q_{ik} \partial q_{i'k'}}$ only if i = i'.
- need $\frac{\partial^2 L}{\partial f_{k\ell} \partial f_{k'\ell'}}$ only if $\ell = \ell'$.
- optimization problems are convex.

11.4.2 fastSTRUCTURE

fastSTRUCTURE

References

 A. Raj, M. Stephens, J.K. Pritchard (2013) Variational Inference of Population Structure in Large SNP Datasets preprint available on bioRχiv

Variational Distributions: tractable family of distributions to approximate posterior.

Variational Bayesian Inference: Instead of sampling from posterior, optimize parameters of variational distributions

Kullback-Leibler Divergence: (=relative entropy)

$$D_{KL}(q||p) = \mathbb{E}_q \log \frac{q(X)}{p(X)} = \int_x q(x) \log \frac{q(x)}{p(x)} dx$$

Approach: Find variational distribution q that minimizes $D_{KL}(q||p)$ to posterior p.

Unrealistic assumption to make variational distributions q tractable:

Their joint variational distribution density is the product of multinomial probabilities for Z, Dirichlet densities for Q, and beta densities for P.

The parameters of these distributions are optimized.

Also here, the optimization of the parameters of one of distribution, keeping the others fixed, is a convex optimization problem.

12 Phasing genotypes and other applications of Li&Stephens' PAC approach

12.1 Classical methods for phasing

Why phasing?

Many sequence datasets from diploid (polyploid) organisms are *unphased*. For example, it is known that some individual has an A and a T at one locus, and a G and a C at another locus on the same chromosome, but not wheter the A is on the same haplotype (chromosome copy) as the C or as the G.

Estimating this ("phasing the data") can be important, e.g. because Linkage Disequilibrium (LD) is informative about

• population structure

Z, P, and Q

- epistatis
- selective sweeps
- whether a gene locus is associated with a trait of interest or just physically linked to a relevant locus

Clark's Algorithm

- parsimonious approach to minimize the total number of haplotype classes observed in the sample
- greedy algorithm
- starting with individuals that are homozygous at all loci or at all up to one
- successively searches individuals that can be phased such that one or both haplotypes is identical to already inferred one.
- final result depends on input order

12.1.1 Excoffier and Slatkin's EM algorithm

References

[ES95] L. Excoffier, M. Slatkin (1995) Maximum-Likelihood estimation of molecular hyplotype frequencies in a diploid population. *Mol. Biol. Evol.* 12(5): 921–927

"phenotype": multilocus genotype with unknown phase, e.g.

 $genotype = \frac{-0-1-0-1-}{-0-0-1-1-} \implies phenotype = [0,0], [0,1], [0,1], [1,1] \text{ (unordered pair)} \qquad (unordered pair) = [0,0], [0,1], [$

pairs)

 P_i : phenotype probability

 n_i : absolute frequency of phenotype *i* in sample, $n = \sum_i n_i$

$$\Pr(\text{sample}|P_1, P_2, \dots, P_m) = \frac{n!}{n_1! \cdot n_2! \cdots n_m!} \cdot P_1^{n_1} \cdot P_2^{n_2} \cdots P_m^{n_m}$$

one aim:

estimate population frequencies p_1, p_2, \ldots of haplotype classes h_1, h_2, \ldots

Expectation Maximization (EM) algorithm

Iterate E step and M step:

E step Use current estimates of p_1, p_2, \ldots to compute expected frequencies $f_{k\ell}$ of all genotypes (k, ℓ) (with $k \leq \ell$) in the sample, given the sampled phenotypes. For this, let $I_{k\ell,j}$ be the indicator function that $[k, \ell]$ leads to phenotype j (i.e. $I_{kl,j} = 1$ in this case and 0 otherwise), and $\delta_{k\ell}$ be the indicator function of $k = \ell$. Then

$$P_j = \sum_k \sum_{\ell} p_k p_l \cdot I_{k\ell,j}$$

and

$$f_{k\ell} = \sum_{j} I_{k\ell,j} \cdot \frac{n_j}{n} \cdot \frac{p_k p_\ell}{P_j} \cdot (2 - \delta_{k\ell}).$$

M step Use expected genotype frequencies in sample to estimate haplotype class probabilities p_i (=frequencies in population).

$$p_i = f_{ii} + \frac{1}{2} \cdot \left(\sum_{k=1}^{i-1} f_{ki} + \sum_{k=i+1}^{\dots} f_{ik}\right)$$

Excoffier and Slatkin use Fisher Information to estimate variance of the estimators, and use estimated p_i to infer haplotypes.

12.1.2 Excursus: EM algorithm

EM algorithm in general

References

[DLR77] Dempster, A.P., Laird. N.M., Rubin, D.B. (1977) Maximum-Likelihood from incomplete data via the EM algorithm. *Journal of the Royal Statistical Society Series B* **39** (1): 1–38

 \boldsymbol{X} observed data

 ${\cal U}\,$ unobserved data

 $\theta\,$ parameter to be estimated

 $\ell~\log$ likelihood

$$\ell(\theta; x, u) = \log P_{\theta}(X = x, U = u)$$

P Probability or probability density

$$\begin{split} \ell(\theta; u \mid x) &:= \log P_{\theta}(U = u \mid X = x) \\ \Rightarrow \quad \ell(\theta; x, u) &= \ell(\theta; u \mid x) + \ell(\theta; x) \\ U \text{ unobserved } \Rightarrow \quad \ell(\theta; x, U) \text{ is a random variable} \\ Q_{\theta'}(\theta) &:= & \mathbb{E}_{\theta'} \left(\ell(\theta; x, U) | x \right) \\ &= & \sum_{u} P_{\theta'}(u | x) \cdot \ell(\theta; x, u) \\ & \left(\text{or } \int P_{\theta'}(u | x) \cdot \ell(\theta; x, u) \, du \right) \\ C_{\theta'}(\theta) &= & \mathbb{E}_{\theta'} \left(\ell(\theta; U | x) | x \right) \\ & \ell(\theta) &:= & \ell(\theta; x) = & Q_{\theta'}(\theta) - C_{\theta'}(\theta) \end{split}$$

To estimate θ iterate the following steps:

E step with current estimate θ' compute the function $Q_{\theta'}: \theta \mapsto Q_{\theta'}(\theta)$

M step

$$\theta^{new} := \arg\max_{\theta} Q_{\theta'}(\theta)$$

Iterate E step with θ' replaced by θ^{new} .

Note that from

$$\ell(\theta) = Q_{\theta'}(\theta) - C_{\theta'}(\theta)$$

follows that

$$Q_{\theta'}(\theta^{new}) \ge Q_{\theta'}(\theta')$$

implies

$$\ell(\theta^{new}) - \ell(\theta') \geq C_{\theta'}(\theta') - C_{\theta'}(\theta^{new}) \\ = \int P_{\theta'}(U = u|x) \cdot \log \frac{P_{\theta'}(U = u|x)}{P_{\theta^{new}}(U = u|x)} du \geq 0$$

Note that the integral is a Kullback-Leibler Divergence and therefore allways ≥ 0 , and = 0 only if the two distributions are equal.

Therefore, an EM step will never decrease the likelihood (which is not true, e.g., for Newton optimization steps).

Why is Excoffier and Slatkin's EM algorithm a special case of this?

x "phenotypes"

U genotypes

 θ haplotype frequencies p_1, p_2, \ldots

$$\mathbb{E}_{\theta'}(\ell(\theta; x, U)|x) = ?$$

If the phenotypes x are in accordance with the genotypes u, then

$$\begin{split} \ell(\theta; x, u) &= \log(P_{\theta}(u)) \\ &= \log\left(\frac{n!}{n_{1}! \cdot n_{m}!}\right) + \sum_{i} \log\left(2p_{u(i,1)}p_{u(i,2)} \cdot \left(\frac{1}{2}\right)^{\delta_{u(i,1),u(i,2)}}\right) \end{aligned}$$

$$\begin{aligned} Q_{\theta'}(\theta) &= \mathbb{E}_{\theta'}(\ell(\theta; x, U) | x) \\ &= \log\left(\frac{n!}{n_1! \cdot n_m!}\right) + \\ &\sum_i \mathbb{E}_{\theta'}\left(\log\left(2p_{U(i,1)}p_{U(i,2)} \cdot \left(\frac{1}{2}\right)^{\delta_{U(i,1),U(i,2)}}\right) \middle| x_i\right) \end{aligned}$$

The conditional expectation in the last line is, by definition,

$$\sum_{[k,\ell]\in\mathcal{P}_i} P_{\theta'}(U=[k,\ell]|x_i) \cdot \log\left(2p_k p_\ell \cdot \left(\frac{1}{2}\right)^{\delta_{k\ell}}\right)$$

,

Where the sum is taken over the set \mathcal{P}_i of all (unordered) haplotype pairs $[k, \ell]$ that are in accordance with phenotype i.

With

$$P_{\theta'}(U = [k, l] | x_i) = \frac{2p'_k p'_\ell \cdot 0.5^{\delta_{k,\ell}}}{\sum_{[k', \ell'] \in \mathcal{P}_i} 2p'_{k'} p'_{\ell'} \cdot 0.5^{\delta_{k',\ell'}}},$$

where $\theta' = (p'_1, p'_2, \ldots).$

Putting it all together and rearranging the sums, we obtain

$$Q_{\theta'}(\theta) = \sum_{k} \sum_{i=1}^{n} \frac{p'_{k} \sum_{\ell} I_{k\ell,i} p'_{\ell}}{\sum_{k'} \sum_{\ell'} I_{k'\ell',i} p'_{k'} p'_{\ell'}} \log p_{k} + \text{const.}$$

where const is a term that does not depend on any p_k . Thus, $Q_{\theta'}(\theta)$ is optimized by setting

$$p_k \propto \sum_{i=1}^n \frac{\sum_{\ell} I_{k\ell,i} p'_k p'_l}{\sum_{k'} \sum_{\ell'} I_{k'\ell',i} p'_{k'} p'_{\ell'}}$$

because, in general, the distribution p_1, p_2, \ldots that maximizes $\sum_i n_i \log p_i$ is $p_i = n_i / \sum n_j$. This follows from the information inequality

$$\sum p_i \log p_i > \sum p_i \log q_i,$$

which is equivalent to

$$\sum p_i \log \frac{p_i}{q_i} > 0$$

(always assuming that distributions p and q are not equal).

Note that, indeed,

$$p_k \propto \sum_{i=1}^{n} \frac{\sum_{\ell} I_{kl,i} p'_k p'_l}{\sum_{k'} \sum_{\ell'} I_{k'l',i} p'_{k'} p'_{l'}}$$

is the same as the M step in Excoffier and Slatkin's EM algorithm.

12.1.3 Basic algorithms in PHASE

References

[SSD01] M. Stephens, Smith, P. Donnelly (2001) A New Statistical Method for Haplotype Reconstruction from Population Data The American Journal of Human Genetics 68(4)

 $G = (G_1, \ldots, G_n)$ observed genotypes of n individuals

 $H_i = (h_{i1}, h_{i2})$ unknown (unordered) haplotypes of individual *i*

Gibbs samping with target distribution Pr(H|G): Start with initial guess for H and iterate the following steps.

- choose individual *i* purely randomly from all ambiguous individuals
- sample updated H_i from $\Pr(H_i|G, H_{-i})$, where H_{-i} is H without H_i .

Problem: $Pr(H_i|G, H_{-i})$ depends on genetic and demographic models, e.g. on priors of haplotype frequencies

 $\Pr(H_i|G, H_{-i}) \propto \Pr(H_i|H_{-i}) \propto \Pr(h_{i1}|H_{-i}) \cdot \Pr(h_{i2}|H_{-i}, h_{i1})$

 $Pr(h_{i1}|H_{-i})$ is only easy in parent-independent mutation model, which is usually unrealistic.

Stephens, Smith and Donnelly (2001) discuss two possible approximations, a "naive" one and their preferred one.

The naive Gibbs sampler

assumes parent-independent mutation

$$\Pr(h|H) = \frac{r_h + \theta v_h}{r + \theta}$$

 r_h number of haplotypes of type h in H

r total number of haplotypes in H

 v_h in case of mutation this is the probability that it leads to v_h

 $\theta\,$ population-scaled mutation rate

If individual *i* has *k* heterozygous loci, 2^{k-1} different haplotypes *h* are possible. If this may be to many, just set $v_h = 1/M$, where *M* is the number of possible haplotypes.

The naive algorithm

- 1. pick individual *i* uniformly, let *k* be its number of heterogeneous loci; let $\{h_1, \ldots, h_m\}$ be the other individuals' haplotypes.
- 2. **for** j = 1, ..., m **do**
 - if H_i could be (h_j, h') then if h' is some $h_k \in \{h_1, \dots, h_m\}$ then $p_j = (r_j + \frac{\theta}{M}) (r_k + \frac{\theta}{M}) - (\frac{\theta}{M})^2$ else $p_j = r_j \frac{\theta}{M}$ end if else $p_j = 0$ end if end for
- 3. With prob $\frac{2^k \left(\frac{\theta}{M}\right)^2}{\sum_j p_j + 2^k \left(\frac{\theta}{M}\right)^2}$ reconstruct H_i completely at random. Else: Choose $H_i = (h_j, h')$ with probability $p_j / \sum_k p_k$.

The basic standard algorithm in PHASE

The basic standard algorithm in PHASE uses an approximation proposed by Stephens and Donnelly (2000):

$$\Pr(h|H) \approx \sum_{\alpha} \sum_{s=0}^{\infty} \frac{r_{\alpha}}{r} \left(\frac{\theta}{r+\theta}\right)^s \frac{r}{r+\theta} (P^s)_{\alpha h}$$

 r_{α} number of haplotypes of type α in H

r total number of haplotypes in H

- θ population-scaled mutation rate (see next slide)
- P transition matrix between types, given a mutation happens

s number of mutations

The basic standard algorithm in PHASE

• For polymorphic sites, assume only one mutation happened and set

$$\theta = \frac{1}{\log 2n}$$

- \bullet Problem: For sequence data, P will be huge. In this case use Gaussian quadrature explained in next section.
- For microsatellite data assume a stepwise mutation model with 50 alleles and set

$$\theta_j = \frac{1}{2} \left(\frac{1}{1+\mathcal{H}} - 1 \right),$$

where \mathcal{H} is the observed heterozygousity at that locus.

The basic standard algorithm in PHASE

Start with initial phasing and iterate the following steps

- 1. Choose individual i uniformly
- 2. Select subset S of (e.g. 5) ambiguous loci i
- 3. Phase the loci in S in individual *i* conditioned on the current phase of all other loci and of all loci in the other individuals.

References

[SD03] M. Stephens, P. Donnelly (2003) A comparison of Bayesian Methods for Haplotype Reconstruction from Population Genotype Data Am. J. Hum. Genet. 73: 1162–1169

introduce a few improvements:

- in each step the genomes of all individuals are subdivided into blocks of the same number of loci (6,7, or 8, with probs. 0.3, 0.3, 0.4). Then, a block is chosen for all individuals in random order the loci of this block are updated (conditioned on all other individual and on all other loci in the focal individual).
- in a certain fraction of individuals, it is allowed that only one haplotype is a copy of another haplotype in the data. This fraction is reduced down to 0 during the MCMC procedure.
- After the blockwise MCMC, haplotype fraquencies are estimated for each block and blocks are iteratively ligated with adjacent blocks into larger blocks.

The phasing methods discussed so far are not based on explicit models for recombination. This is done (and added to PHASE) in

References

[SS05] Stephens, Scheet (2005) Accounting for Decay of Linkage Disequilibrium in Haplotype Inference and Missing-Data Imputation Am. J. Hum. Genet. 76:449–462

We will discuss this later as an application of Li and Stephen's PAC methods.

12.2 Li&Stephens' PAC approach

12.2.1 Excursus: Stephens and Donnelly's Importance Sampling

References

[SD00] M. Stephens, P. Donnelly (2000) Inference in molecular population genetics J. R. Statist. Soc. B 62(4):605–655

improved Griffiths und Tavaré's Importance sampling scheme for the case of the classical (unstructured) coalescent.

A history \mathcal{H} is a sequence $(H_{-m}, H_{-(m-1)}, \ldots, H_0)$, where

 H_{-i} is the unorded list of types of the uncestral lineages, *i* events (mutations and coalescent events) before present. Thus,

 H_0 is the sampled data.

 $H_{i-1} = H_i - \alpha + \beta$ stands for a mutation from α to β (back into past; note that i < 0), and

 $H_{i-1} = H_i - \alpha$ for a coalescence of two lineages of type α .

 $P_{\alpha\beta}$ probability that an α that is hit by a mutation becomes a β .

 n_{α} number of lineages in H_{i-1} of type α ,

 $n = \sum_{\alpha} n_{\alpha},$

$$\Pr_{\theta}(H_i \mid H_{i-1}) = \begin{cases} \frac{n_{\alpha}}{n} \cdot \frac{\theta}{n-1+\theta} P_{\alpha\beta} & \text{if} & H_i = H_{i-1} - \alpha + \beta \\ \frac{n_{\alpha}}{n} \cdot \frac{n-1}{n-1+\theta} & \text{if} & H_i = H_{i-1} + \alpha \\ 0 & \text{otherwise} \end{cases}$$

 $\pi_{\theta}(.)$: distribution of genotype vector A_n in a sample of size n. Note that A_n is an ordered list. n_{α} : number of α in H_0

$$\pi_{\theta}(A_n \mid \mathcal{H}) = \pi_{\theta}(A_n \mid H_0) = \begin{cases} (\prod_{\alpha} n_{\alpha}!) / n! & \text{if } H_0 \text{ compatible with} A_n \\ 0 & \text{otherwise} \end{cases}$$

If histories $\mathcal{H}^{(1)}, \mathcal{H}^{(2)}, \ldots, \mathcal{H}^{(M)}$ are generated independently according to the proposal distribution $Q_{\theta_0}(.)$, the importance sampling formula implies:

$$L(\theta) \approx \frac{1}{M} \sum_{i=1}^{M} \pi_{\theta}(A_n \mid \mathcal{H}^{(i)}) \cdot \frac{P_{\theta}(\mathcal{H}^{(i)})}{Q_{\theta_0}(\mathcal{H}^{(i)})}$$

E.g. with the proposal distribution Q_{θ}^{GT} of Griffiths and Tavaré, for given H_0 the histories H_{-1}, H_{-2}, \ldots are generated by a Markov chain with $q_{\theta}(H_{i-1} \mid H_i) \propto p_{\theta}(H_i \mid H_{i-1})$.

Let \mathcal{M} be the class of proposal distributions, for which H_{-1}, H_{-2}, \ldots is Markovian with start in H_0 and

$$\sup\{q_{\theta}(. \mid H_{i})\} := \{H_{i-1} : q_{\theta}(H_{i-1} \mid H_{i}) > 0\} \\ = \{H_{i-1} : p_{\theta}(H_{i} \mid H_{i-1}) > 0\}.$$

Optimal would be $Q^*_{\theta}(\mathcal{H}) = P_{\theta}(\mathcal{H} \mid A_n)$, because

$$\pi_{\theta}(A_n \mid \mathcal{H}) \frac{P_{\theta}(\mathcal{H})}{Q_{\theta}^*(\mathcal{H})} = \frac{P_{\theta}(\mathcal{H} \cap A_n)}{P_{\theta}(\mathcal{H} \mid A_n)} = \pi_{\theta}(A_n) = L(\theta)$$

Theorem 3 Let $\pi_{\theta}(\alpha \mid A_n) = \frac{\pi_{\theta}((A_n, \alpha))}{\pi_{\theta}(A_n)}$ be the conditioned probability that the n + 1-st allele sampled from the population is of type α , given that the first n types are given by A_n . The optimal proposal distribution Q_{θ}^* belongs to \mathcal{M} and is defined by

$$q_{\theta}^{*}(H_{i-1} \mid H_{i}) = \begin{cases} \frac{\theta \cdot n_{\alpha}}{n \cdot (n-1+\theta)} \frac{\pi(\beta \mid H_{i}-\alpha)}{\pi(\alpha \mid H_{i}-\alpha)} P_{\beta\alpha} & f\ddot{u}r \quad H_{i-1} = H_{i} - \alpha + \beta \\ \frac{n_{\alpha} \cdot (n_{\alpha}-1)}{n \cdot (n-1+\theta)} \frac{1}{\pi(\alpha \mid H_{i}-\alpha)} & f\ddot{u}r \quad H_{i-1} = H_{i} - \alpha \end{cases}$$

Proof

Consider the case $H_{i-1} = H_i - \alpha + \beta$

Let $a_k(t)$ be the type of lineage k at time t. Assume $\delta > 0$ and let Y_m be the event that in the last δ time units a mutation from $a_k(t - \delta) = \beta$ to $a_k(t) = \alpha$ occurred.

We obtain:

$$\Pr\{Y_m \cap A_k(t-\delta) = (\alpha_1, \dots, \alpha_{k-1}, \beta) \mid A_k(t) = (\alpha_1, \dots, \alpha_{k-1}, \alpha)\}$$
$$= \frac{\pi(\alpha_1, \dots, \alpha_{k-1}, \beta) \cdot \delta \cdot \theta \cdot P_{\beta\alpha}/2}{\pi(\alpha_1, \dots, \alpha_{k-1}, \alpha)} + o(\delta)$$
$$= \delta \cdot \frac{\pi(\beta \mid A_k - \alpha)}{2\pi(\alpha \mid A_k - \alpha)} \cdot P_{\beta\alpha} + o(\delta)$$

This implies the result if we let δ go to 0, multiply by n_{α} (as instead of α_k any other α could be affected, and H_i is unordered) and divide by the total rate.

The proof for $H_{i-1} = H_i - \alpha$ is analogous.

But:

In general, $\pi(\alpha \mid A_n)$ are hard to compute and we cannot use Q_{θ}^* .

Ansatz: If $\pi(\alpha \mid A_n)$ cannot be calculated, approximate it and use the approximations in the formulas in the theorem.

Definition 1

$$\widehat{\pi}(\beta \mid A_n) := \sum_{\alpha \in E} \sum_{m=0}^{\infty} \frac{n_{\alpha}}{n} \left(\frac{\theta}{n+\theta}\right)^m \cdot \frac{n}{n+\theta} (P^m)_{\alpha\beta}$$

This probability distribution can be approximated as follows: Choose a purely randomly individual from A_n and mutate it according to P geometrically often with parameter $\frac{\theta}{n+\theta}$.

properties of $\hat{\pi}$:

- (a) For parent-independent mutation: $\hat{\pi}(. \mid A_n) = \pi(. \mid A_n)$.
- (b) For reversible P with n = 1: $\hat{\pi}(. | A_n) = \pi(. | A_n)$.
- (c) The distribution $\widehat{\pi}(. \mid A_n)$ fulfills

$$\widehat{\pi}(\beta \mid A_n) = \sum_{\alpha} \frac{n_{\alpha}}{n} M_{\alpha\beta}^{(n)} \qquad (*)$$

for suitable $M^{(n)}$. Thus, it can be simulated by drawing a random lineage and draw the type according to a distribution that depends only on n and on the type of the drawn lineage. (In the case of $\hat{\pi}$ holds $M^{(n)} = (1 - \lambda_n)(I - \lambda_n P)^{-1}$ with $\lambda_n = \frac{\theta}{n+\theta}$.)

more properties of $\hat{\pi}$:

(d) $\hat{\pi}$ is the distribution that fulfills (*) and (b) and

$$\widehat{\pi}(\beta \mid A_n) = \sum_{\alpha} \widehat{\pi}(\alpha \mid A_n) \cdot \widehat{\pi}(\beta \mid (A_n, \alpha)) \qquad (**)$$

This means: Given the first three n, the n + 1st has the same distribution as the n + 2nd.

(e) $\hat{\pi}(. | A_n)$ is the stationary distribution of a Markov chain with transition matrix

 $T_{\alpha\beta} = \frac{\theta}{n+\theta} P_{\alpha\beta} + \frac{n_{\alpha}}{n+\theta}$

Proofs

(a) For parent-independent mutation $P_{\alpha\beta} = P_{\beta}$ holds $P = P^m$ and thus:

$$\pi(\beta \mid A_n) = \frac{n_{\beta} + \theta P_{\beta}}{n + \theta} = \widehat{\pi}(\beta \mid A_n)$$

(b) Let X and Y be the types of the leaves, R the type of the root, m_1 the number of mutations between R und X and m_2 that of the mutation between R and Y. Then:

$$Pr(Y = \beta \mid R = \gamma) = (P^{m_2})_{\gamma\beta}$$

$$Pr(R = \beta \mid X = \alpha) = (P^{m_1})_{\alpha\beta}$$

$$Pr(Y = \beta \mid X = \alpha) = (P^{m_1+m_2})_{\alpha\beta}$$

The total number of mutations between X and Y is geometrically distributed with parameter $\frac{\theta}{1+\theta}$

(c)

$$\widehat{\pi}(\beta \mid A_n) = \sum_{\alpha} \sum_{m=0}^{\infty} \frac{n_{\alpha}}{n} \left(\frac{\theta}{n+\theta}\right)^m \frac{n}{n+\theta} (P^m)_{\alpha\beta}$$
$$= \sum_{\alpha} \sum_{m=0}^{\infty} \frac{n_{\alpha}}{n} (1-\lambda_n) \left[(\lambda_n P)^m \right]_{\alpha\beta}$$
$$= \sum_{\alpha} \frac{n_{\alpha}}{n} (1-\lambda_n) \left[(I-\lambda_n P)^{-1} \right]_{\alpha\beta}$$

The last equation follows from the geometric sum formula of matrices. $\sum_{m=0}^{\infty} M^m = (I - M)^{-1}.$

proof of (d)

Let $\widetilde{\pi}(\beta \mid A_n) = \sum_{\alpha} \frac{n_{\alpha}}{n} M_{\alpha\beta}^{(n)}$ for some $M_{\cdots}^{(.)}$ fulfilling (**):

$$\begin{split} \left(\frac{n_{\alpha}}{n}, \frac{n_{\beta}}{n}, \dots, \frac{n_{\gamma}}{n}\right) \cdot M_{\alpha\beta}^{(n)} &= \tilde{\pi}(\beta \mid A_n) \\ &= \sum_{\alpha} \tilde{\pi}(\alpha \mid A_n) \tilde{\pi}(\beta \mid (A_n, \alpha)) \\ &= \sum_{\alpha} \sum_{\gamma} \frac{n_{\gamma}}{n} M_{\gamma\alpha}^{(n)} \cdot \sum_{\xi} \frac{n_{\xi} + \delta_{\alpha\xi}}{n+1} M_{\xi\beta}^{(n+1)} \\ &= \sum_{\gamma} \sum_{\xi} \left(\frac{n_{\gamma}}{n} \frac{n_{\xi}}{(n+1)} M_{\xi\beta}^{(n+1)} + \frac{n_{\gamma}}{n \cdot (n+1)} M_{\gamma\xi}^{(n)} M_{\xi\beta}^{(n+1)}\right) \\ &\quad (\text{denn } \forall \gamma : \sum_{\alpha} M_{\gamma\alpha}^{(n)} = 1) \\ &= \frac{1}{n+1} \left[\left(\frac{n_{\alpha}}{n}, \dots, \frac{n_{\gamma}}{n}\right) \cdot \left(n M^{(n+1)} + M^{(n)} M^{(n+1)}\right) \right]_{\beta} \end{split}$$

proof of (d) continued

As this holds for all vectors $\frac{n_{\alpha}}{n}, \ldots, \frac{n_{\gamma}}{n}$, we conclude:

$$(n+1)M^{(n)} = n \cdot M^{(n+1)} + M^{(n)} \cdot M^{(n+1)}$$

From this recursion and the initial value $M^{(1)} = (1 - \lambda_1)(I - \lambda_1 P)^{-1}$ set by (b), follows $M^{(n)} = (1 - \lambda_n)(I - \lambda_n P)^{-1}$. This implies $\tilde{\pi} = \hat{\pi}$.

For the more complicated proof of (e), see Stephens und Donnelly (2000).

We define the proposal distribution Q_{θ}^{SD} with \hat{q} like Q_{θ}^* with q by replacing π by the approximation $\hat{\pi}$.

Theorem 4

$$\sum_{H} \widehat{q}_{\theta}(H \mid H_i) = 1$$

and $\widehat{q}_{\theta}(. \mid H_i)$ can be simulated as follows:

- 1. Choose a purely random $\alpha \in H_i$.
- 2. For all β compute $\widehat{\pi}(\beta \mid H_i \alpha)$

3.

$$H_{i-1} := \begin{cases} H_i - \alpha + \beta & \text{with probability} \quad \propto \theta \widehat{\pi} (\beta \mid H_i - \alpha) \cdot P_{\beta \alpha} \\ H_i - \alpha & \text{with probability} \quad \propto n_\alpha - 1 \end{cases}$$

Thus, $\hat{\pi}(\beta \mid H_i - \alpha)$ must be computed only for a few pairs (α, β) . First sample α and then decide whether it mutated to beta β or coalesces with another α . It is efficient to compute $\hat{\pi}(\beta \mid H_i - \alpha)$ and to simulte Q_{θ}^{SD} .

Proof:

The probability that a mutation of a type α is involved, is

$$p_m(\alpha) = \frac{1}{n(n-1+\theta)} \sum_{\beta} \frac{\theta}{2} n_{\alpha} \frac{\widehat{\pi}(\beta \mid H_i - \alpha)}{\widehat{\pi}(\alpha \mid H_i - \alpha)} P_{\beta\alpha}.$$

The probability that two lineages of type α coalesce, is:

$$p_c(\alpha) = \frac{n_\alpha(n_\alpha - 1)}{n(n - 1 + \theta)} \cdot \frac{1}{\widehat{\pi}(\alpha \mid H_i - \alpha)}$$

This implies $p_m(\alpha) + p_c(\alpha) = 1$.

What to do with sequence data???

For nucleotide (or protein) sequences of length ℓ there are 4^{ℓ} (or 20^{ℓ}) different possible genotypes $\alpha = (\alpha_1, \ldots, \alpha_{\ell})$, and the transition matrix $(P_{\alpha\beta})_{\alpha\beta}$ could be very large.

 $\theta/2$: mutation rate per site.

For $\hat{\pi}(. | A_n)$ draw a geometrically number *m* of mutations with parameter $\frac{\ell\theta}{n+\ell\theta}$ and spread them randomly on the sites.

Equivalent: draw $\exp(1)$ -distributed time t and then for each site i a $Poisson(t\theta/n)$ distributed number m_i of mutations. This implies

$$\widehat{\pi}(\beta \mid A_n) = \sum_{\alpha \in A_n} \frac{n_\alpha}{n} \int \exp(-t) F_{\alpha_1 \beta_1}^{(\theta,t,n)} \cdots F_{\alpha_\ell \beta_\ell}^{(\theta,t,n)} dt$$

with

$$F_{\alpha_i\beta_i}^{(\theta,t,n)} = \sum_{m=0}^{\infty} \frac{(\theta t/n)^m}{m!} \exp(-\theta t/n) (P^m)_{\alpha_i\beta_i}.$$

Stephens and Donnelly suggest to approximate the integral with Gauß quadrature (siehe Press et al. (1992)) to obtain

$$\widehat{\pi}(\beta \mid A_n) = \sum_{\alpha \in A_n} \sum_{i=1}^s \frac{n_\alpha}{n} w_i F_{\alpha_1 \beta_1}^{(\theta, t_i, n)} \cdots F_{\alpha_\ell \beta_\ell}^{(\theta, t_i, n)}$$

for certain s, w_i and t_i . The $F_{\alpha_i \beta_i}^{(\theta,t,n)} = \sum_{m=0}^{\infty} \dots$ can be approximated by finite sums.

12.2.2 Estimating LD and recombination hotspots

Problems of models to estimate local recombination rates:

LAMARC etc. (ARG-based): not feasible for larger parts of the genome

Summary-statistics-based: lose too much information

some composite-likelihood methods: Hudson (2001), Fearnhead, Donnelly (2002), McVean (2002) assume fixed recombination rate along the genome

References

 P. Fearnhead, P. Donnelly (2001) Estimating Recombination Rates From Population Genetic Data Genetics 159: 1299–1318

Aim: Approximate the joint likelihood surface for the recombination rate and the mutation rate.

Model assumption: panmictic population, constant size N

 $\theta = 4N\mu$

 $\mu\,$ Mutation rate per generation and chromosome

$$\rho = 4Nr$$

r Recombination rate per generation and chromosome

Two different mutation modes:

- infinite-sites model
- at each site finitely many types with transition matrix $P_{\alpha\beta}$
- \mathcal{G} set of all ancestral histories (containing all mutations) that are consistent with the data D, such that $\forall_{G \in \mathcal{G}} \Pr(D|G) = 1$
- **Importance Sampling:** If G_1, \ldots, G_m are sampled independently according to some density q with $\mathcal{G} \subseteq \operatorname{supp}(q)$, then

$$L(\rho,\theta) \approx \int_{\mathcal{G}} P(G|\theta,\rho) dG \approx \frac{1}{M} \sum_{i=1}^{M} \frac{P(G_i|\rho,\theta)}{q(G_i)}$$

What is a good proposal distribution q?

idea: Extend method of Stephens, Donnelly (2000) by recombination

H set of already sampled haplotypes

 α potential type of j + 1st sampled haplotype

- $p(\alpha|H)$ will, like in Stephens, Donnelly (2000), be approximated to be used in importance sampling scheme
- **important:** To use approximation q in importance sampling it must be possible to **sample** according to q(.|H) and to **compute** $q(\alpha|H)$ for given α .

We specify $q(\alpha|H)$ by showing how to sample from it:

initialization: Let x_1, \ldots, x_s be the segregating sites in the *j* chromosomes in *H*.

recombination: For i = 1, ..., s - 1 there is a recombination event in the middle between x_i and x_{i+1} in α with probability

$$a_i := \frac{(x_{i+1} - x_i)\rho}{(x_{i+1} - x_i)\rho + j}.$$

Let k be the number of recombinations and $r = \{r_1, \ldots, r_{k+1}\}$ the resulting fragments.

imputation: For nonancestral sites in H impute types according to their frequency at that site in H.

mutations: Each r_i is simulated (independently of any r_j) according to Stephens, Donnelly's (2000) approximation $\hat{\pi}$ for sequence data.

To compute $q(\alpha|H)$ for the correction in the Importance Sampling formula, we need to sum over all possible combinations of recombinations, imputations, and mutations that would lead to α .

This is done by dynamic programming: compute iteratively

- $q_i(\alpha)$ probility that simulated type will coincide with α at first *i* loci.
- $q_i(\alpha|s,t)$ as above, but conditioned that *i*th locus is a mutated copy of the *i*th locus in H_s with Poisson(θt) mutations.

For this, the following approximation is used:

$$q_i(\alpha) \approx \sum_{m=1}^k \sum_{b=1}^j w_m q_i(\alpha|b, t_m/j)/j,$$

where w_1, \ldots, w_k and t_1, \ldots, t_k are the weights and points from the Gauß quadrature $\int_0^\infty e^{-t} f(t) dt \approx \sum_{m=1}^k w_m f(t_m)$.

To compute $q_i(\alpha|s,t)$ from previously computed $q_{i-1}(\alpha|s,t)$ and $q_{i-1}(\alpha)$ first compute the transition matrix for time t:

$$Q(t) = \exp\left(\theta t (P - I)/s\right)$$

where P as before is the transition matrix given that a mutation happens.

If H_s is ancestral at locus *i* and has type β there, set

$$R := Q_{\beta,\alpha_i}(t),$$

and otherwise

$$R := (\pi_i Q(t))_{\alpha_i}$$

where π_i is the vector of proportions of types in H at position i. Then:

$$q_i(\alpha|s,t) = [(1 - a_{i-1}) \cdot q_{i-1}(\alpha|s,t) + a_{i-1} \cdot q_{i-1}(\alpha)] \cdot R.$$

Using these regression formulas in a dynamic-programming approach, $q(\alpha|H)$ can be computed and used to compute the proposal probability.

In the Importance Sampling step, the proposal probability is compared to the original ARG probability (ARG=ancestral recombination graph) and corrected accordingly to approximate the likelihood function for ρ and θ in the ARG model.

Li and Stephens' PAC approach, in contrast, replace the ARG model by a simpler model.

Li & Stephens' approach to analyze patterns of LD

References

[LS03] Na Li, Matthew Stephens (2003) Modeling Linkage Disequilibrium and Identifying Recombination Hotspots Using Single-Nucleotide Polymorphism Data Genetics 165

ideas:

- relate LD directly to underlying recombination process
- Sometimes, block-like LD structure is reported. True or artifact of LD mapping? Allow for both.
- consider all loci simultaneously, not pairwise
- should be computionally tractable even for complete chromosomes

Li & Stephens' PAC approach

 h_1, h_2, \ldots, h_n : haplotypes sampled from panmictic population with constant size and random mating

 ρ : recombination parameter (may be a vector if recombination rate varies within the region of interest)

Product of Approximate Conditionals (PAC)

$$\Pr(h_1,\ldots,h_n|\rho) = \Pr(h_1) \cdot \Pr(h_2|h_1,\rho) \cdot \ldots \cdot \Pr(h_n|h_1,\ldots,h_{n-1},\rho)$$

approximate $\Pr(h_k|h_1, \ldots, h_{k-1}, \rho)$ by simpler $q(h_k|h_1, \ldots, h_{k-1}, \rho)$. Properties of $\Pr(h_k|h_1, \ldots, h_{k-1}, \rho)$

- 1. h_k is more likely to match another haplotype if the latter is frequent among $h_1, h_2, \ldots, h_{k-1}$
- 2. the probability of seeing a novel haplotype decreases as k increases
- 3. the probability of seeing a novel haplotype increases with $\theta = 4N_e\mu$.
- 4. if a new haplotype does not exactly match any previous one, it will differ from one of those only by a small number of mutations.
- 5. effect of recombination: the next haplotype will be composed by segments which are similar to segments in previously sampled haplotypes. These segments tend to be longer if recombination rates are low.

Assume the sampled haplotypes h_1, h_2, \ldots, h_n are typed at S biallelic loci (e.g. SNPs).

$$q(h_1) = \left(\frac{1}{2}\right)^S$$

For the definition of $q(h_{k+1}|h_1, h_2, \ldots, h_k)$ let $X_i := j$ if at the *i*-th locus, the closest relative of h_{k+1} among h_1, \ldots, h_k is h_j .

- d_i distance between loci i and i + 1
- c_i recombination rate between loci *i* and i + 1 per site and per generation

$$\rho_i = 4N_e c_i$$

The simplifying assuption is then that X_1, X_s, \ldots, X_S is a Markov chain on $\{1, \ldots, k\}$ with $Pr(X_1 = j) = 1/k$ and

$$\Pr(X_{i+1} = j | X_i = \ell) = \begin{cases} (1 - e^{-\rho_i d_i/k})/k & \text{if } j \neq \ell \\ e^{-\rho_i d_i/k} + (1 - e^{-\rho_i d_i/k})/k & \text{if } j = \ell \end{cases}$$

Mutations

For SNP data we assume that each locus is hit by one mutation, such that

$$\widetilde{\theta} := 1 \left/ \sum_{m=1}^{n-1} \frac{1}{m} \right|$$

is assumed to be the corrected rate of mutations per SNP site. Note that this does not exclude double hits (just some bias if double hits are frequent.)

Then, with probability $\frac{k}{k+\tilde{\theta}}$ the copy has the same type as the original and with probability $\frac{\tilde{\theta}}{(k+\tilde{\theta})}$ the haplotype has the other of the two possible alleles.

Compute $q(h_{k+1}|h_1,\ldots,h_k)$ by HMM forward algo:

 $h_{k+1,\leq j} := (h_{k+1,1}, \ldots, h_{k+1,j}) :=$ types of the first j sites in h_{k+1}

 $\alpha_j(x) := \Pr(h_{k+1,\leq j}, X_j = x | h_1, \dots, h_k)$

(note that with mutations any X_1, \ldots, X_S can emit h_k .) Then,

$$q(h_{k+1}|h_1,\ldots,h_k) = \sum_{x=1}^k \alpha_S(x).$$

"dynamic programming": we can compute all $\alpha_i(x)$ by the recursion

$$\alpha_{j+1}(x) = \Pr(h_{k+1,j+1}|X_{j+1} = x, h_1, \dots, h_k) \cdot \sum_{x'=1}^k \alpha_j(x') \cdot \Pr(X_{j+1} = x|X_j = x')$$

= $\Pr(h_{k+1,j+1}|X_{j+1} = x, h_1, \dots, h_k) \cdot \left(e^{-\rho_j d_j/k} \cdot \alpha_j(x) + \left(1 - e^{-\rho_j d_j/k}\right) \cdot \frac{1}{k} \sum_{x'=1}^k \alpha_j(x')\right)$

Bias correction

Simulations show that estimations of ρ based on q are biased.

For bias-correction replace ρ_j in the computation of $\Pr(X_{j+1} = x' | X_j = x)$ by

$$\rho_i \cdot e^{a + b \log_{10} \rho_j},$$

where a and b are fitted to simulated data, taking the numbers of haplotypes and segregating sites into account.

Models for ρ considered by Li and Stephens

- 1. constant ρ
- 2. single-hotspot model
- 3. all recombination rates $\rho_1, \rho_2, \ldots, \rho_{S-1}$ may differ

Software by Matthew Stephens using PAC: Hotspotter, PHASE

12.2.3 PAC in PHASE

References

[SS05] Matthew Stephens, Paul Scheet (2005) Accounting for Decay in Lincage Disequilibrium and Missing-Data Imputation Am. J. Hum. Genet. 76:449–462

- Use information about order and distance between marker positions
- recombination rates may vary and are estimated
- applicable also when LD is "blocklike"
- imputation of missing data

n number of individuals

L number of loci

 $G = (G_1, \ldots, G_n)$ genotypes; observed up to missing loci

 $H = (H_1, \ldots, H_n)$ haplotypes; to be reconstructed

 $H_{-i} = (H_1, \dots, H_{i-1}, H_{i+1}, \dots, H_n)$

 $\rho = (\rho_1, \ldots, \rho_{L-1})$ recombination rates between loci

$$\rho_\ell = \frac{4N_e c_\ell}{d_\ell}$$

- c_{ℓ} recombination probability per generation between loci ℓ and $\ell + 1$; to be estimated
- $d_\ell\,$ known distance between loci ℓ and $\ell+1$

strategy of PAC approach in PHASE

Start with initial H and ρ the following steps many times:

- 1. for each *i* update H_i by sampling from $\Pr(H_i|G_i, H_{-i}, \rho)$
- 2. propose change of ρ and accept or reject with Metropolis-Hastings (MH) step
- 3. update ordering ν of individuals with MH step for order-dependent PAC probabilities

Needed in these steps:

$$\Pr(H_i = (h, h') | H_{-i}, \rho) \propto (2 - \delta_{hh'}) \cdot p(h' | H_{-i}, \rho) \cdot p(h | H_{-i}, h', \rho)$$

(where $p(h|H_{-i}, h', \rho)$ will be approximated by $p(h|H_{-i}, \rho)$)

Simplifying assumption in the computation of $p(h|h_1, \ldots, h_k, \rho)$:

- when a locus in h is copied from some h_i only two possible coalescence times are allowed $(t_1 = 0.586/k, t_2 = 3.414/k)$ and taken with probabilities $w_1 = 0.854$ and $w_2 = 0.146$. This is a Gauß quadrature approximation of the exponential distribution.
- if X_{ℓ} is the number of the allele from which locus ℓ in h is copied and T_{ℓ} the corresponding coalescence time, then $(X_1, T_1), (X_2, T_2), \ldots$ is a Markov chain with $\Pr(X_1 = x, T_1 = t_r) = w_r/k$ and transition probabilities $\Pr(X_{\ell+1} = x', T_{\ell+1} = t_{r'}|X_{\ell} = x, T_{\ell} = t_r) =$

$$(1 - e^{-\rho_l d_l/k}) \cdot w_r/k + \delta_{xx'} \delta_{rr'} e^{-\rho_l d_l/k}.$$

Thus, HMM algorithms can be applied again.

$$\Pr(h_{k+1} = a | X_{\ell} = x, T_{\ell} = t, h_1, \dots, h_k, \rho) = \sum_m \frac{(\theta t)^m}{m!} e^{-\theta t} (P^m)_{h_{x,\ell} a}$$

Proposals for step 1 are halplotypes that are composed by blocks as described in Stephens and Donnelly (2003), leading to a list of promising haplotypes compatible with G_i .

For these haplotypes probabilities are computed with forward algorithm and one of them is chosen randomly according to the computed probabilities.

For imputation of missing types, probabilities are computed with forward-backward algorithm and types are sampled accordingly.

performance studies haplotype inference:

•

dataset1 40 X chromosomes from unrelated males, paired into 20 pseudo-individuals, 8 regions of 87–327 kb and 45–165 segregating sites

dataset2 autosomal data from 129 children with known phase (as parents were also genotyped),

result PHASE with recombination PAC model best overall and for most regions.

imputing missing data:

- data 50 genes sequenced for 24 humans of African descent and 23 of European descent, 15–230 segregating sites per gene.
- simulation remove 5% of the data (in addition to 4.6% that was actually missing), either single alleles or the genotypes.

result PHASE with recombination PAC model always best

References

- [CB+04] Crawford, Bhagale, Li, Hellenthal, Rieder, Nickerson, Stephens (2004) Evidence for substantial fine-scale variation in recombination rates across the human genome *nature genetics*
- [CB+04] Myers, Freeman, Auton, Donelly, McVean (2008) A common sequence motif associated with recombination hot spots and genome instability in humans *nature genetics*

12.2.4 Population splitting and recombination

References

- [DPC09] D. Davison, J.K. Pritchard, G. Coop (2009) An approximate likelihood for genetic data under a model with recombination and population splitting. *Theoretical Population Biology* 75:331-345
 - two populations split G generations ago, F = G/(2N).
 - no ongoing geneflow
 - for simplicity: assume that both populations and the ancestral population have size N
 - Copying occurs in daughter population (S = d) and in ancestral population (S = a)

Again, the PAC approach is used and we have to approximate the probability of a haplotype $h_{k_1+k_2+1}$ given already sampled haplotype $h_1, \ldots, h_{k_1+k_2}$, of which k_1 were sampled on island 1 and k_2 on island 2.

Let $z_i \in \{1, 2\}$ indicate the island where h_i was sampled, $z_* := z_{k_1+k_2+1}$, and X_{ℓ} indicates the h_i that is the closest relative to $h_{k_1+k_2+1}$ at site ℓ .

to be specified:

1. prior prob of hidden copying states (S_{ℓ}, X_{ℓ}) at a single site ℓ .

- 2. probability of new allelic state conditioned on the state of the copied allele and the level S_{ℓ} .
- 3. Transition probabilities between the hidden copying state at adjacent states (in case of linked loci).

Point 1: $Pr(X_{\ell} = i | S_{\ell} = d)$, unlinked case

In the case of unlinked sites, we obtain first consider the case of unlinked sites,

$$\Pr(X_{\ell} = i | S_{\ell} = d) = \begin{cases} \frac{1}{k_{z_*}} & \text{if } z_* = z_i \\ 0 & \text{else} \end{cases}$$

where k_{z_*} is the no. of lineages sampled

from pop.
$$z_*$$
 so far
 $\Pr(X_{\ell} = i | S_{\ell} = a) = \mathbb{E}\left(\frac{J_{z_i}}{J_1 + J_2}\right) \cdot \frac{1}{k_{z_i}},$

Where J_i is the number of ancestral lineages that enter the ancestral pop. from pop. *i*. To compute the expectation first compute for all $j_i < k_i$ the probabilities that k_i lineages coalesce down to j_i lineages in G generations. These values are also needed to compute $\Pr(S_{\ell} = d)$.

Point 2: Mutation probability; unlinked case

Simplification: For time T_{coal} of coalescence use expectation

$$t_s = \mathbb{E}(T_{coal}|S, k_1, k_2, F)$$

Then:

$$\begin{aligned} u(h_{k_1+k_2+1}|h_i,s) &= & \Pr(h_{k_1+k_2+1}|S_\ell = s, X_\ell = i, k_1, k_2, F) \\ &= & \begin{cases} 1 - e^{-\theta t_s} & \text{if } h_{k_1+k_2+1} \neq h_i \\ e^{-\theta t_s} & \text{if } h_{k_1+k_2+1} = h_i \end{cases}, \end{aligned}$$

where θ is corrected for using only polymorphic sites as in Li&Stephens.

Thus, we approximate $\Pr(h_{k_1+k_2+1}|h_1,\ldots,h_{k_1+k_2})$ by

$$\sum_{s \in \{a,d\}} p(S=s) \cdot \sum_{i=1}^{k_1+k_2} u(h_{k_1+k_2+1}|h_i,s) \cdot p(X=i|S=s)$$

now for the case of (loosly) linked loci

- Now $(S_1, X_1), \ldots, (S_L, X_L)$ are not independent.
- Simplify applying Markov model, such that HMM algorithms are applicable
- Computing transition probabilities

$$p(S_{\ell+1} = s', X_{\ell+1} = i'|S_{\ell} = s, X_{\ell} = i)$$

= $p(S_{\ell+1} = s'|S_{\ell} = s) \cdot p(X_{\ell+1} = i'|S_{\ell+1} = s') + \delta_{ii'}\delta_{ss'} \cdot p(NR|S_{\ell}),$

where NR stands for "no recombination" is tricky, several simplifying approximation are applied, e.g.:

• if A is the event that a recombination happens on the new lineage in the daughter population, then

$$p(S_{\ell+1} = d|S_{\ell} = a) = p(A) \cdot p(S = d|A)$$
(1)

$$\approx (1 - e^{-\rho_{\ell} F}) \cdot p(S = d) \tag{2}$$

- Simulation study
 - works well in case of unlinked loci
 - estimates of F biased for version with linked loci
 - not well understood where this bias comes from, but suggest a bias correction
- Discuss how method could be extended to models with gene flow

12.2.5 Diversifying selection and recombination

References

[WM06] D.J. Wilson, G. McVean (2006) Estimating diversifying selection and functional constraints in the presence of recombination Genetics 172:1411-1425

Apply Bayesian variant of PAC to infer from population genetic data which regions are under diversifying selection and which are under purifying selection.

 $\omega = d_N/d_S$ fraction of rates of nonsynonymous vs. synonymous mutations

diversifying selection corresponds to large ω and

purifying selection to small ω .

Software: omegaMap http://www.danielwilson.me.uk/omegaMap.html

NY98 Codon mutation model

Nielsen and Yang (1998)

Mutation rate $q_{ij} = \pi_j \cdot \mu_{ij}$, where *i* and *j* are codons, $i \neq j$ or one of then is an insertion/deletion (indel), π_j is the frequency of j and

for synonymous transversion

 $\mu_{ij} = \begin{cases} 1 & \text{for synonymous transition} \\ \kappa & \text{for synonymous transition} \\ \omega & \text{for nonsynonymous transition} \\ \omega \kappa & \text{for nonsynonymous transition} \\ \omega \phi & \text{if exactly one of } i \text{ and } j \text{ is an indel} \\ 0 & \text{otherwise} \end{cases}$

(original NY98 is without indels)

Model for ω along the gene:

There are B transition points s_1, \ldots, s_B , such that $\forall_j : \omega$ is constantly ω_j between s_j and s_{j+1} .

 p_{ω} Probability of transition point between two codons.

 ω_i are independent of each other and have prior $\exp(\lambda)$

Similar model for change of recombination rate ρ ; independent of ω configuration.

H haplotypes sampled from population

 Θ model parameters, including all ω_j and ρ_j and change points.

MCMC sample parameter values according to

$$P(\Theta|H) \propto P(H|\Theta) \cdot P(\Theta)$$

PAC with HMM forward algorithm is applied to approximate $P(H|\Theta)$ via PAC approximations of

 $p(H_{k+1}|H_1, H_2, \ldots, H_k, \Theta)$

MCMC moves

To propose e.g. μ' as a replacement of current μ , choose $U \sim \operatorname{unif}(-1, 1)$, und set $\mu' = \mu \exp(U)$. Accept or reject with MH step.

Same for κ, ω_j, ρ_j .

MCMC step to shift block change point.

Reversible Jump steps to update blocks:

- split block
- merge block

 $\lambda, \phi, p_{\omega}, p_{\rho}$ are specified by user to specify prior.

Application example

79 alleles of porB locus of Neisseria meningitidis

permutation test shows significant correlation of LD and distance between sites. \Rightarrow Phylogenetic methods not appropriate.

Found four sections in the gene where high ω values are probable, indicating diversifying selection, whereas almost everywhere else, $\omega < 1$, indicating purifying selection.

Indeed, regions with large ω are loops exposed to immune system of host, such that diversifying selection is plausible, and other regions form beta sheet barrel, which explains functional constraints. (nice picture in paper!)

Model without recombination leads to different results, but

Model Criticism via posterior predictive *P*-value shows that model without recombination fits the data poorly. This means, if *D* is some statistic of the data and $D_{H'}$ is the statistic for a dataset H' simulated under the PAC model used for inference, then the

posterior predictive *P*-value is:

$$p = \int P(D_{H'} \ge D_H | \Theta, H) P(\Theta | H) d\Theta \approx \frac{1}{M} \sum_{i=1}^M I(D_{H'_i} \ge D_H)$$

Wilson and McVean perform simulation studies for several conditions to assess how well their method works.

This is very important for heuristic approaches like PAC because it is otherwise not clear how accurate these methods are even if sampling from some approximate posterior approximate confidence intervals are computed.

12.3 Phasing large genomic datasets

12.3.1 fastPHASE

References

[SS06] P. Scheet, M. Stephens (2006) A Fast and Flexible Statistical Model for Large-Scale Population Genotype Data: Applications to Inferring Missing Genotypes and Haplotypic Phase Am. J. Hum. Genet. 78:629–644 If n haplotyps are to be reconstructed (that is, from n/2 sampled individual) at M marker positions, than the complexity of HMM algorithms in PHASE is $\mathcal{O}(n^2 M)$.

fastPHASE reduces this to $\mathcal{O}(nM)$.

Instead of sampling sections of haplotypes from copies of other haplotypes, all section are sampled from K clusters, similar to STRUCTURE.

First consider clustering method of haplotypes, where cluster just is a set of closely related haplotypes.

Then extend for phasing with in Hardy-Weinberg Equilibrium (HWE) within clusters. First: consider local clustering method for haplotypes.

Given $h = (h_1, \ldots, h_n)$ haplotypes with M biallelic $\{0, 1\}$ (can be relaxed) marker positions.

 $z_{im} \in \{1, \ldots, K\}$ origin of h_{im} , (marker position m in h_i). $z_i = (z_i, \ldots, z_{iM})$ modeled as a Markov chain with

$$p(z_{i1} = k) = \alpha_{k1}$$

and $p_m(k \to k') :=$

$$p(z_{im} = k'|z_{i(m-1)} = k, \alpha, r) = (1 - e^{-r_m d_m}) \cdot \alpha_{k'm} + \delta_{kk'} \cdot e^{-r_m d_m}$$

where d_m is the distance between markers m-1 and m, and the recombination parateters $r = (r_2, \ldots, r_M)$ as well as $\alpha = (\alpha_{km})$ are to be estimated.

Now for the emission probabilities:

$$p(h_i|z_i,q) = \prod_{m=1}^M p(h_{im}|z_{im},q) = \prod_{m=1}^M q_{z_{im}m}^{h_{im}} \cdot (1 - q_{z_{im}m})^{1 - h_{im}},$$

where q_{km} is the frequency of allele 1 at marker m in cluster k.

Again, we obtain an HMM, parameter estimation can be done with EM, assignents of haplotype sections to culsters e.g. with Viterbi-Algorithm or Bayesian sampling tracing back contributions in the forward algorithm.

Now assume that unphased genotypes $g = (g_1, \ldots, g_n)$ are given, $g_{im} \in \{0, 1, 2\}$ is the genotype at marker m in individual i. Now assume HWE in each cluster. Let \tilde{z}_{im} be the unordered pair of clustes of

origin of g_{im} :

$$p(\tilde{z}_{i1} = \{k_1, k_2\}) = (2 - \delta_{k_1 k_2}) \alpha_{k_1} \alpha_{k_2}$$

and assume that $\tilde{z}_i = (\tilde{z}_{i1}, \ldots, \tilde{z}_{iM})$ is a Markov chain with transition probabilities $p_m(\{k_1, k_2\} \rightarrow \{k'_1, k'_2\}) =$

$$p_m(k_1 \to k_1') \cdot p_m(k_2 \to k_2') + \left(1 - \delta_{k_1 k_2} \delta_{k_1' k_2'}\right) \cdot p_m(k_1 \to k_2') \cdot p_m(k_2 \to k_1').$$

Emission probabilities:

$$p(g_{im}|\tilde{z}_{im} = \{k_1, k_2\}, q) = \begin{cases} (1 - q_{k_1m})(1 - q_{k_2m}) & \text{if } g_{im} = 0\\ q_{k_2m}(1 - q_{k_1m}) + q_{k_1m}(1 - q_{k_2m}) & \text{if } g_{im} = 1\\ q_{k_1m}q_{k_2m} & \text{if } g_{im} = 2 \end{cases}$$

Difference to approach of Falush *et al.* (2003) implemented in STRUCTURE: Here, α varies between

marker positions but not between individuals. In Falush *et al.* it is vice versa (for the parameter there called q). That is, here, α controls the frequency of the common haplotypes, not the contribution of the

different clusters to an individual's genome.

HWE assumption is violated if the population is substructured. Applications of fastPHASE for

data imputation or phasing may be robust against such violations. Moreover, extension of model is

possible, assuming that individuals are sampled from known subpopulations and the parameters r and α vary between the subpopulations.

Parameter estimation with EM: Found that 20 independent starts with 25 iterations each is enough.

K = ?: How many clusters to choose? Cross validation: Mask 15% of the genotypes, impute the genotypes with fastPHASE with various K between 4 and 12. Choose the K for which the genotypes a correct as often as possible (was K = 8 for data used in Scheet and Stephens, 2006). But also suggest to run with various K and compare results rather than relying on a single value of K.

12.3.2 Phasing with Beagle software package

References

[BB07] S.R. Browning and B.L. Browning (2007) Rapid and Accurate Haplotype Phasing and Missing-Data Inference for Whole-Genome Association Studies By Use of Localized Haplotype Clustering Am. J. Hum. Genet. 81:1084–1097

For an initial guess of the haplotypes first construct a directed acyclic graph (DAG), in which

- each edge has a level m corresponding to marker position m
- and a lable corresponding to an allele occuring at marker position m,
- and for each of the occuring haplotypes $h_i = (h_{i1}, \ldots, h_{iM})$ there is path from the start node to the end node such that the lables of the edges are h_{i1}, \ldots, h_{iM} .
- (If a node has ingoing edges of level m than all its outgoin edges are of level m+1, and vice versa.)

Method of graph construction described in paper by S.R. Browning (2006)

Then construct an HMM whose possible states at step m are ordered pairs of DAG edges of the same level m. Transition probabilities:

$$P((e_1, e_2) \to (e_3, e_4)) = P(e_1 \to e_3) \cdot P(e_2 \to e_4),$$

where

$$P(e_i, e_j) = \frac{\#\{\text{haplotypes whose path contains } e_2 \text{ and } e_j\}}{\#\{\text{haplotypes whose path contains } e_i\}}$$

Emission probability: 1 if genotype at marker position m is compatible with labels of edges belonging to state, otherwise 0.

Now use "diploid HMM" to sample for each individual several haplotypes (in Beagle software 4 haplotype pairs per individual). Pool these haplotypes to construct DAG for next iteration. For

sampling use forward algorithm restricted on states corresponding to states of the focal individual, and random tracebacks, with probabilities always proportional to current state. In last iterations use Viterbi

paths instead of random paths.

12.3.3 IMPUTE version 2

References

[HDM09] B.N. Howie, P. Donnelly, J. Marchini (2009) A Flexible and Accurate Genotype Imputation Method for the Next Generation of Genome-Wide Association Studies *PLoS Genetics* 5(6)

Similar to PAC-approach in PHASE, but is made for situation when reference haplotype data is available. Reference haplotypes and unphased genotypes are used together in phasing update step. For

runtime efficiency untyped SNPs are imputed in haplotype HMM framwork rather than in diploid HMM.

For accelaration restrict set of possible haplotypes in each iteration to those that are similar to existing ones.

12.3.4 MaCH

References

[LW+10] Y. Li, C.J. Willer, J. Ding, P. Scheet, G.R. Abscasis (2010) MaCH: Using Sequence and Genotype Data to Estimate Haplotypes and Unobserved Genotypes Genet. Epidemiol. 24(8): 816–834

Similar to fastPHASE, but uses a larger number of haplotype templates instead of few haplotype groupings. In emission probabilities use error parameter ε_j that can depend on position j and covers

sequencing error, gene conversion,...

12.3.5 polyHAP

References

[SW+08] S.Y. Su, J. White, D.J. Balding, L. J. M. Coin (2008) Inference of haplotypic phase and missing genotypes in polyploid organisms and variable copy number genomic regions BMC Bioinformatics 9:513

Similar HMM approach like fastPHASE but for polyploid data. Computationally very demanding

because states are unordered lists stating how many alleles have been sampled from how many clusters. Thus, many possible transitions between hidden states are considered.

13 Simulating the genetic footprints of selection

We have already discussed one genetic signal of selection: dN/dS. We will now consider the effect of

selection and adaptation on genealogies. We will discuss how these effects can be simulated, because

- 1. this is a way to specify the theoretical model and
- 2. if we know how to simulate data, we can apply ABC and similar methods for statistical inference of model parameters.

Possible scenarios for the case of positive selection (directional selection):

- 1. A beneficial mutation appears once, spreads in the population and will eventually be fixed
- 2. there is a balance between mutation and selection
- 3. selection pressure changes in time and a certain allele is favored for a while and increases in frequency during that time

Other forms of selection:

background selection, also called negative selection

balancing selection can lead to maintance of two alleles over a long period of time

diversifying selection : new types appear by mutation and have an advantage until the reach a certain frequency

etc.

Basic model of positive selection: Each individual *i* of the *N* population of size *N* has a fitness w_i , which is the expected number of kids. The *N* surviving offspring of the next generation are sampled from the kids of all individuals. Thus, the expected number of surviving offspring of *i* is $w_i / \sum_{j=1}^{N} w_j$.

Let's assume a simple scenario: haploid population with one type A of fitness 1 + s and one type a of fitness 1.

Moran model

Assume a population of 2N gametes. An alternative to the Wright-Fisher model is the Model of

Moran(1958): Each gamete has a rate of 1 to generate one offspring and replace one randomly chosen gamete. For $N \to \infty$ and time scaled in units of N (not 2N!) generations, the genalogy of a sample

from the Moran model converges to the standard Kingman coalescent. Add selection to Moran model:

Type A replaces produces offspring at rate 1 and type a at rate (1 - s). This approximates the diploid

case with fitness 1 of AA, 1-s of Aa, and $(1-s)^2 \approx 1-2s$ of aa. (Note that capital letter A does not indicate dominance.)

Transition rates of number of allele A gametes in Moran model with selection:

$$i \to i+1$$
 at rate $\frac{(2N-i)\cdot i}{2N}$
 $i \to i-1$ at rate $\frac{(2N-i)\cdot i}{2N}\cdot (1-s)$

More facts about Moran model with selection:

Fixation probability: If we start with i gametes of type A, the fixation probability of A is

$$\frac{1 - (1 - s)^i}{1 - (1 - s)^{2N}} \approx \frac{1 - e^{-is}}{1 - e^{-2Ns}}$$

Fixation time: Assume that type A starts with one gamete. Conditioned on the fixation of A, the expectation value of the fixation time is in the limit of large populations is asymptotically

$$\frac{2}{s}\log N$$

For proofs see:

References

[D08] R. Durrett (2008) Probability Models for DNA Sequence Evolution 2nd Ed., Springer

In mathematical population genetics two cases are considered:

weak selection: as $N \to \infty$, $s \to 0$ such that $Ns \to \tilde{s} < \infty$.

strong selection: as $N \to \infty$, s is stays constant, with the consequence that the fixation time of the advantageous allele is 0 on the time scale of N generations.

13.1 Ancestral Selection Graphs

References

- [NK97] C. Neuhauser, S.M. Krone (1997) Ancestral processes with selection *Theor. Pop- Biol.* **51**:210–237
- [KN97] S.M. Krone, C. Neuhauser (1997) The genealogy of samples in models with selection *Genetics* 145:519–534

Ancestral Selection Graph (ASG)

Weak selection: $2Ns \to \tilde{s}$ as population size $2N \to \infty$. Each pair of ancestral lineages coalesces at

rate 1. At rate $\theta/2$ lineage of type a mutates into A and vice versa. Each lineage x is hit by "arrow" at

rate \tilde{s} . Arrow was shot by random individual y from population. If (further in the past) x was of type a and y of type A, replace (in future direction) x by type A. To find out whether this applies, trace lineages back into past. At latest when all lineages are coalesced, types of all lineages are determined.

This happens almost surely after finite time because number j of lineages to trace back jumps to j + 1 at rate $\tilde{s} \cdot j$ only but jumps to j - 1 at rate $j \cdot (j - 1)/2$.

ASG for frequency-dependent selection with advantage of rare alleles

References

[N99] C. Neuhauser (1999) The ancestral graph and gene genealogy under frequency-dependent selection Theoretical Population Biology 56:203–214

When lineage x is hit by "replacement arrow" from y, it shoots a "check arrow" to some random

individual z from the population. It copies the type of y if and only if the type of z is different than that of y. Thus, lineages of x, y, and z have to be traced back. But again all lineages will coalesce in

finite time because rate of adding lineages is linear whereas rate of coalescence is quadratic in number of lineages. In structured population one can also assume that the arrows are shot locally to model that

selection depends on local frequencies.
13.2 Simulating selective sweeps and other kinds of strong selection

In the case of strong selection, coalescent based simulation faces the problem that in time span of length 0 advantageous type becomes fixed, and backward in time all lineages would coalesce at that time. In

case of the ancestral recombination graph (ARG) there is even no time for recombination. However,

if we model a locus that is far from selected locus, recombination rate is also high and in mathematical models we could also let it go to ∞ such that lineages can escape the selective sweep. In the simulation

programm MSMS, however, the approach is to first simulate the locus under selection for finite N, and then the ARG around (or next to) it conditioned on the frequency trajectory of the selected allele.

References

[EH10] G. Ewing, J. Hermisson (2010) MSMS: a coalescent simulation program including recombination, demographic structure and selection at a single locus *Bioinformatics* 26(16): 2064–2065

Strategy: First simulate the site under selection forward in time with discrete generations and finite N. Then generate the ARG backwards in time conditioned on the simulated development of allele frequencies. Allows to specify when selection starts and when it ends (or some condition, e.g. fixation).

MSMS model for selected locus

Works for fitness function of haploids or diploids.

Selection can depend on deme.

Fitness of genotypes aa, aA and AA on deme i: $(1 + s_i^{aa})$, $(1 + s_i^{aA})$, and $(1 + s_i^{AA})$ Also balancing selection possible by choosing $s_i^{aa} < s_i^{aA} > s_i^{AA}$

 m_{ij} : fraction of island j immigrants on island i

$$m_{ii} := 1 - \sum_{i \neq i} m_{ij}.$$

 x_i : relative frequency of A on island i

- $\mu\,$: mutation rate $a \to A$
- ν : mutation rate $A \rightarrow a$

$$\eta_i^A := \sum_j m_{ij} x_j \left(1 + (1 - x_j) s^{aA} + x_j s^{AA} \right)$$

$$\eta_i^a := \sum_j m_{ij} (1 - x_j) \left(1 + x_j s^{aA} + (1 - x_j) s^{aa} \right)$$

$$x_i' := \frac{(1 - \nu) \eta_i^A + \mu \eta_i^a}{\eta_i^A + \eta_i^a}$$

Then, the number of copies of A on island i in the next generation is drawn from binomial distribution with parameters $(2N_i, x'_i)$. For ARG backwards simulations, continuous time is assumed. For this, each

generation from the forward simulation is replaced by suitable time span.

MSMS simulation strategy for ARG

Simulate migration, coalescence, mutation and recombination. As far as possible use that the time to

the first event (back in time) of several possible events with exponential waiting time is also exponentially distributed with rate being the sum of the single rates. But take into account that rates vary in time

due to population size changes and changes of allele frequencies at locus under selection. Lineages can

coalesce only if they have the same type A or a at the selected locus.

E.g. if there are k lineages of type A on island i, the total coalescence rate of these lineages is

$$\frac{k \cdot (k-1)}{2N_i x_i}$$

as long as type A has frequency x_i on island *i*.

Migration and Mutation rate must be corrected for allele frequencies simulated afore. If m_{ij} is the

fraction of island *i* inhabitants that immigrated from island *j*, then the fraction of immigrants from *j* of type *A* is $x_j m_{ij}$. Thus, the fraction of immigrants among the type *A* inhabitants of island *i* is $x_j m_{ij}/x_i$.

Similarly, lineages of type A are traced back to be mutated from lineages of type a on island i at rate $\mu \cdot (1-x_i)/x_i$.

Simulating the ARG, given the locus under selection

During the backwards simulation, all lineages have sequences with "active" and "inactive" sections. Active means that a mutation in such a region would lead to a polymorphic site in the sampled sequences. In the beginning, all sites are active. If recombination happes, the lineage is split into two, and in one everything left of the recombination site is deactivated, and in the other one everything right of the recombination point is deactivated. If two lineages coalesce, the active regions in the resulting lineage is the union of all active regions in the two coalescing lineages, with one exception: If a region is active in only one lineage, it is deactivated. When a recombination happens in an inactive range, its exact location is irrelevant (like mutations in these regions), again with one exception: If the locus under selection is in the inactive region, it matters whether recombination happened left or right of it.

We must alway keep track of the type a or A of each lineage at the selected locus, even if this locus is outside the range for which we simulate the ARG. In particular, when recombination leads to a split

of a lineage, one lineage keeps the locus under selection (which one is clear from the position of the recombination point). The type of the other lineage is of type A or a with probabilities x_i or $1 - x_i$, respectively.

New versions of msms (or future versions?) can also simulate the case of more than one locus under selection.